



# Infrastructure Supported Automated Driving in Transition Areas – a Prototypic Implementation



Julian Schindler



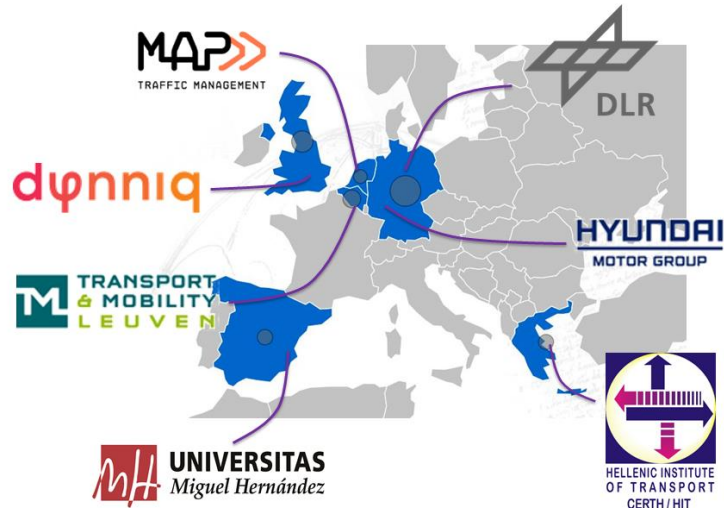
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# Transition Areas for Infrastructure Assisted Driving

