

Enhanced Traffic Management Procedures of Connected and Autonomous Vehicles in Transition Areas

Sven Maerivoet

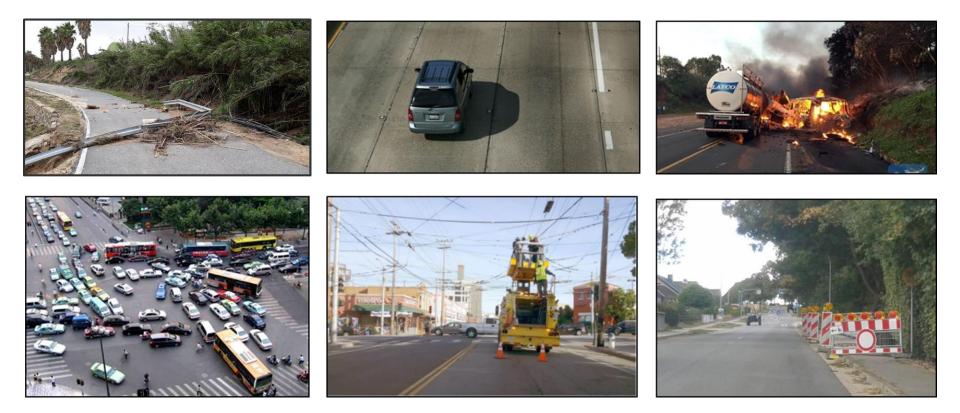


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Situations in which (C)AVs may struggle





Main observations about state-of-the-art for traffic management

- General approaches
 - Coordinated network-wide traffic management
 - Using KPIs, hierarchical controls via layered architectures, TMaaS
- Cooperative systems
 - V2X / VANETs / C-ITS
- Machine learning techniques (AI)
 - Traffic light control and congestion / queue length predictions

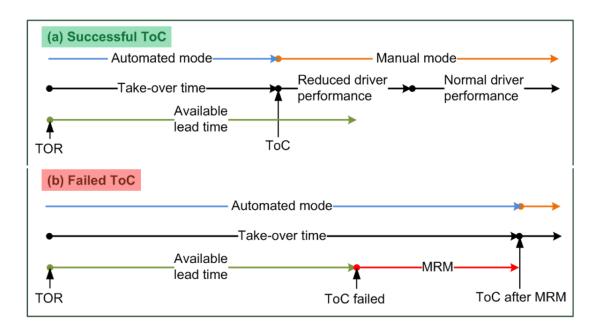
Conclusion

- <u>No (readily available) implementations of more advanced</u> TM schemes
- Focus on solving partial problems with specific measures



Sequence of events when AD disengages

- Take-over request (**TOR**) issued by the car
- Transition of Control (ToC) from car to driver
- Minimum-Risk Maneuver (MRM) by the car
- Driving at the boundary of the **ODD**

