



Is Packet Dropping a Suitable Congestion Control Mechanism for Vehicular Networks?

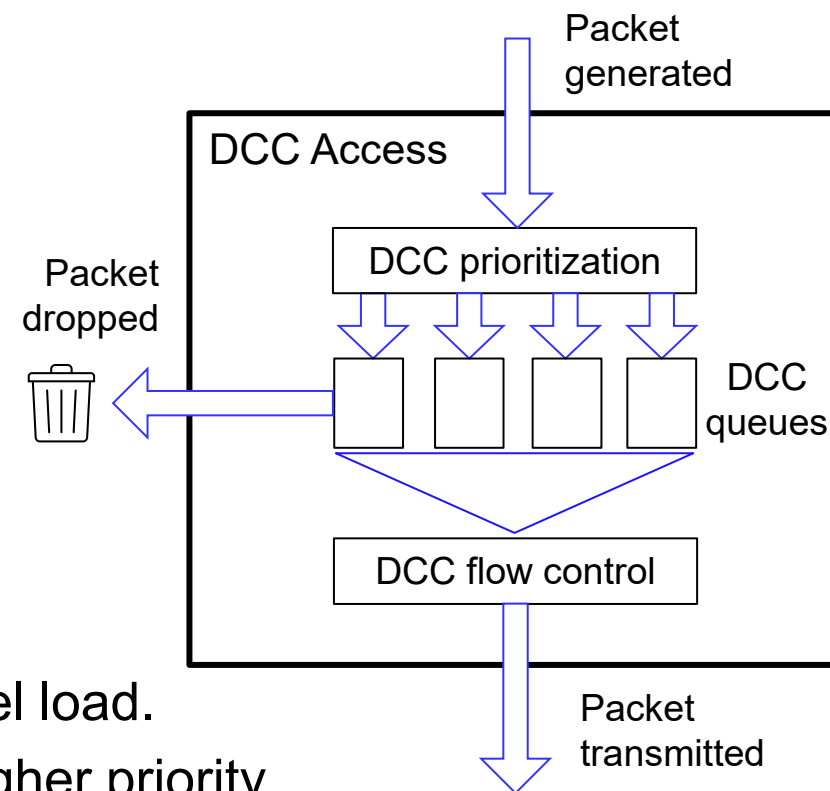
Miguel Sepulcre, Jorge Mira, Gokulnath Thandavarayan, Javier Gozalvez

msepulcre@umh.es, jorge.mira01@goumh.umh.es gthandavarayan@umh.es, j.gozalvez@umh.es

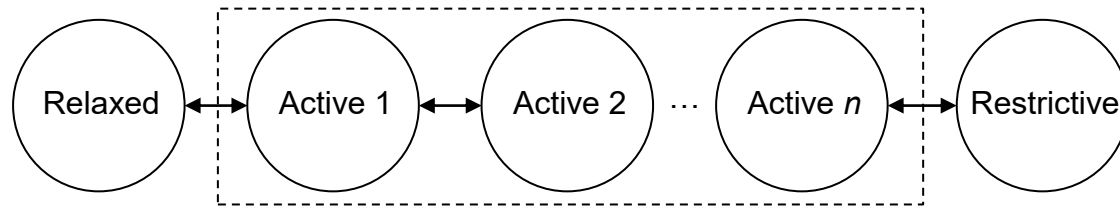


- Vehicular networks based on V2X exchange of information.
 - Radio channel has limited bandwidth and channel load needs to be controlled.
- ETSI Decentralized Congestion Control (DCC).
 - DCC Access: packet tx rate control based on packet dropping.
 - Reduction of interference: improvement of performance at radio level.
 - Packets dropped are not transmitted and hence lost from the application perspective.
- Objective: study impact of DCC Access V2X performance.
 - Analysis at radio and application levels.
 - Different DCC Access approaches, varying packet priorities and mixed traffic scenarios.

- Prioritization:
 - Packets classified in 4 different DCC Profiles (DP).
- Queuing:
 - Packets must wait until a new tx is allowed.
 - If a queue is full, packets are dropped.
- Flow control:
 - Adapts time between tx packets (T_{off}) based on channel load.
 - Low priority packets tx when there is no packet with higher priority.
 - Two approaches defined: Reactive and Adaptive.



- Reactive approach:
 - Based on a state machine, where the current state depends on the channel load.
 - Each state has a maximum packet rate (minimum interval T_{off}).