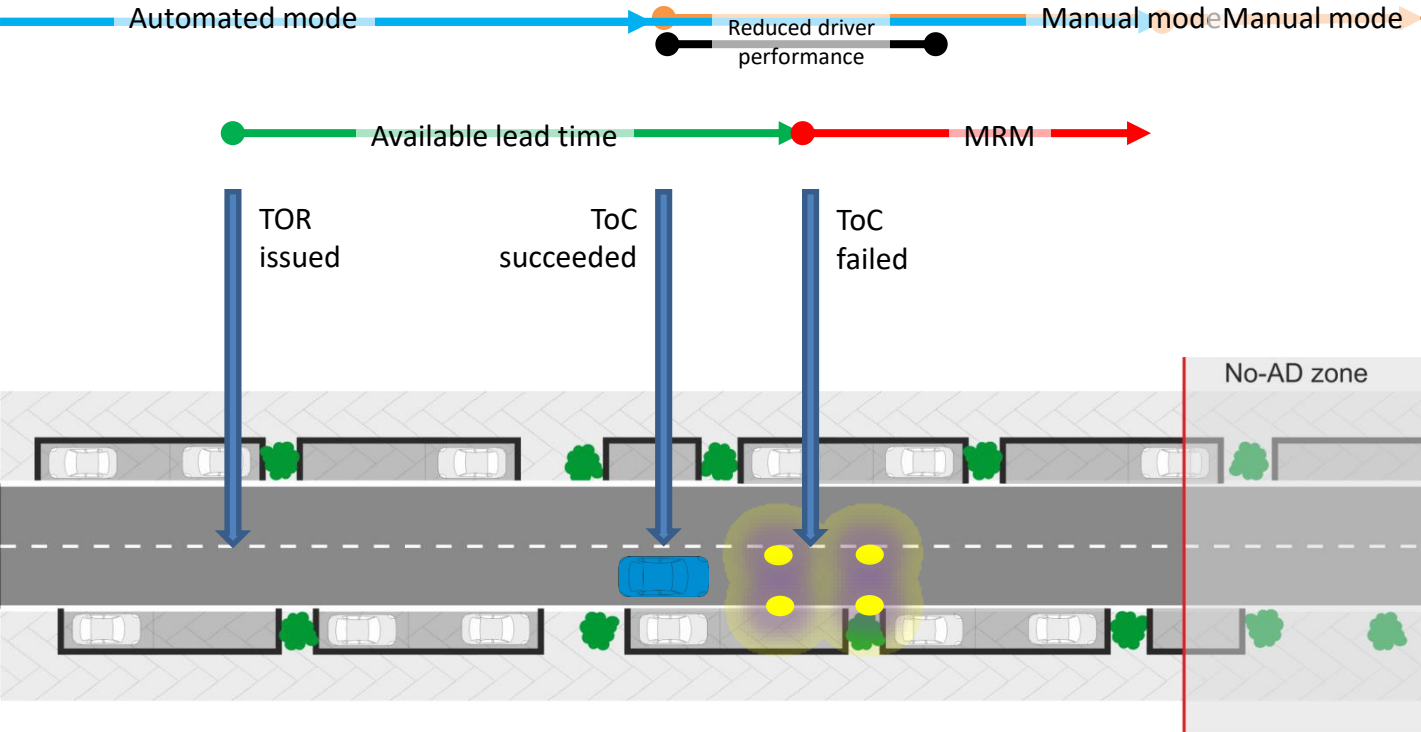


## European H2020 project

- ART-05-2016 - Automated Road Transport
- Period: 01-09-2017 ~ 31-08-2020  
COVID-19 Extension to 31-12-2020
- Budget: € 3,836,353
- 7 partners + 12 associated partners



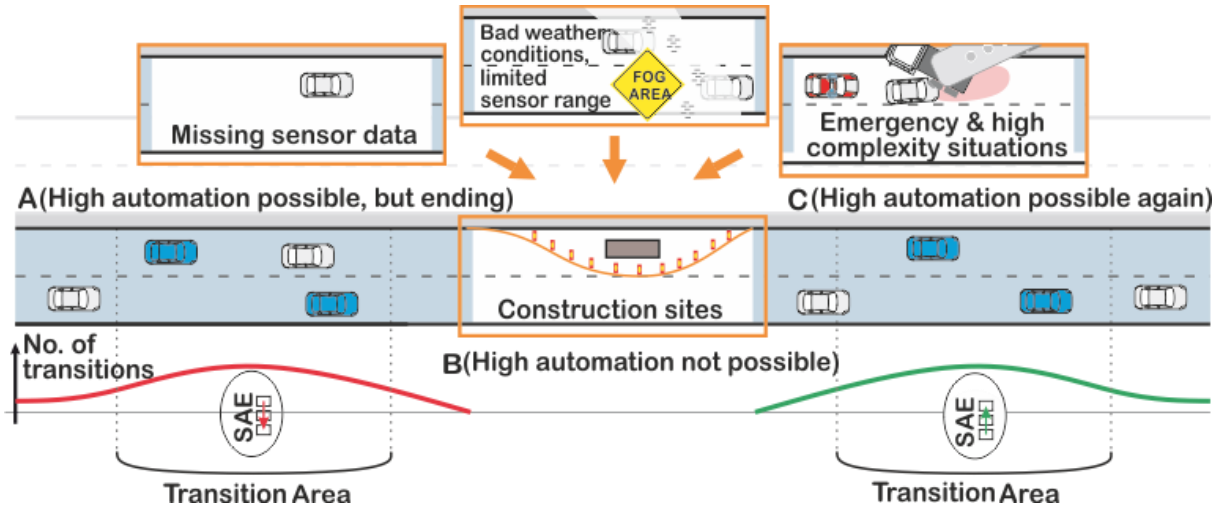
# Definition: ToC, TOR & MRM



- ToC: Transition of Control
- TOR: Take Over Request
- MRM: Minimum Risk Maneuver



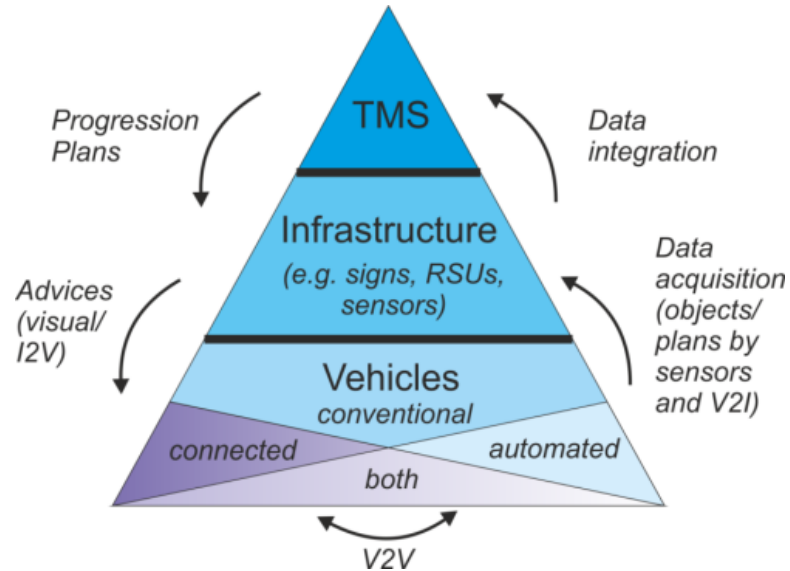
# Definition: "Transition Areas"



