

Enhanced Traffic Management Procedures in Transition Areas

Dr. Sven Maerivoet



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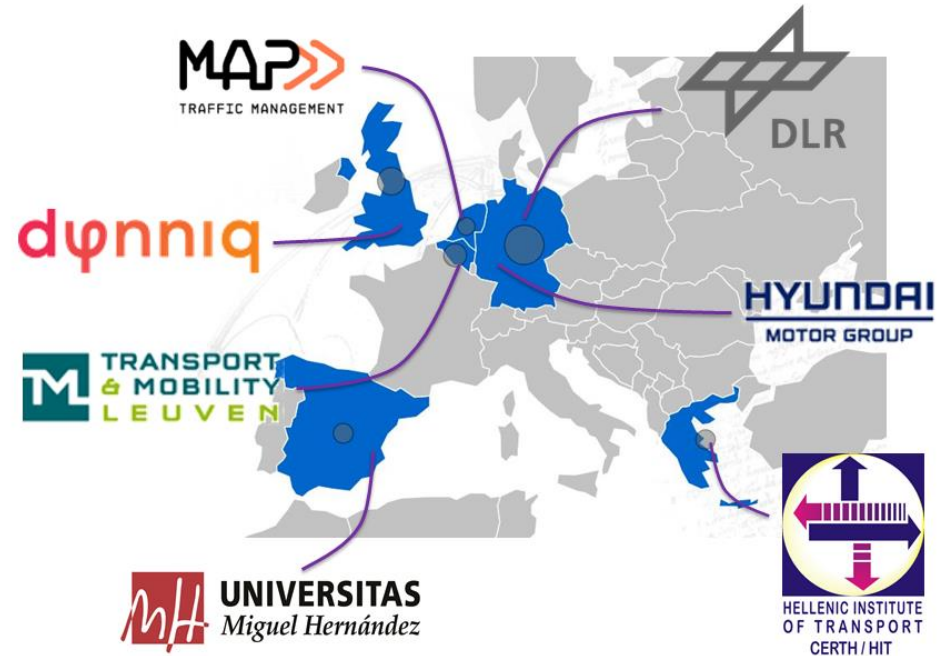
Scope and background

- Different SAE levels, (C)AVs, legacy vehicles, ... share the road
- Missing sensor inputs, highly complex situations, adverse weather, ...
 - Current limitations of automated driving may require a change of level
 - **Transition Areas**
- TransAID focuses on:
 - Realistic driver/vehicle behaviour and V2X communications
 - **Hierarchical traffic management procedures for transition areas**
 - Field tests in The Netherlands and Germany
 - Guidelines and roadmap for stakeholders (OEMs, authorities, cities, ...)

The TransAID project

- Horizon 2020 ART-05-2016
- 36 months (09/17-09/20)

Associated partners: Attikes Diadromes, Car2Car-Communication Consortium, DGT, ECTRI, EURECOM, Huawei, IKUSI, ITS Niedersachsen, Region of Central Macedonia, Rijkswaterstaat, TRL, and University of Twente.



SotA of traffic management

- **Main topics**

- General approaches

- Coordinated network-wide traffic management
 - Using KPIs, hierarchical controls via layered architectures, TMaaS

