



Towards Continuous External Assistance of Automated Mobility

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MAP traffic management (MAPtm)



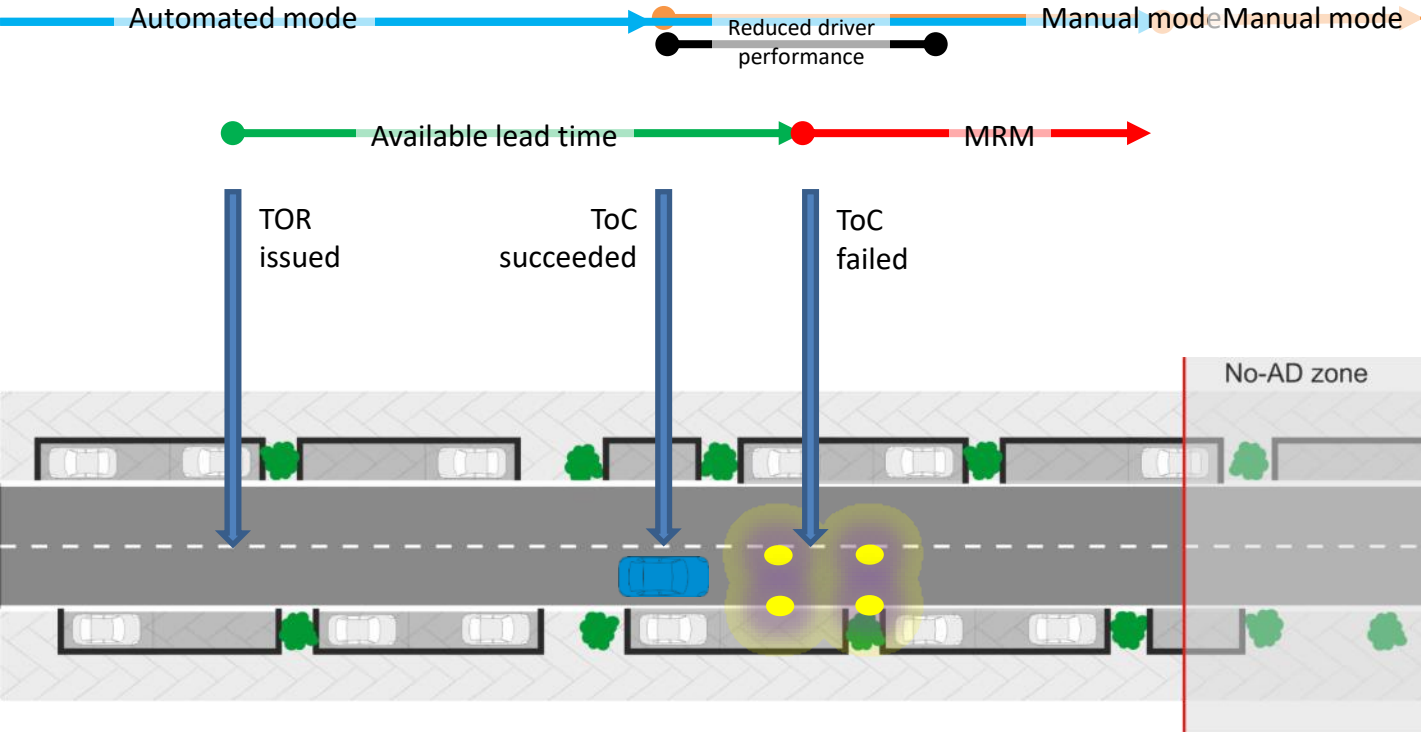
TRAFFIC MANAGEMENT