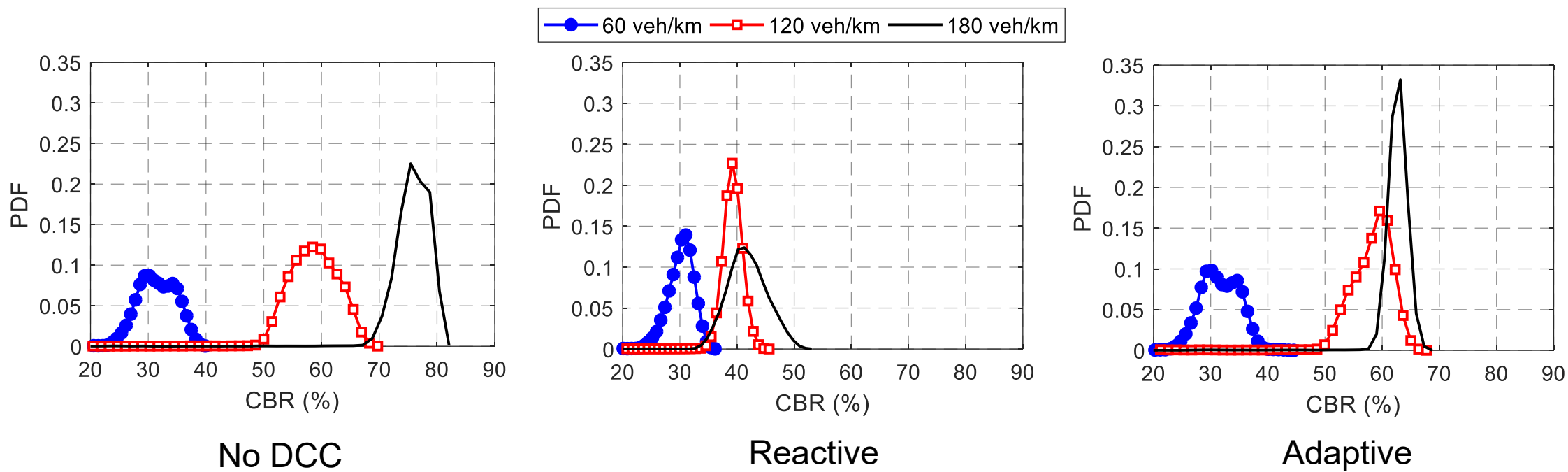
State	CBR	Packet rate	T_{off}
Relaxed	< 30%	20 Hz	50 ms
Active 1	30% to 39%	10 Hz	100 ms
Active 2	40% to 49%	5 Hz	200 ms
Active 3	50% to 65%	4 Hz	250 ms
Restrictive	> 65%	1 Hz	1000 ms

- Adaptive approach:
 - Linear control process to adapt the packet transmission rate (or interval T_{off}).
 - Designed to converge to a target channel load value of $CBR_{target} = 68\%$.

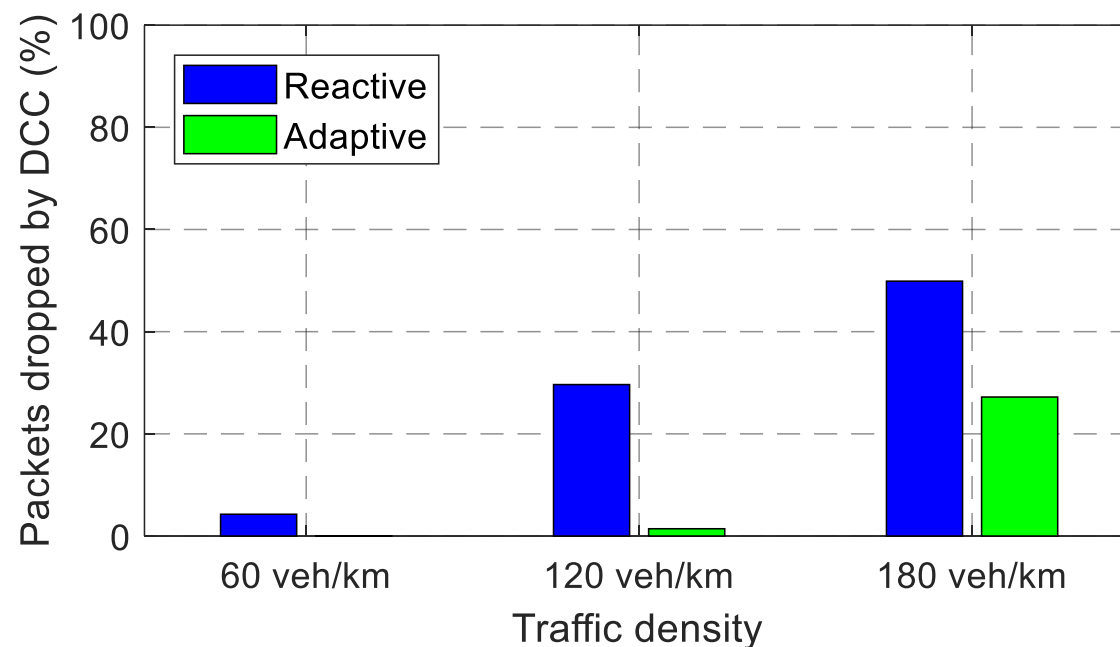
- Simulation tool: **ns-3**
 - DCC Access module available: <https://github.com/msepulcre/DCC-ns3>
- Traffic parameters: 6 lane highway scenario.
 - Traffic densities: 60, 120 and 180 vehicles/km.
 - Vehicle speed: 100 km/h (for all densities).
- Message generation rate:
 - CAM rate: 3 Hz; CAM size: 350 bytes; DCC profile: DP2.
 - CPM rate: 8.5 Hz; CPM size: 261 bytes; DCC profile: DP2 or DP3.
- DCC Access:
 - Reactive and Adaptive approaches implemented and evaluated.
 - Queue length: 10 packets; Packet Time to Live: 1 second.