- Cooperative systems

- V2X / VANETs / C-ITS

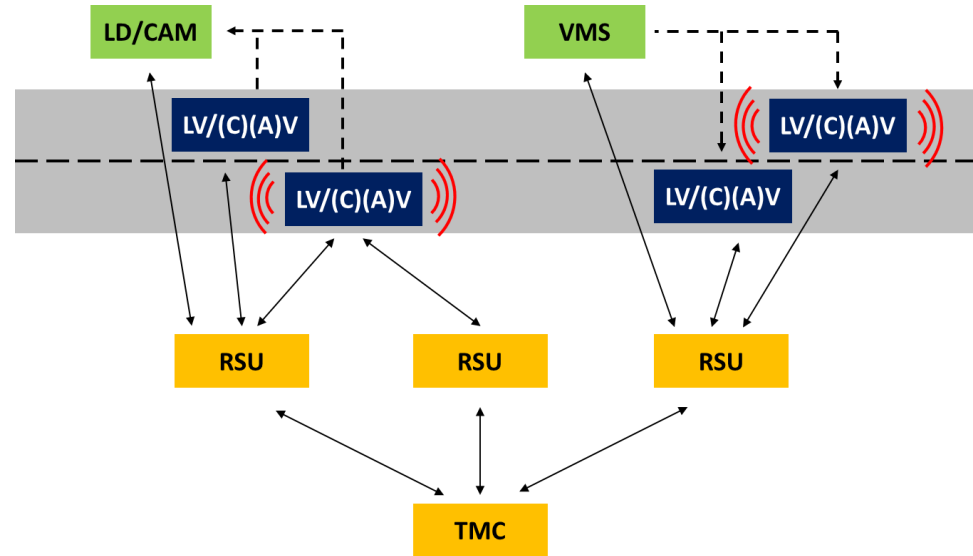
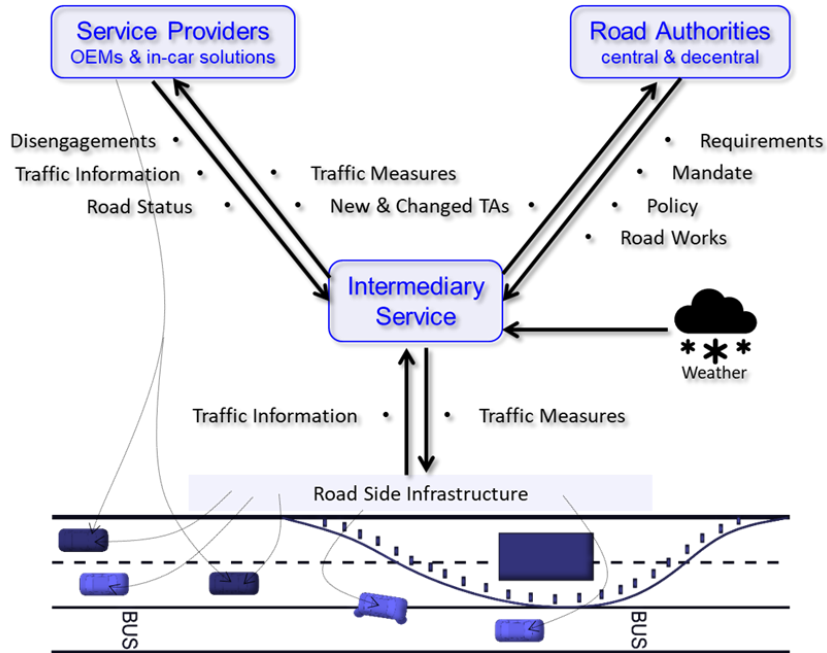
- Machine learning techniques (AI)

- Traffic light control and congestion / queue length predictions

- **Conclusion**

- No (readily available) implementations of more advanced TM schemes
 - Focus on solving partial problems with specific measures