*"Transition Areas" are areas on the road where many highly automated vehicles (blue) are changing their level of automation due to various reasons.*



# Hierarchical approach

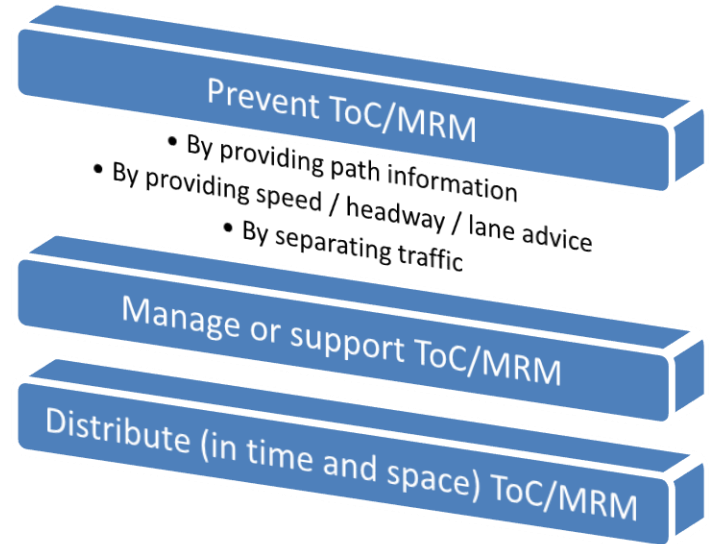
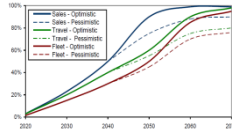
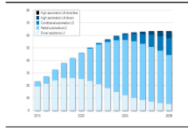
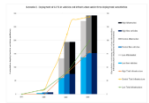