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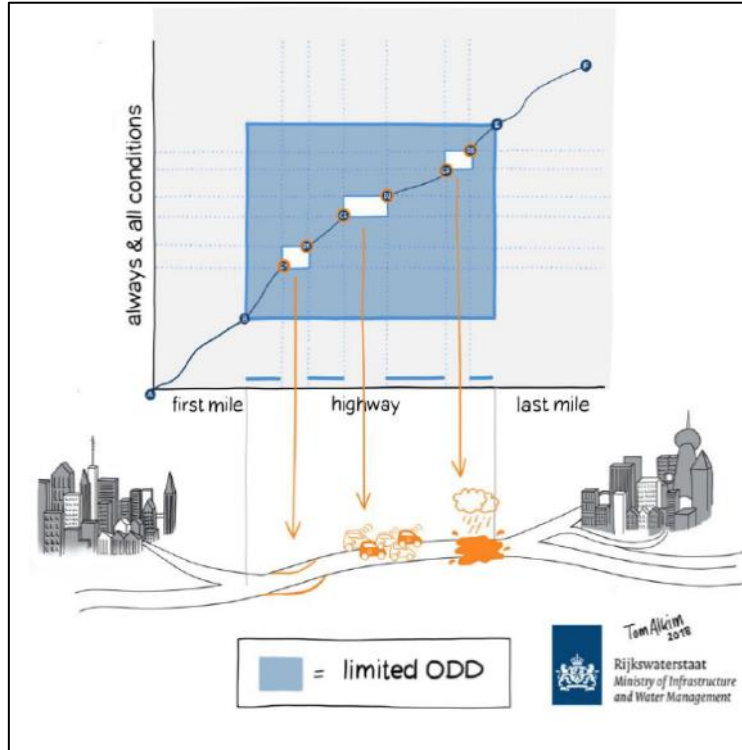


Definition: ToC, TOR & MRM



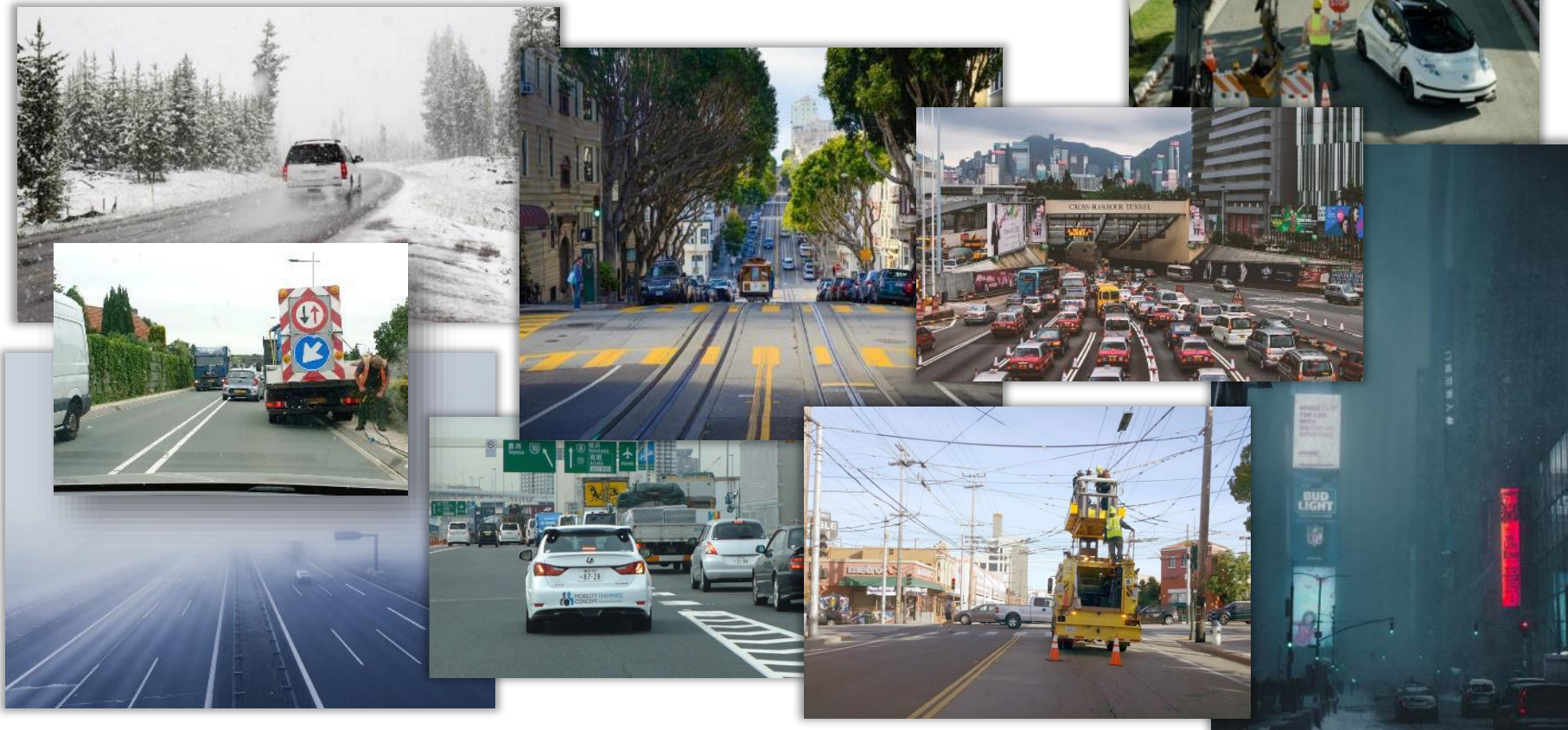
- ToC: Transition of Control
- TOR: Take Over Request
- MRM: Minimum Risk Maneuver