Intermediary service provider



High- and low-level
traffic management operations

Simulation environment


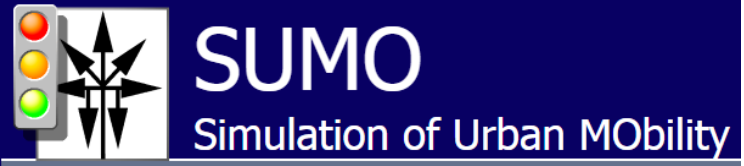


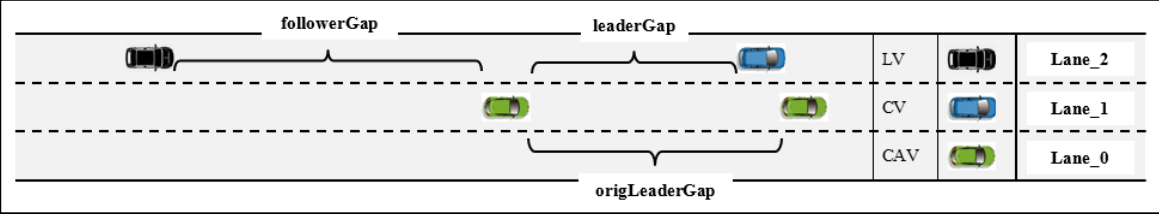
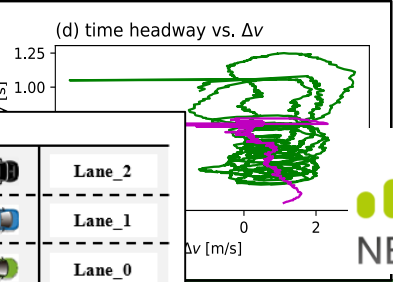
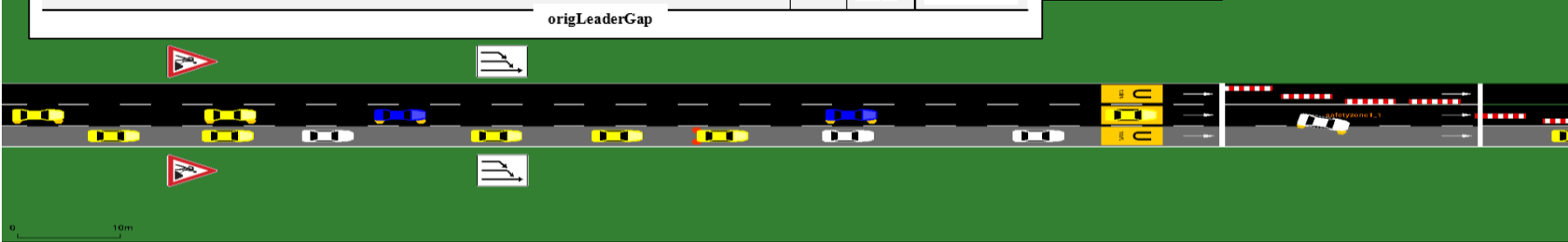








Diagram illustrating the simulation environment components and vehicle interactions:

Vehicle Lanes and Gaps:

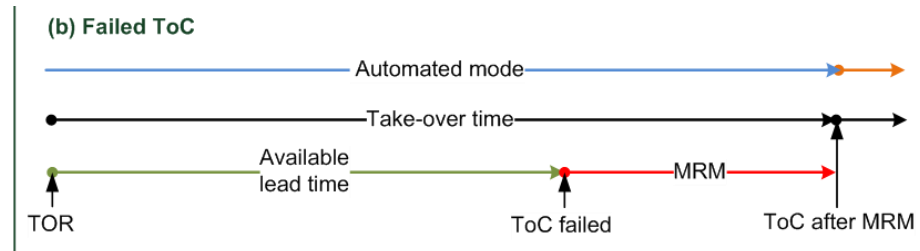
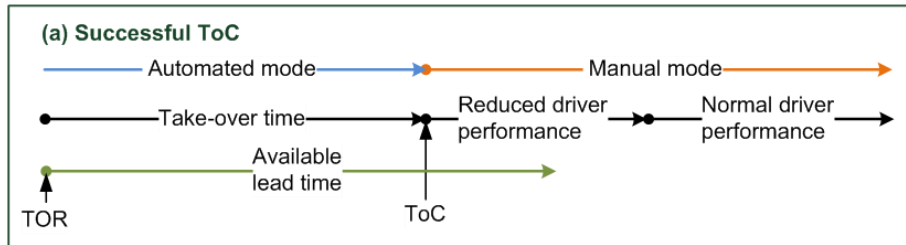
followerGap	leaderGap	LV	Lane_2
		CV	Lane_1
		CAV	Lane_0
origLeaderGap			

Graph (d) time headway vs. Δv :

The graph shows time headway (y-axis, 1.00 to 1.25) versus Δv [m/s] (x-axis, 0 to 2). The plot displays a green line representing a constant time headway and a purple line representing a variable time headway.