- Channel load or Channel Busy Ratio (CBR).
 - Without DCC, CBR increases with density up to more than 80%.
 - Reactive approach drastically reduces the CBR below 50%.
 - Adaptive approach limits the maximum CBR to 68%.

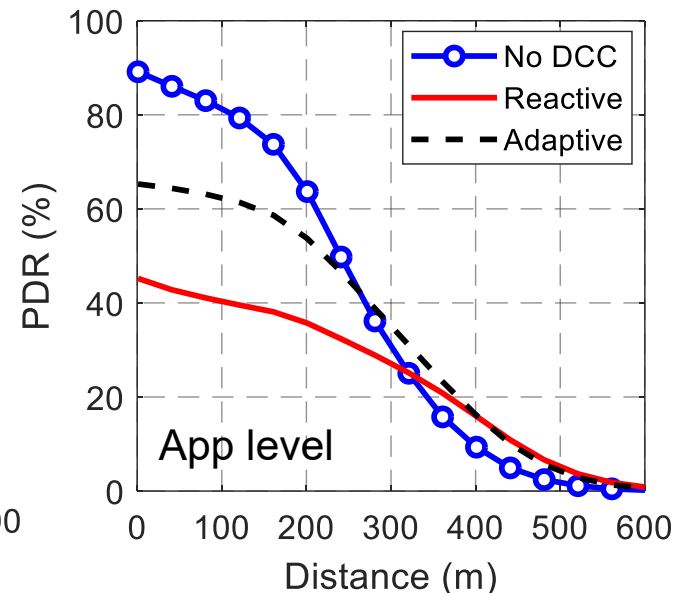
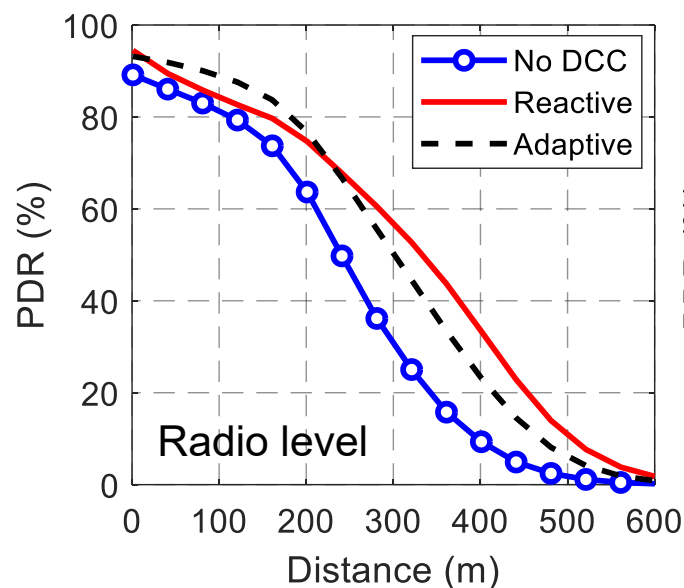


- Packets dropped by DCC at Access layer.
 - DCC drops packets to control the channel load.
 - Reactive approach increase the packet drop significantly.
 - Packets dropped are not transmitted, hence lost.



- Packet Delivery Ratio (PDR).
 - DCC improves PDR at radio level due to lower interference.
 - DCC degrades PDR at application level.
 - Highest density: significant portion of packets generated are not transmitted.
 - Medium and low density: Adaptive and No DCC have similar performance.