Managing the ODD



- An ODD has boundaries and gaps.
- What happens if an automated **vehicle is unable** to solve the situation ahead?
- ...what if, this happens not to a single, but to **several vehicles**?
- ...what if, it **systematically** happens on the same spot or in similar circumstances?
- ...what if, this **affects** traffic flow, traffic safety, etc.

Automated Driving Limitations



Question

What do you expect a CAV will do in case of a Minimum Risk Manoeuvre?

- Drive carefully
- Execute a diversion
- Stop in lane
- Park at safe harbour
- Other

VIEW OF OUR GEO-FENCED SELF-DRIVING FLEET IN SAN FRANCISCO



Remaining Routes: "AV Eligible"

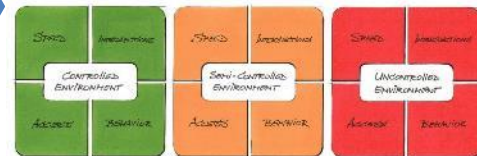


SAE J3016™ LEVELS OF DRIVING AUTOMATION

Vehicle AD functions & capabilities

Geo-Area / Operational Domain

Road environment (access, intersections, behaviour)



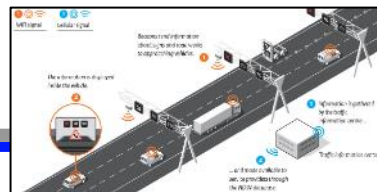
Vehicle / System operational performance

Situational / environmental conditions

Physical infrastructure measures



Digital infrastructure measures

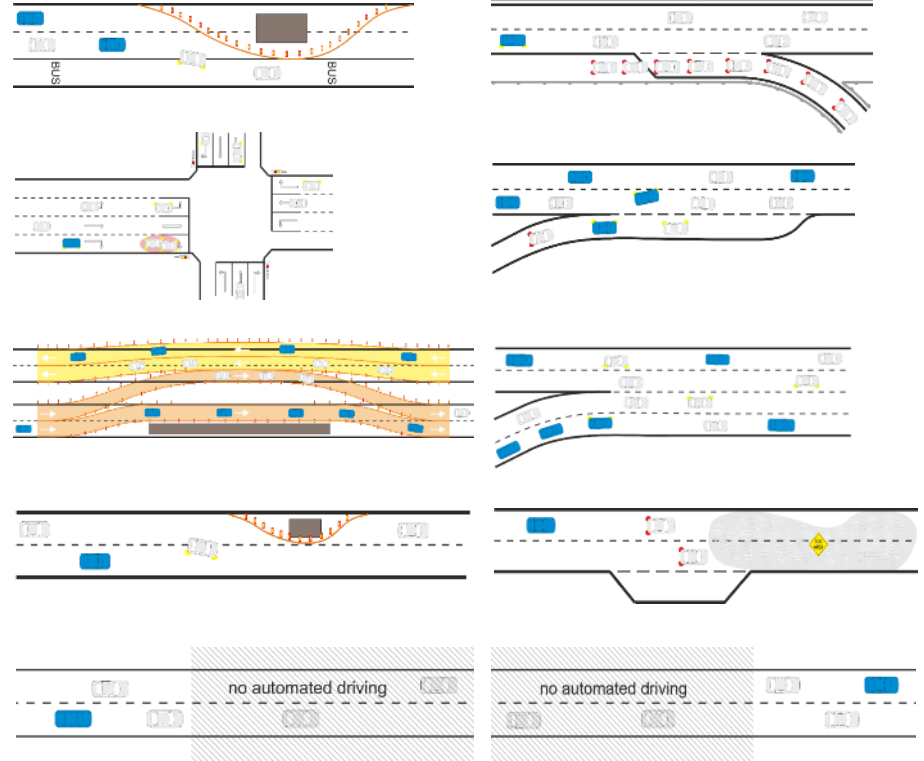


Assisting Automated Driving

- **Sense** and build environmental awareness
 - Situational support: provide relevant information (prevent)
 - E.g. digital map, objects/obstacles, (dynamic) regulations
- Ability to **plan** action(s)
 - Operational support: provide an (alternative) action (prevent)
 - E.g. path information, speed, headway, merge or lane advice
- Ability to perform **action**(s)
 - Tactical support: arrange favourable conditions (manage)
 - E.g. routing, orchestration, scheduling of ToC/MRM

TransAID services and use cases

1. Provide vehicle path information.
2. Provide speed, headway and/or lane advice.
3. Traffic separation.
4. Guidance to safe spot.
5. Orchestration, distribution and scheduling.