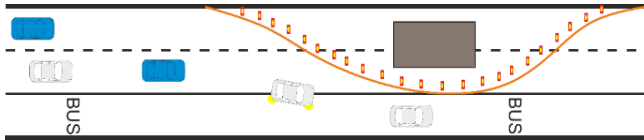
When AD is not possible/allowed

- Take-over request (**TOR**) issued by the car
- Transition of Control (**ToC**) from car to driver
- Minimum-Risk Maneuver (**MRM**) by the car

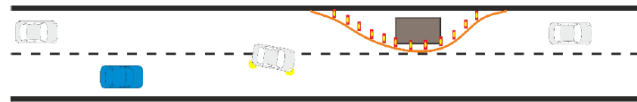


First selection of services / use cases

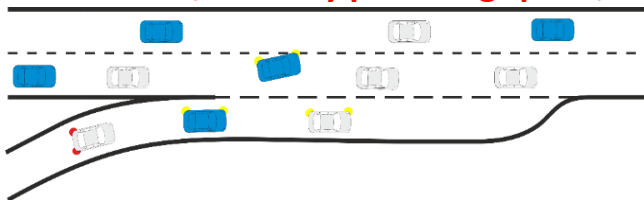
Prevent ToC/MRM by providing vehicle path information



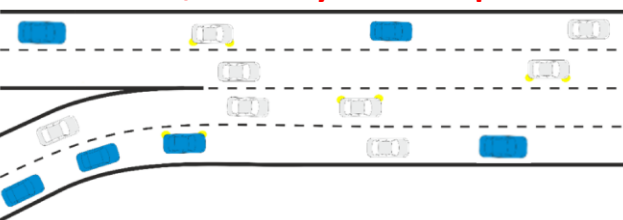
Manage MRM by guidance to safe spot (urban & motorway)



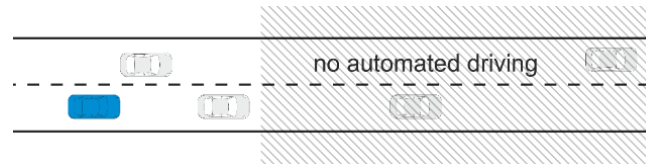
Prevent ToC/MRM by providing speed, headway and/or lane advice



Prevent ToC/MRM by traffic separation

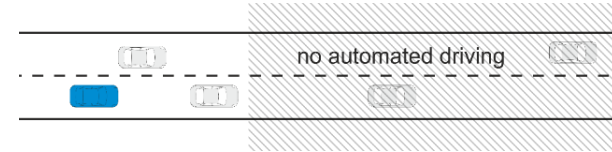


Distribute ToC/MRM by scheduling ToCs



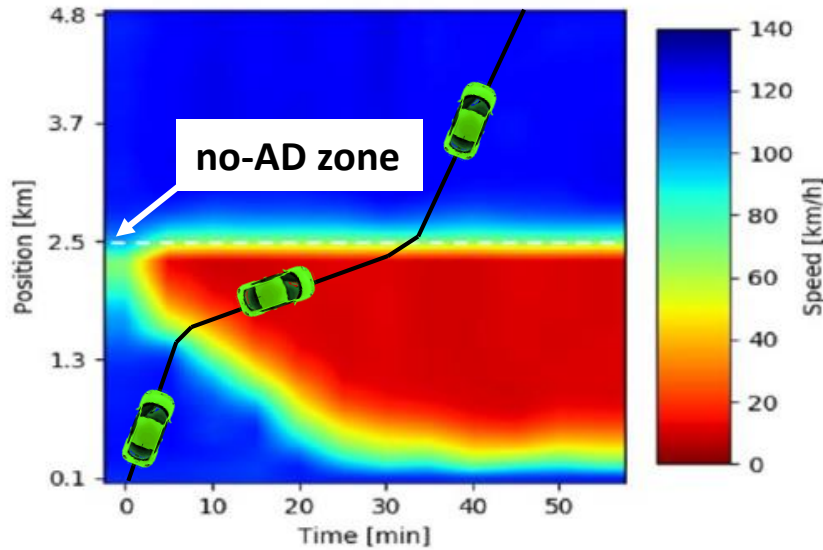
(with traffic conditions (LoS) and vehicle mixes)

