





Assessment of automated driving to design infrastructure-assisted driving at transition areas

Anton Wijbenga MAP traffic management, the Netherlands







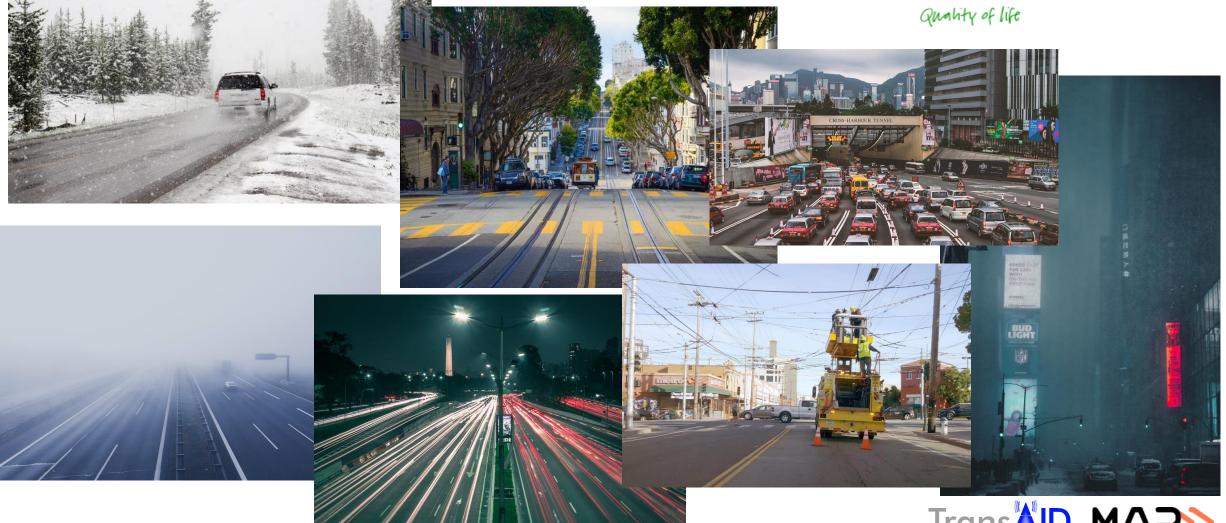




TransAID is funded by the EC Horizon 2020 Research and Innovation Framework Programme, under Grant Agreement No. 723390

### AUTOMATED DRIVING LIMITATIONS



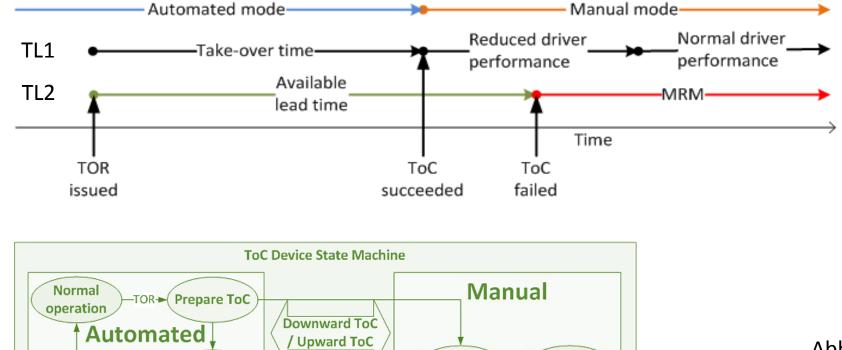






#### Perform Post-ToC Normal TOR: MRM operation Recovery ٠ ToC: • Constant decele-Increased driving errors: TL: • ration until stop Perception errors on object distance and speed difference (scaled with distance) Perception thresholds for changes (scaled with awareness and distance) TransAID is funded by the EC Horizon 2020 Research and Innovation Framework Programme, under Grant Agreement No. 723390

# TRANSITION OF CONTROL PROCESS





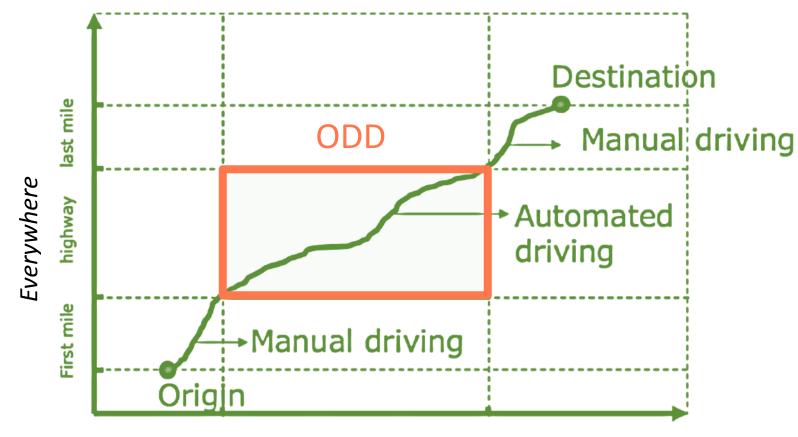
**Abbreviations** 

- Take Over Request
- Transition of Control
- MRM: Minimum Risk Manoeuvre
- Time Line