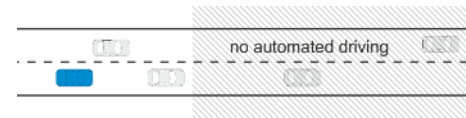


Question

Which TransAID service for infrastructure-assisted driving do you consider to be most realistic?

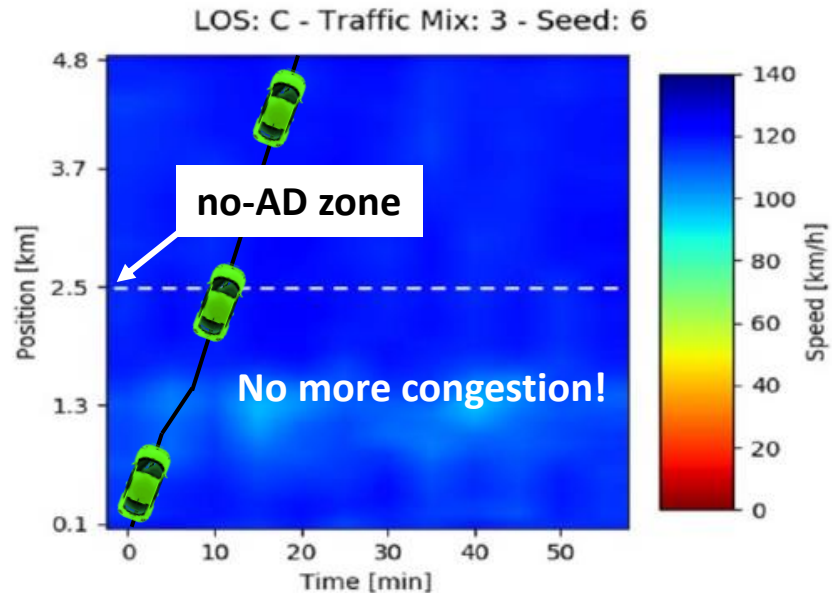
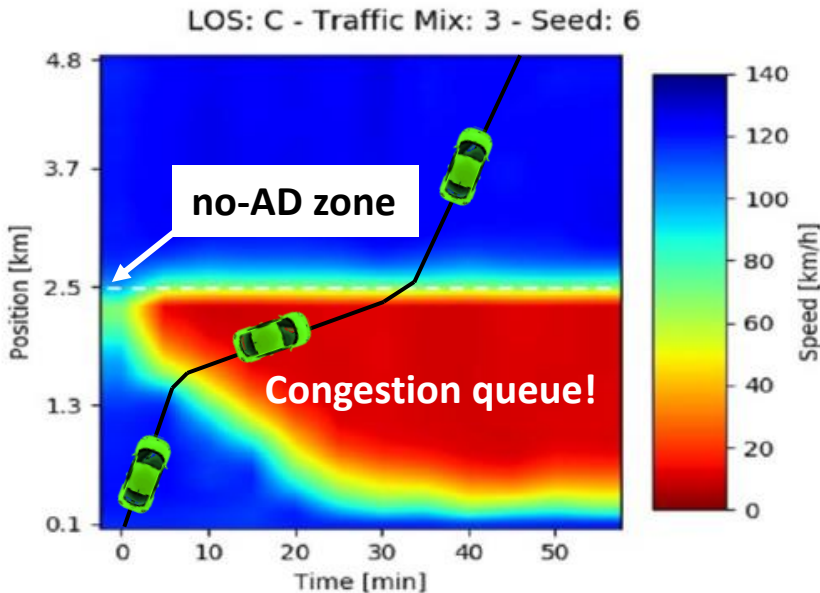
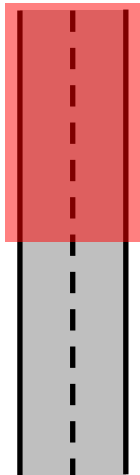
- Provide vehicle path information
- Provide speed, headway and/or lane advice
- Traffic separation
- Guidance to safe spot
- Orchestration, distribution and scheduling