# Service definition

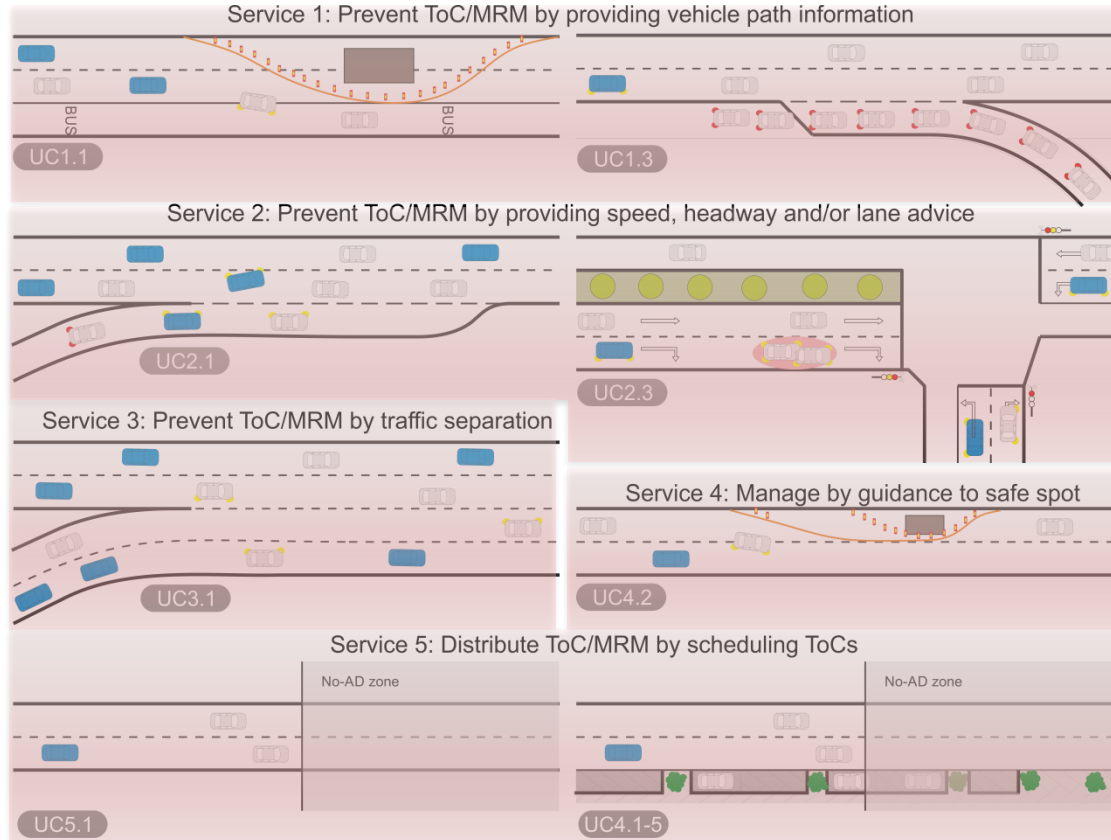


Performed literature studies, expert interviews and stakeholder workshops with surveys

- Various parameters (environmental causes, vehicle behaviour, HMI, driver reaction, time ...)
- only limited data available



# Services and Use Cases



Each use case tested in several scenarios

→ Sum of approx. 50 scenarios





# ITS-G5 communication as enabling technology

CAM

DENM

SPATEM

MAPEM

CPM

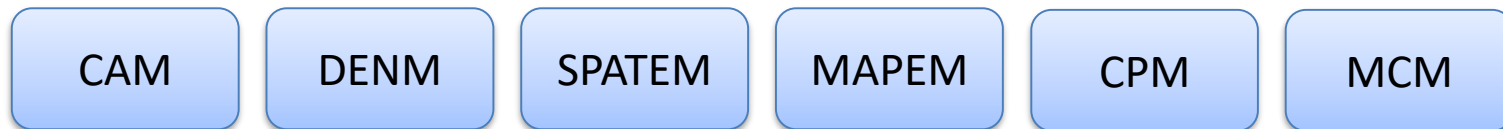
MCM

## Cooperative Awareness Message

- Type
- Position
- Orientation
- Velocity
- + Current automation level
- + Currently performing ToC/MRM