## CONSIDERING OPERATIONAL DESIGN DOMAIN





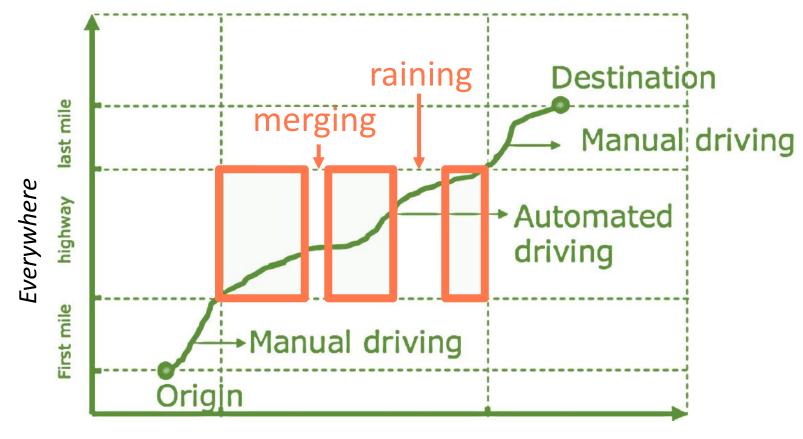
Always & All conditions



Tom Alkim, Rijkswaterstaat, 2017

## CONSIDERING OPERATIONAL DESIGN DOMAIN





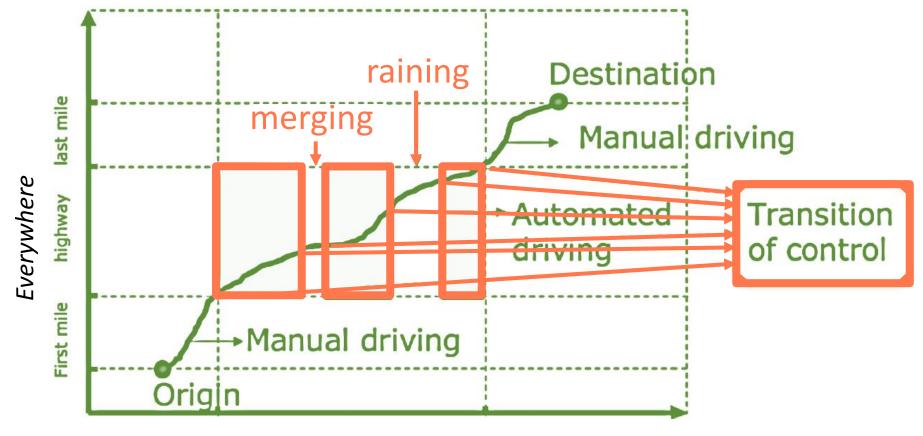
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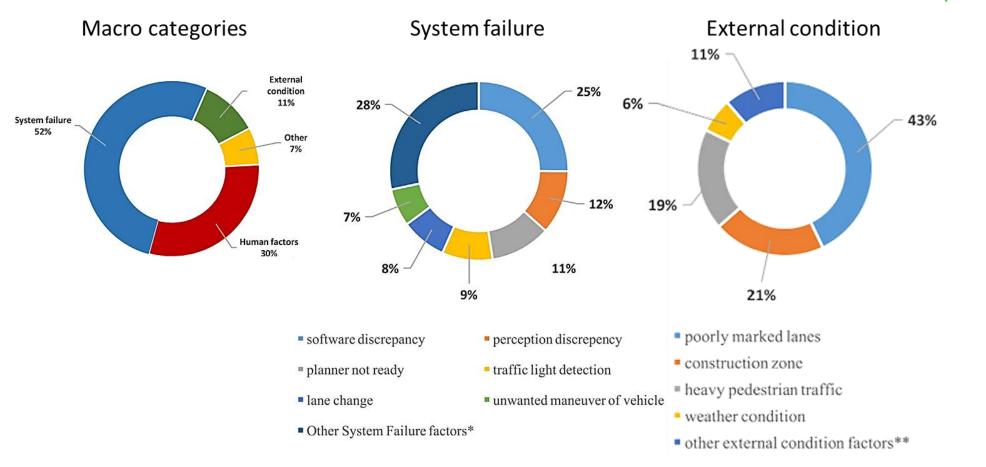
Always & All conditions



Tom Alkim, Rijkswaterstaat, 2017

### DISENGAGEMENT REPORTS 2017





Favaro et al. (2017). Autonomous vehicles' disengagements: Trends, triggers, and regulatory Limitations. *Accident Analysis & Prevention*, 110, 136–148.