Example use case 5.1 (Distribute the TORs within a dedicated TOR area)



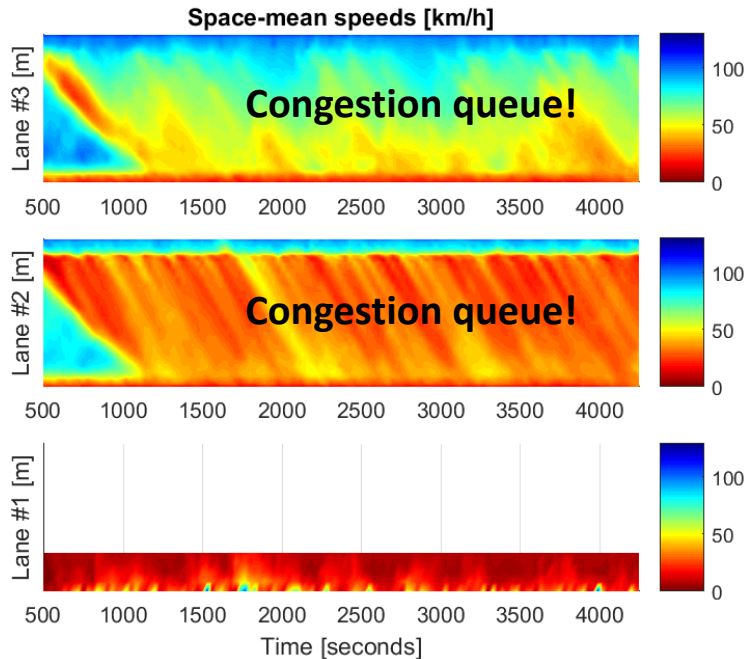
Without traffic management

With traffic management

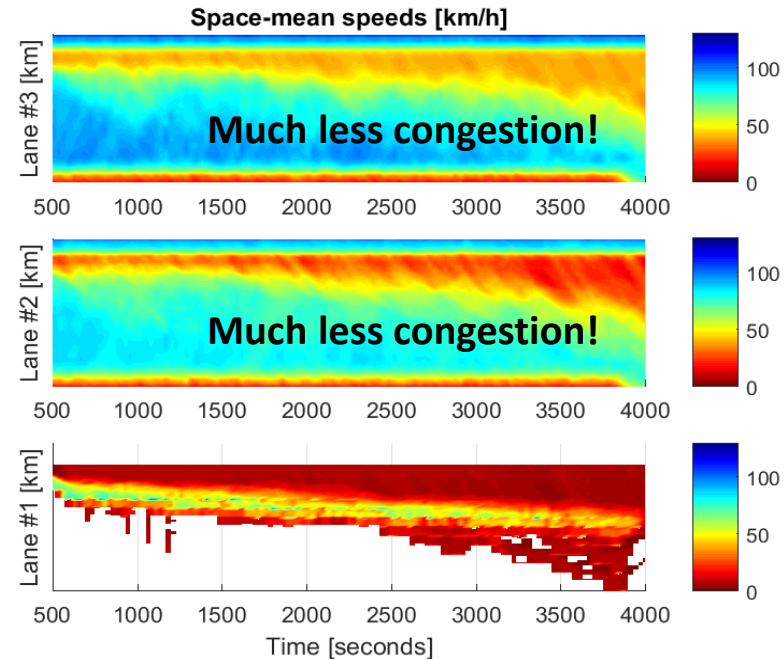


Example use case 1.3 (queue spillback at motorway exit ramp)