Ex. Distribution of TORs



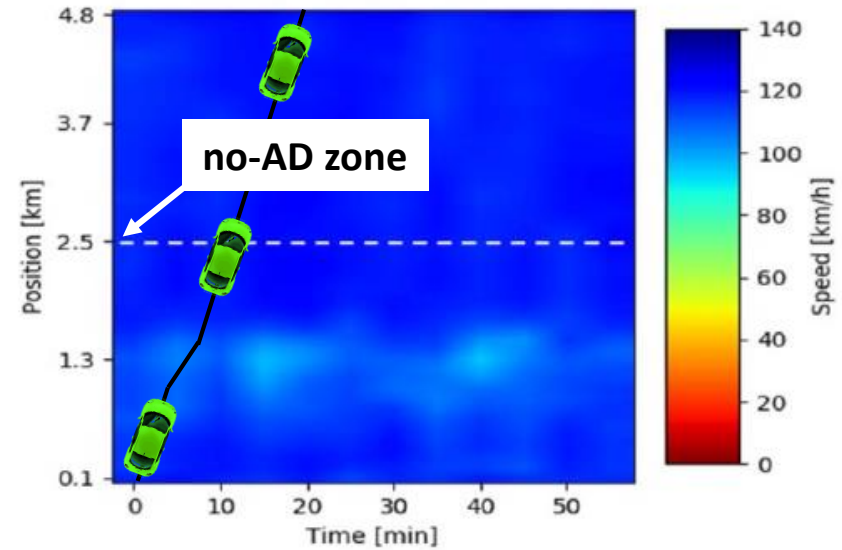
Without traffic management

LOS: C - Traffic Mix: 3 - Seed: 6



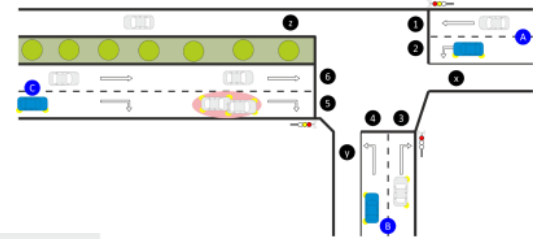
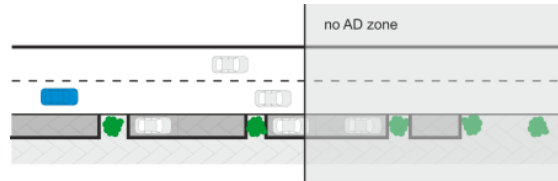
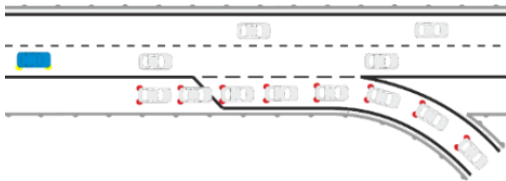
With traffic management

LOS: C - Traffic Mix: 3 - Seed: 6



Main results and outlook

- **Smother** traffic flows (higher average speeds and throughputs)
+ lower emissions (CO₂)
- **Safer** conditions (less time-to-collisions < 3 sec)
- Insights lead to:
 - New/modified use cases
 - Incorporation of realistic **V2X** communications



Deliverable D4.2

Let's stay in touch

- **Contact:**

- julian.schindler@dlr.de (DLR, project coordinator)
- sven.maerivoet@tmleuven.be (TML)

- **Social media:**



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