# ITS-G5 communication as enabling technology

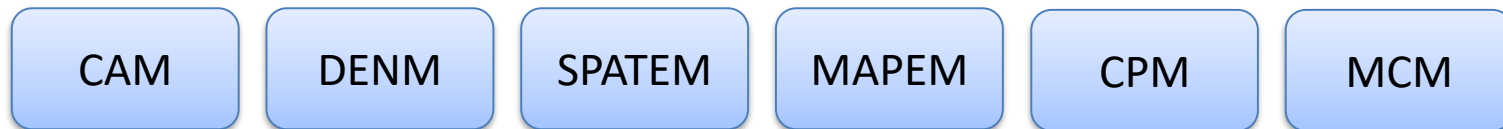


## Decentralized Environmental Notification Message

- Warnings and hazards
- Road works
- Broken down vehicles



# ITS-G5 communication as enabling technology

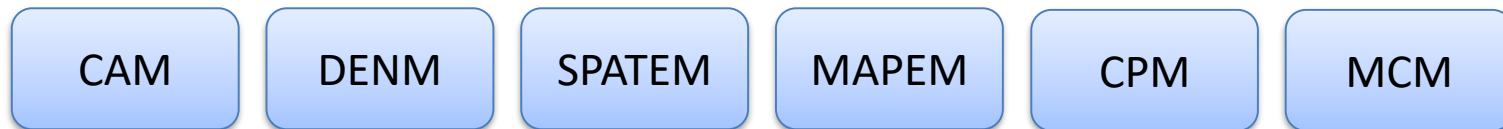


Signal Phase and Timing Extended Message

- Traffic light phases



# ITS-G5 communication as enabling technology

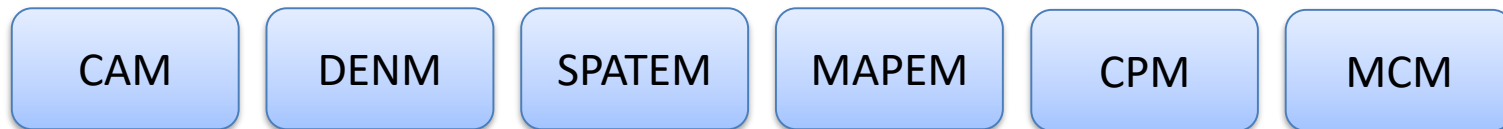


## Map Extended Message

- For intersections
  - Topology
  - Lane types
  - Lane links
- + Used also on standard roads
- + E.g. Safe Spot definitions



# ITS-G5 communication as enabling technology



## Collective Perception Message

Standardization  
activities by  
TransAID

- Information about sensor
- Detected objects
  - Type
  - Position
  - Orientation
  - Velocity



# ITS-G5 communication as enabling technology

CAM

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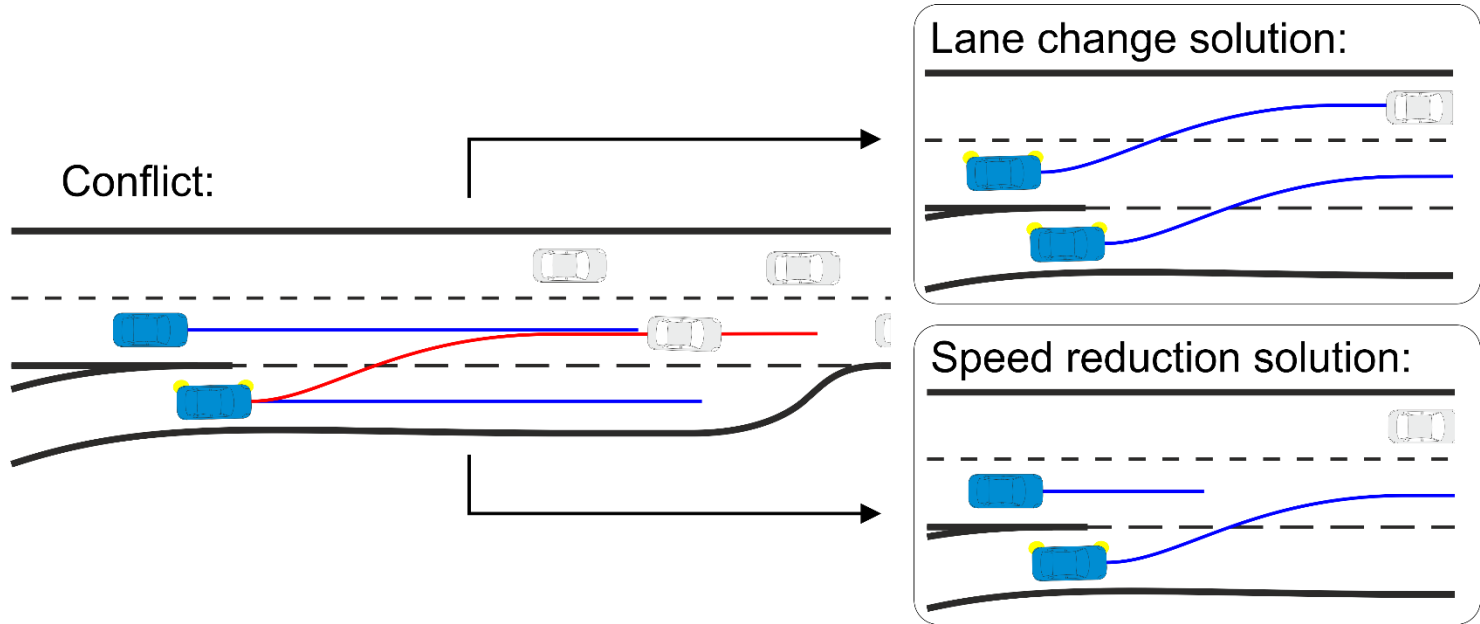
Standardization  
activities by  
TransAID

