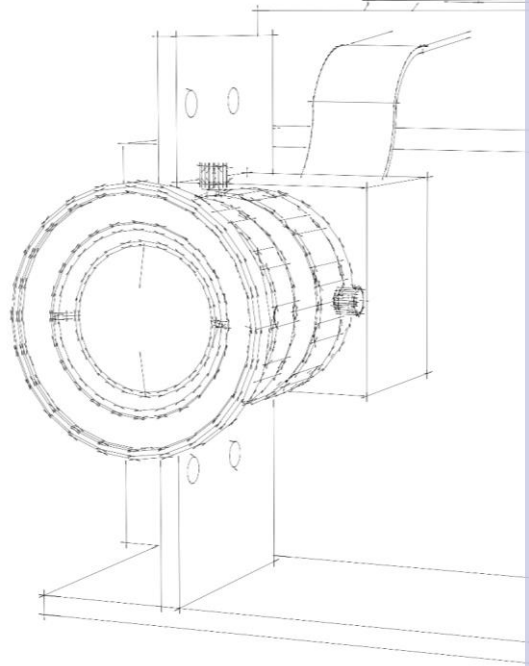




# GUARD-1

Underwater Autonomous  
Smart Camera



## Target

Infrastructure or environmental monitoring, in marine protected areas, coastal areas or open sea, up to the deepest and remote areas of the oceans

## Applications

fixed or mobile platforms (drifter buoys, ARGO Float, sea gliders, oceanographic moorings, landers, cabled observatories) also for long-term missions.

## Why

The programmable device is suitable for monitoring anthropogenic impacts and climate change effects, as well as the integrity of submerged artificial infrastructures:

# GUARD-1

## Underwater Autonomous Smart Camera



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### KEY FEATURES

- AI autonomous system
- Freely programmable frequency for time-lapse acquisition of images
- Adjustable image quality for deep-sea and shallow coastal areas.
- PYXALIS (HDR) and SONY CMOS sensor configurations
- Onboard storage for over 10,000 images (depending on image quality)
- PC board for implementation of customized processing algorithms (C++/Python) – YOCTO OS
- Image preprocessing function library for rapid prototyping
- Incorporated lighting system for operating in absence of natural light
- Battery pack for long autonomy (> 12 months, depending on the computational load)
- Easy re-charge, easy/fast image download and management
- Multiple mechanical configurations, deployable up to 1000 m depth
- Ethernet cable for PC data communication in shallow water deployments (1-3 m) or for connection to vehicles or buoys
- Internal high speed digital lines (i2C) for expansions electronics and communication devices.

### MONITOR

Biodiversity  
Mucilage  
Commercial fish species  
Invasive marine species  
Jellyfish invasion early-warning  
Underwater geological structures  
Marine protected areas  
Pipeline integrity  
Wrecks detection.



Multiple Optical Configuration  
C or CS mount compatible



Carrier Board and NX ITX  
computing board with STM32  
microcontroller



Some example pictures,  
courtesy of CNR-ISMAR

### PATENT

Made by Oengineering in accordance to the European patent EP2863257 by the National Research Council (Italy) and OnAir S.R.L. (Italy)



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