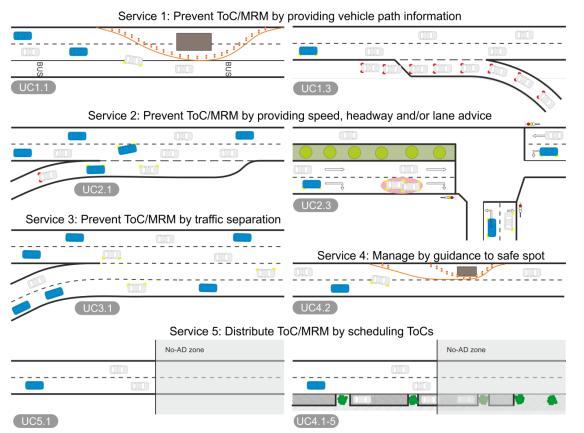




Developing TransAID's services for traffic management in transition areas

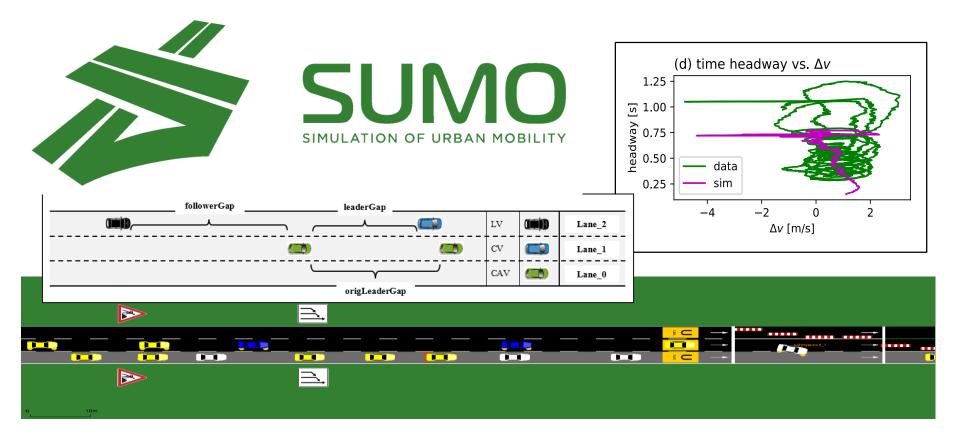
- Solutions take the form of these actions:
 - Prevent ToC/MRM
 - Manage or support ToC/MRM
 - Distribute (in time and space) ToC/MRM
- Assess solutions based on impacts measured by **KPIs**:
 - Traffic efficiency
 - Network-wide: average speeds and throughput
 - Local: tempo-spatial diagrams
 - Traffic safety
 - Number of events with time-to-collision < 3 sec
 - Environmental impact
 - CO₂ emissions

Services and use cases





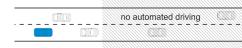
Simulating the impact of traffic management



TransAID



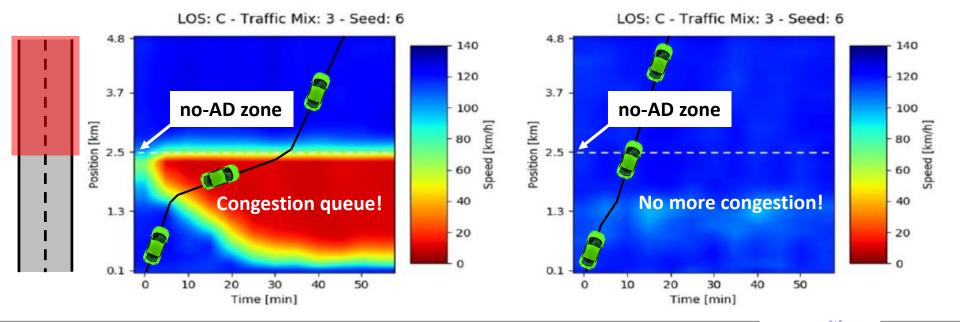
Example use case 5.1 (Distribute the TORs within a dedicated TOR area)



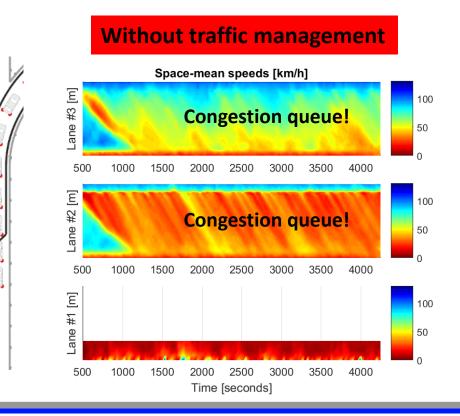
TransAID

Without traffic management

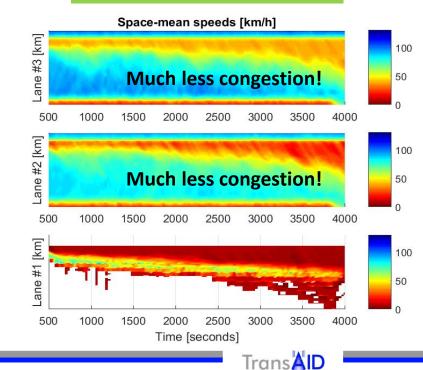
With traffic management



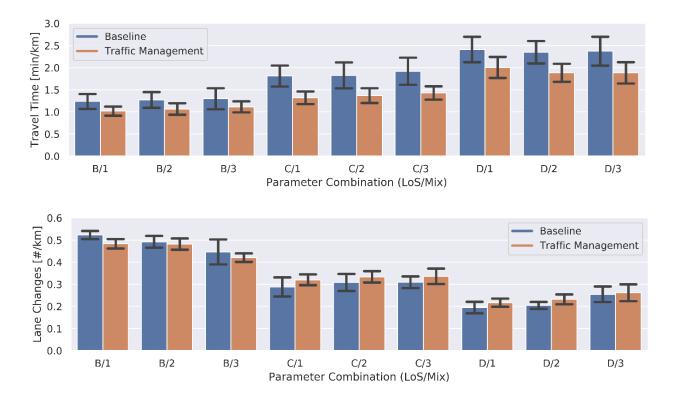
Example use case 1.3 (queue spillback at motorway exit ramp)



With traffic management



Measuring the impact (e.g., travel times, number of lane changes, ...)







Questions? Let's stay in touch!

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