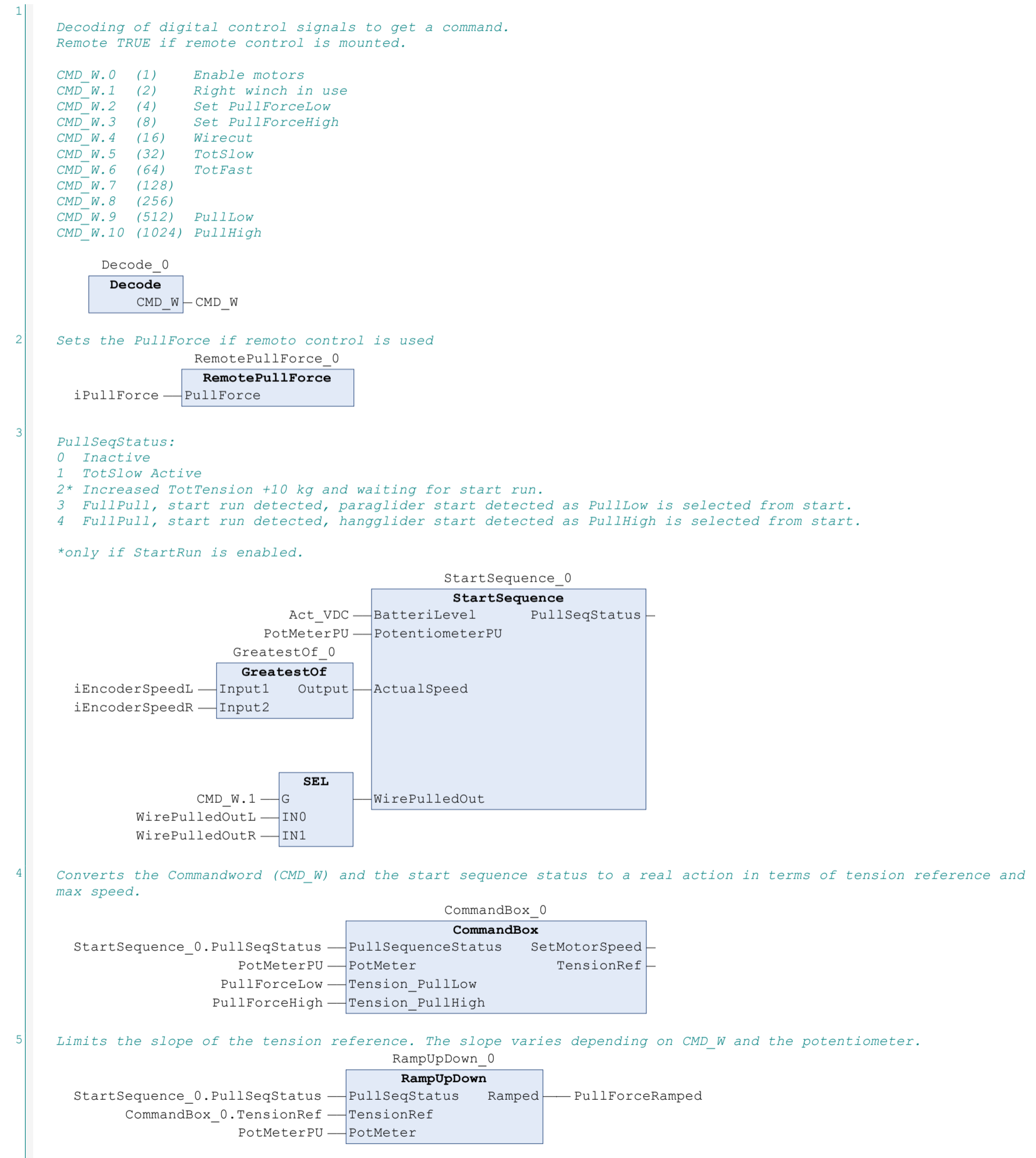


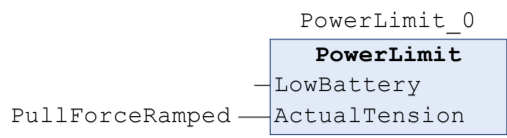
```

1  PROGRAM Drum
2  VAR
3      Decode_0 : Decode ;
4      RemotePullForce_0 : RemotePullForce ;
5      GreatestOf_0 : GreatestOf ;
6      StartSequence_0 : StartSequence ;
7      CommandBox_0 : CommandBox ;
8      RampUpDown_0 : RampUpDown ;
9      PowerLimit_0 : PowerLimit ;
10     SpeedReduce_0 : SpeedReduceBox ;
11     VFDCCommand_0 : VFDCCommand ;
12     VFDCCommand_1 : VFDCCommand ;
13 END_VAR
14

```

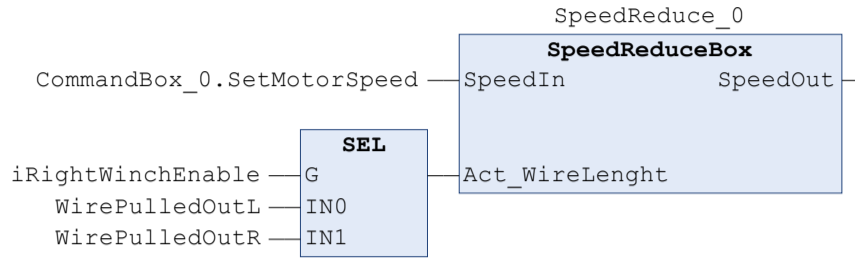


6



7

Reduces the motor speed when the wire approaches the winch to avoid damage of wire and winch.



8

Scaling of the final values to torque and and speed for the variable frequency drive. Select block is used when more than one drum.