PDR at radio level:
ratio between
packets received
and transmitted



PDR at app level:
ratio between
packets received
and generated

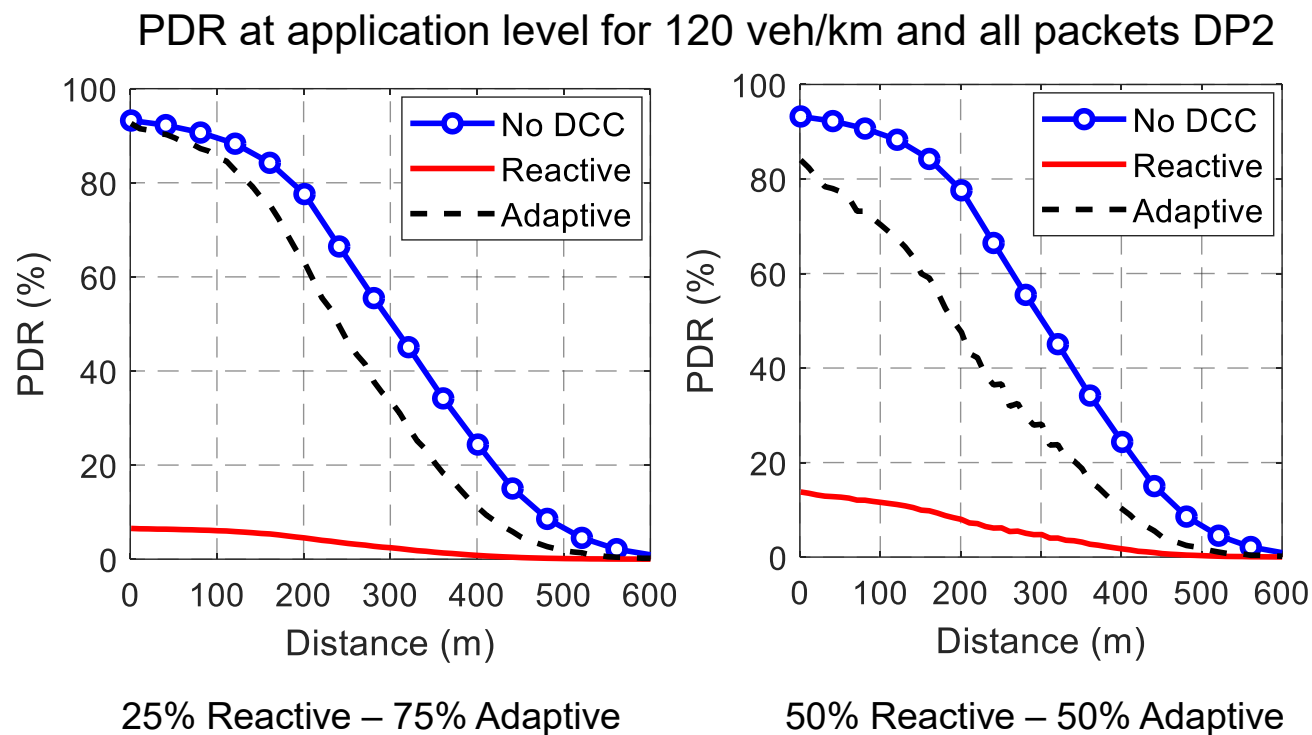
Traffic density: 180 veh/km; all packets DP2

- Packet prioritization: CAM as high priority (DP2) and CPM as low priority (DP3).
 - Almost no CAMs are dropped because their higher priority.
 - Up to 70% (Reactive) and 37% (Adaptive) of CPMs are dropped.

Traffic density	Reactive		Adaptive	
	CAM	CPM	CAM	CPM
60 veh/km	0.09 %	5.9 %	0.08 %	0.8 %
120 veh/km	0.05 %	40.3 %	0.03 %	2.2 %
180 veh/km	0.10 %	70.4 %	0.07 %	37.2 %

Packets dropped by DCC when CAMs are configured as DP2 and CPMs as DP3

- Mixed of vehicles using Reactive and Adaptive.
 - Best performance achieved when DCC is not used.
 - Vehicles using Reactive experience a significantly low performance.
 - Increasing vehicles using Reactive decreases the performance of Adaptive.



- Congestion control based on packet dropping degrades application level performance.
 - A significant portion of packets are generated, but not transmitted.
 - Not using congestion control can provide better performance than packet dropping.
- DCC needs adequate configuration.
 - Lower priority services/applications can be highly degraded.
 - In mixed scenarios, vehicles using Reactive degrade the performance.
- Future alternatives are needed to reduce and control the load.
 - More intelligent message generation.
 - Power or data rate control.
 - V2X message compression.

Thank you for your attention



Miguel Sepulcre, Jorge Mira, Gokulnath Thandavarayan, Javier Gozálvez
msepulcre@umh.es, jorge.mira01@goumh.umh.es gthandavarayan@umh.es, j.gozalvez@umh.es



The authors acknowledge the support of the Spanish Ministry of Economy and Competitiveness and FEDER funds under the project TEC2017-88612-R, and the support of the Horizon2020 Programme through the TransAID project (Grant Agreement no. 723390).