



TransAID

<u>Transition Areas for</u> <u>Infrastructure-Assisted Driving</u>

Project description, targets & partners

TransAID investigates (since 09/2017) the impact of new vehicle automation systems, focussing on situations where these systems are NOT working. For instance, due to system limitations, missing road markings, sensor malfunctions, complex intersections, construction sites, ...

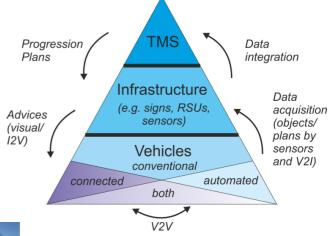
TransAID's objectives are:

- Perform simulations of different vehicle automations in different market penetrations.
- Develop new traffic management measures.
- Create new V2X message sets.

Traffic management, methodology and foreseen use cases

TransAID follows the approach of hierarchical traffic management.





Simulations using SUMO, ns-3, and the iTETRIS Framework are performed.

- Test prototypes and scenarios on real roads.
- Provide guidelines and a roadmap.

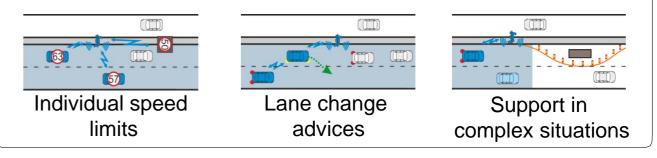
Project consortium:



Associated partners: Attikes Diadromes, Car2Car-Communication Consortium, DGT, ECTRI, EURECOM, Huawei, IKUSI, ITS Niedersachen, Region of Central Macedonia, Rijkswaterstaat, TRL, University of Twente

New traffic management measures to enhance traffic efficiency and safety are being developed and implemented as real-world prototypes on the AIM reference track in Braunschweig, Germany.

Examples of use cases:



Collaboration opportunities

Projects:

- TransAID is cooperating with related EU-funded projects in the domain of cooperative and automated driving, such as:
 - MAVEN (hierarchical traffic management)
 - INFRAMIX (traffic flow modelling, simulation of automated vehicles)
 - CoEXist (automation-ready framework for road authorities and traffic simulation tools)

Stakeholders:

- Stakeholder workshops are organised to get insight in the view of OEMs, cities, and road authorities for guidelines and roadmap creation.
- We welcome all stakeholders to be actively involved, especially OEMs, authorities, and end-users!