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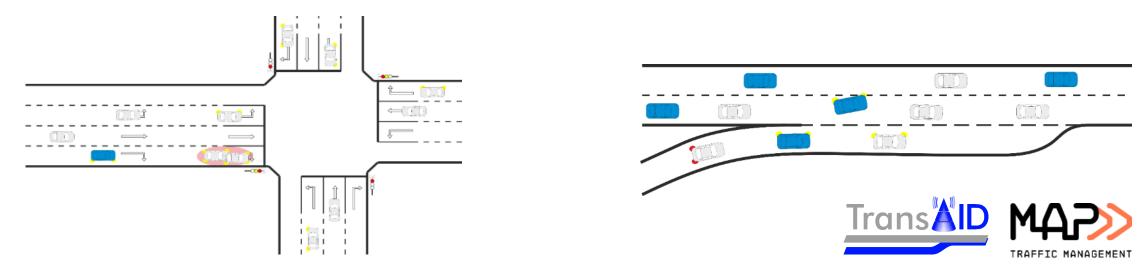
#### TransAID SERVICES AND USE CASES



• Service 1: Prevent ToC/MRM by providing vehicle path information



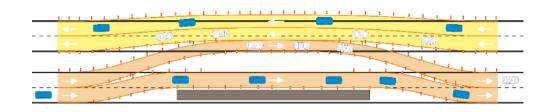
• Service 2: Prevent ToC/MRM by providing speed, headway and/or lane advice



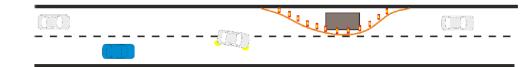
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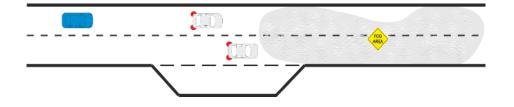


• Service 3: Prevent ToC/MRM by traffic separation



- Service 4: Manage MRM by guidance to safe spot







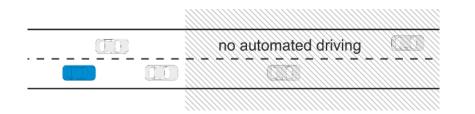


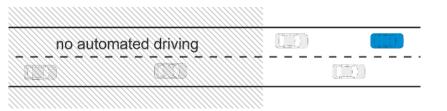


#### TransAID SERVICES AND USE CASES



• Service 5: Distribute ToC/MRM by scheduling ToCs

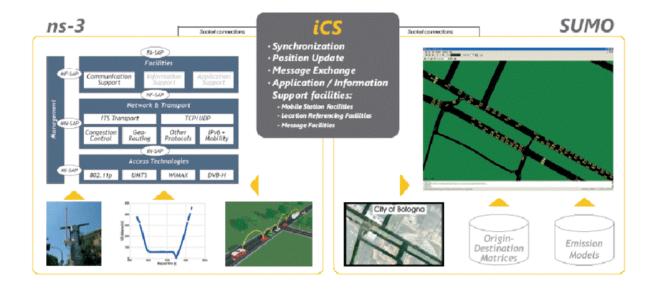






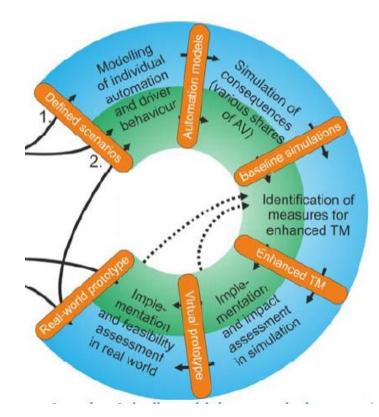


## TransAID UPCOMING ACTIVITIES







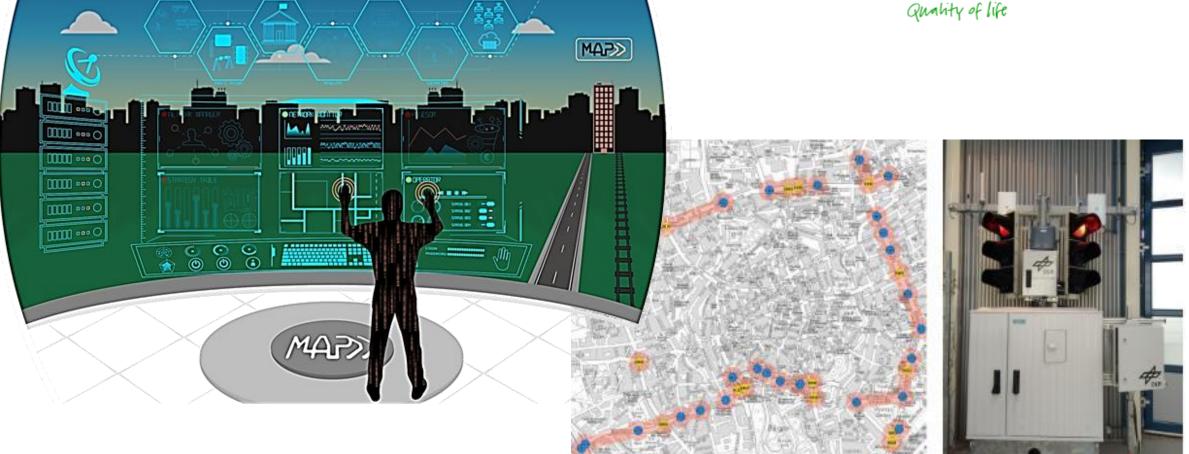






## TransAID UPCOMING ACTIVITIES















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