Without traffic management

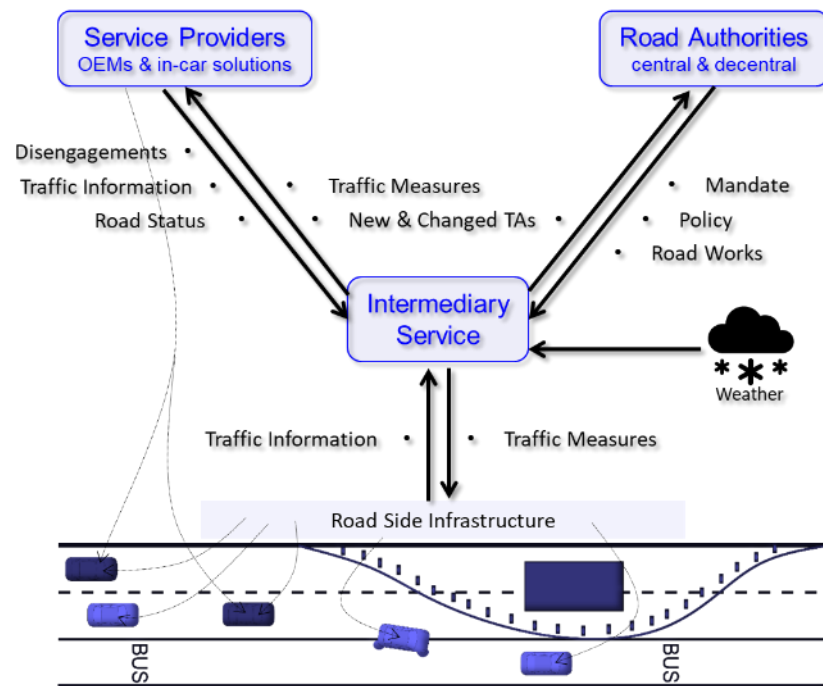


With traffic management



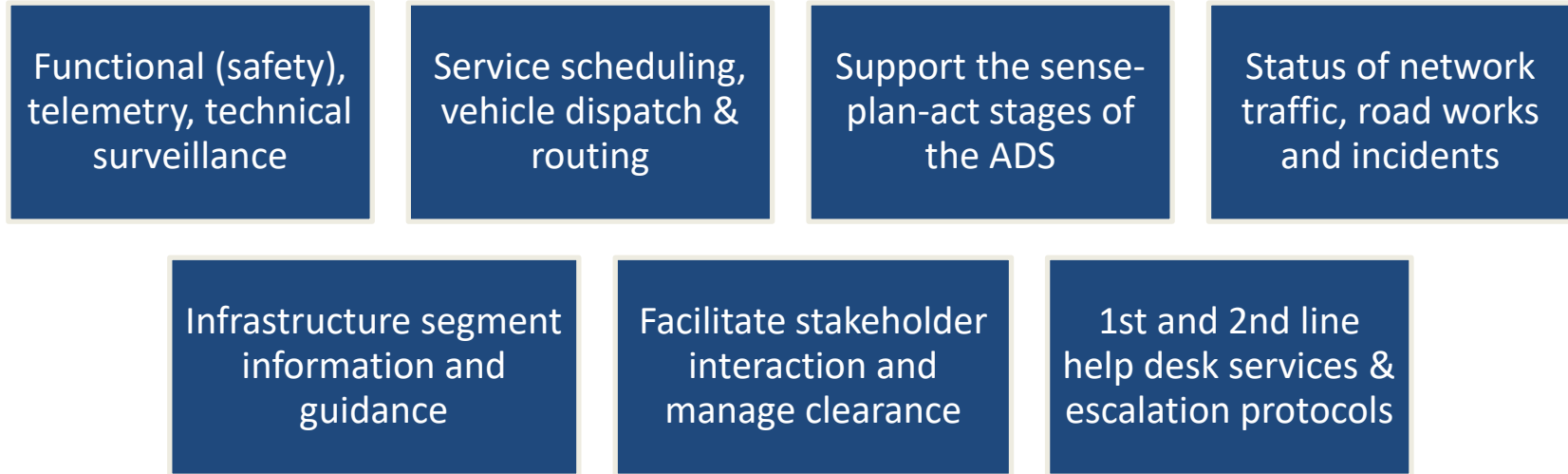
Intermediary service

- Connecting RAs and OEMs cooperate by linking *traffic management* and *fleet management*:
 - Generate trust
 - Create understanding
 - Align measures (space, time, type)
- Single point of access, possibly mandated by both RAs and OEMs.
- Apply across road authority borders (incl. those without a TMC).



Remote monitoring & control centres

- For the foreseeable future, safe and comfortable L4 autonomous mobility applications in mixed traffic (i.e. without steward or fall-back on board), will rely on a **remote supervisory services**:



- The presence of operators in a control room also contributes to the **public acceptance** of autonomous vehicles.

Vision

- Cross-domain service centre
- Integrating related operational processes
- Stakeholder intermediary
- (applied) University-level operators
- Multi-brand, multi-application, anywhere
- ISO certified
- Scalable



Question

What do you expect of remote control?

- Extended environmental awareness
- Mission management
- Autopilot assistance
- Remote driving
- Other

Question

Remote monitoring and control centres should be owned and operated by:

- Vehicle manufacturers
- Fleet owners
- Road authorities
- Qualified entity
- Other



Thank you for listening!

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