## Maneuver Coordination Message

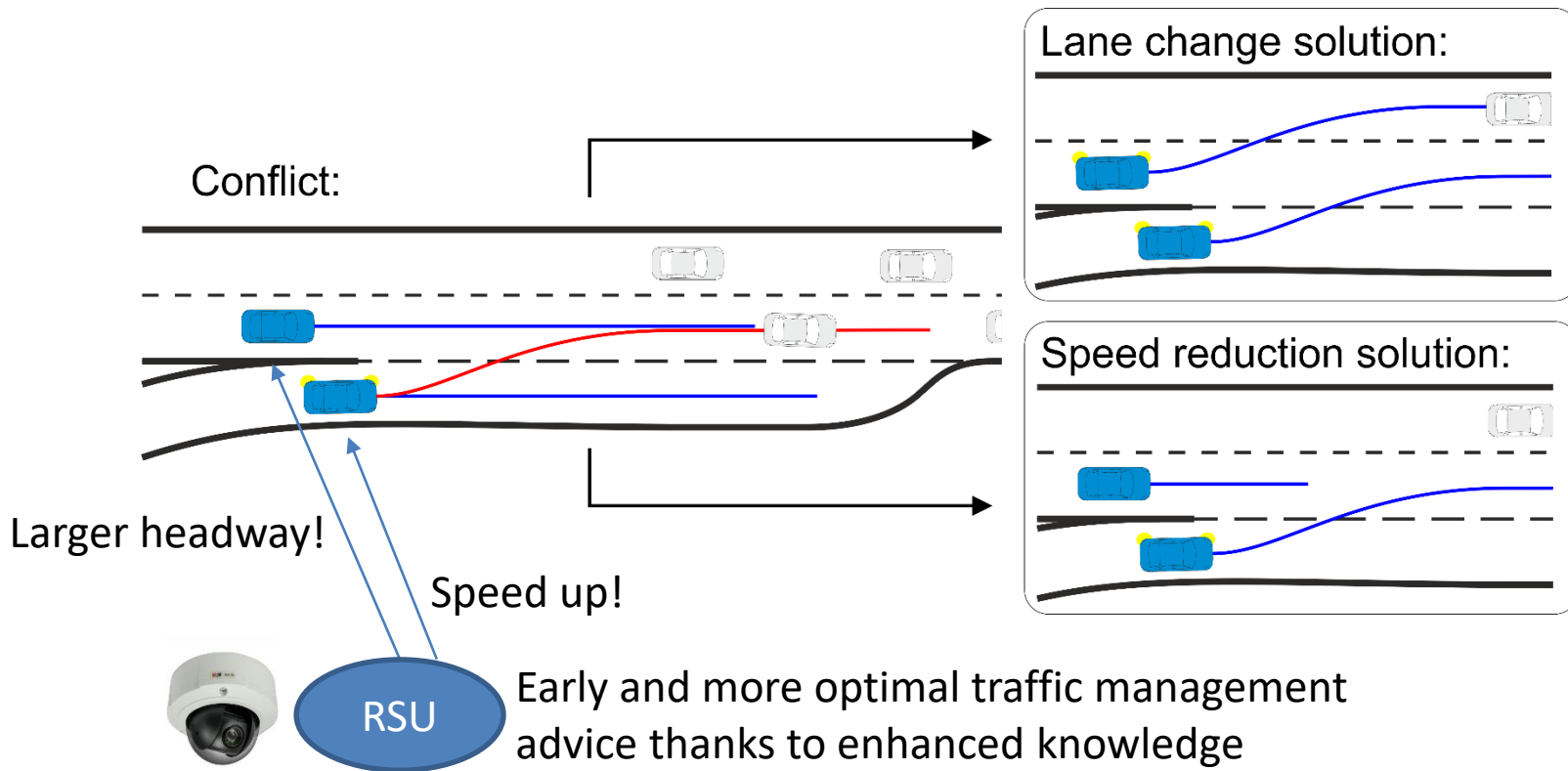
- V2V-Part
  - Current trajectories
  - Desired trajectories
- + I2V-Part
  - + ToC advice
  - + Lane advice
  - + Speed/Headway advice
  - + Safe Spot advice



# MCM V2V Communication



# MCM Communication with infrastructure support

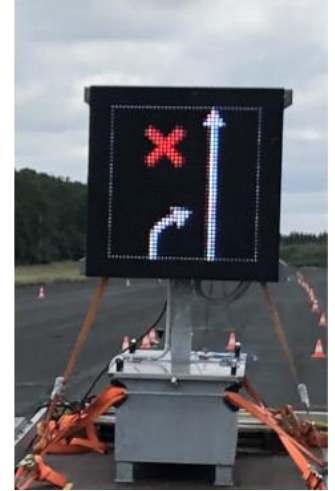


Early and more optimal traffic management advice thanks to enhanced knowledge

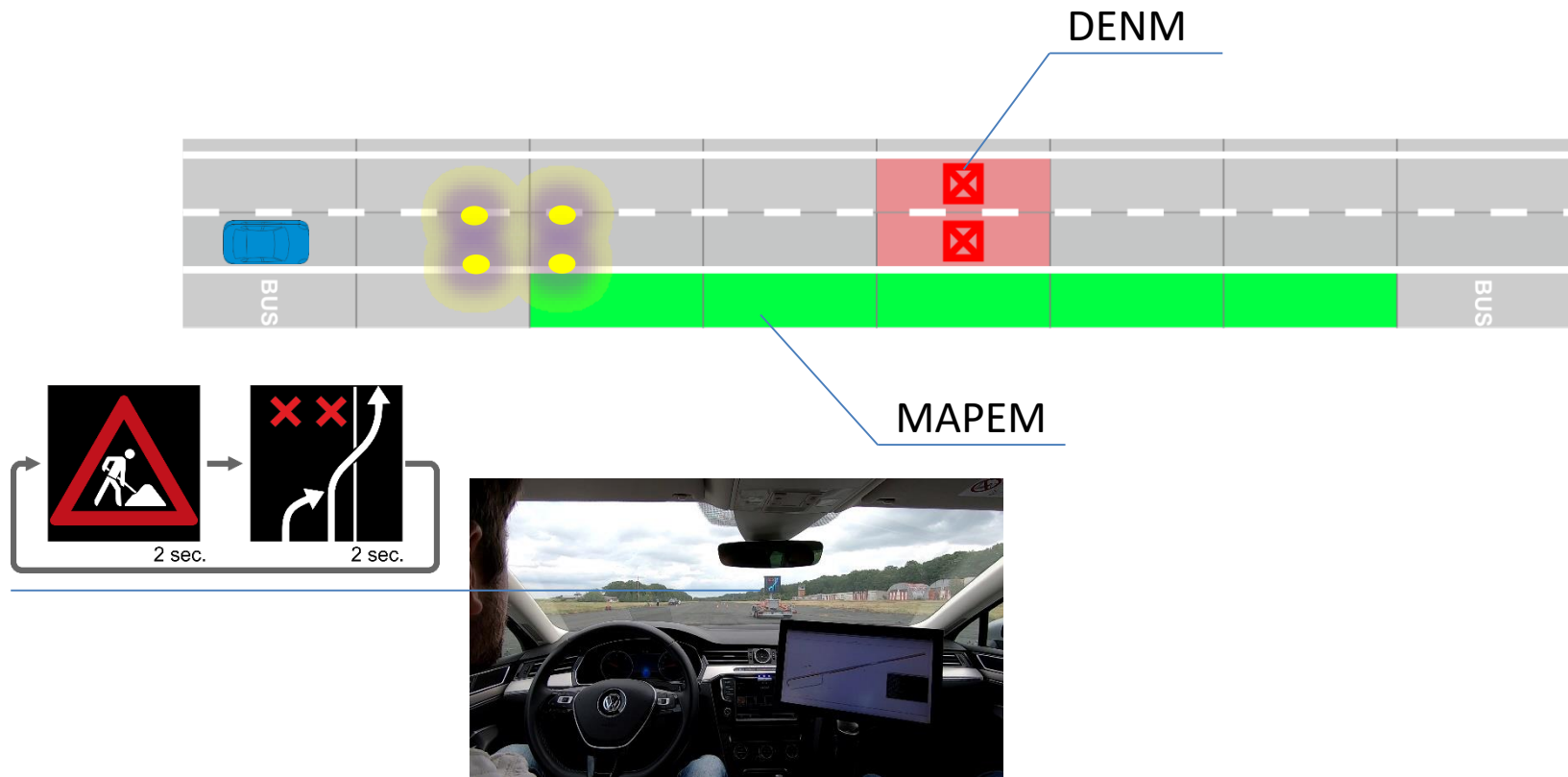




# Feasibility assessment in real world



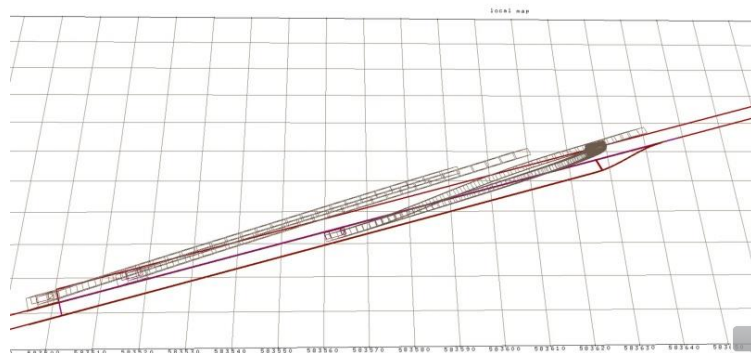
# Service 1 example: Provide path information



# Service 2 example: Cooperative Lane Change and Merging

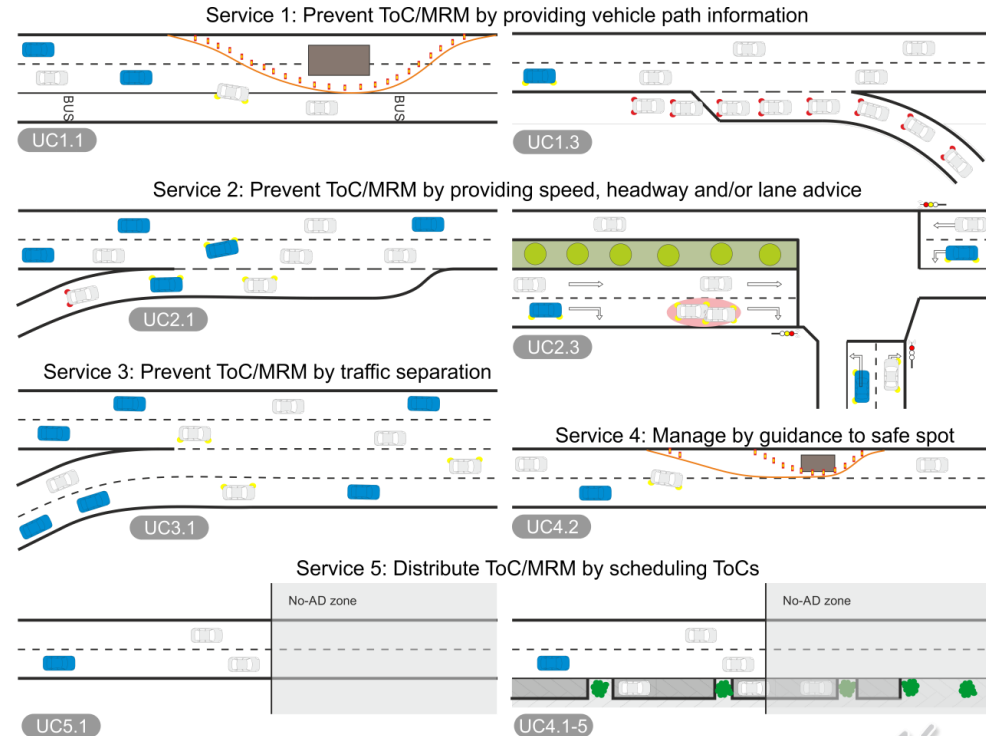


- Infrastructure gives early speed advice to on-ramp vehicle
- and early ToC advice in case of impossible merging
- V2V cooperation when CAVs meet:
  - If possible, highway vehicle changes lane
  - If not, gap opening



# Feasibility results

- Tested 5 services in approx. 50 scenarios
- All traffic management measures could be applied with ITS-G5 communication
- Developed messages suitable for solving critical vehicle automation behaviour
- Infrastructure is able to provide information for more smooth and comfortable driving



# TransAID



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