ΗΙΟΚΙ

Improve Power Conversion Efficiency

From DC to 2 MHz, industry's proven solution for high-accuracy power analysis. The High Accuracy Power Analyzer.



Upgrade New current sensors
Engineered for more accurate power measurement

Improved frequency bandwidth and accuracy



Scan QR Code to Watch Video

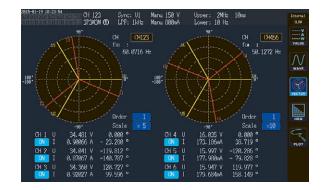


Achieving true power analysis

DC, 0.1 Hz to 2 MHz frequency bandwidth Obtain even greater accuracy in high-frequency power measurements with the aid of Hioki's current sensor phase shift function

A wide frequency range is required for power measurement due to the acceleration of switching devices, especially SiC. High accuracy, broadband, and high stability. The PW6001's world-class technology-based fundamental performance makes in-depth power analysis a reality.

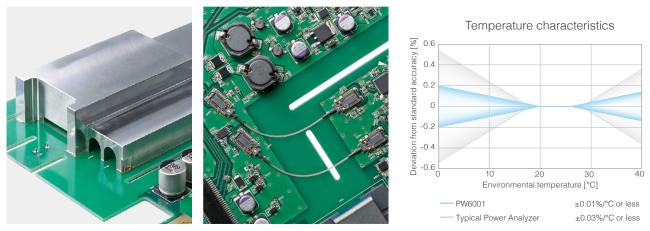
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I pk1+		A	UDF	48.5026	16 items	PLUI
I pk1-	-14.4671	Α	UDF ₂	271.864	37 items	
OFF			UDF16			
f1	59.9753	Hz	WP1+	4.8448 WH		



±0.02%* basic accuracy for power Strengthened resistance to noise and temperature fluctuations in the absolute pursuit of measurement stability

The custom-shaped solid shield made completely of finely finished metal and optical isolation devices used to maintain sufficient creepage distance from the input terminals dramatically improve noise resistance, provide optimal stability, and achieve a CMRR performance of 80 dB/100 kHz. Add the superior temperature characteristics of ±0.01%/°C and you now have access to a power analyzer that delivers top-of-the-line measurement stability.

*Device accuracy only



Solid shield

Optical isolation device

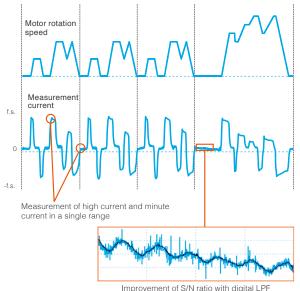
18-bit resolution, 5 MS/s sampling

Measurements based on sampling theorem are required to perform an accurate power analysis of PWM waveforms. The Hioki PW6001 features direct sampling of input signals at 5 MS/s, resulting in a measurement band of 2 MHz. This enables analysis without aliasing error.

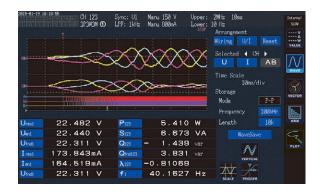


TrueHD 18-bit converter* measures widely fluctuating loads with extreme accuracy

A built-in 18-bit A/D converter provides a broad dynamic range. Even loads with large fluctuations can be shown accurately down to tiny power levels without switching the range. Further, a digital LPF is used to remove unnecessary high-frequency noise, for accurate power analysis.



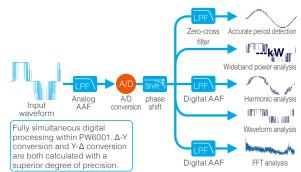
Conversion efficiency measurement during mode measurement without switching ranges



Achieve lightning fast calculations for 5 independent signal paths at the same time with the Power Analysis Engine II



Calculations for up to five independent signal paths (period detection/broadband power analysis/ harmonic analysis/waveform analysis/FFT analysis) are independently and digitally processed, eliminating any effects one may have on another. Achieve a 10 ms data update speed while maintaining full accuracy through high-speed processing.



* AAF (Anti-aliasing filter): This filter prevents aliasing errors during sampling.

^{*}True HD : True High Definition

Functions and Characteristics

Max Speed 10 ms, Maximum 12 ch* High Accuracy Power Calculation

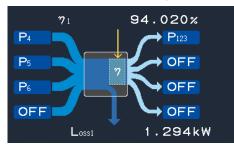
Data updates in 10 ms to 200 ms. Make high speed calculations while maintaining high accuracy. Achieve measurement stability with original digital filter technology, and measure power after automatically tracking frequency fluctuations from 0.1 Hz.

2815-86-24 17 84	Designations OH 1	Sync: U1	Manu 3		ns Intea.	Internal
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I ant		A	Qtrd1	-0.08787kvar		
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Upi1- Upi1-	135.864	v	71	100.000 % 0.00000kW		HRW
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Int-	-14.4671	A	UDF2	271.864	S2 Long	
OFF			UDF16			
	59.9753	Hz	WP1+	4.8448 Wh		

* Two 6-channel model devices, during synchronized function usage

Simple, high-precision efficiency and loss calculations

When measuring DC/AC converter efficiency, accuracy is required not only for AC but also DC. The basic DC measurement accuracy of the PW6001 is $\pm 0.02\%$, enabling you to make accurate and stable efficiency measurements.

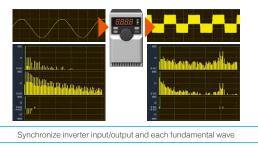


Setting up efficiency calculation formulas for power conditioners and similar equipment is simple on the dedicated screen. Simultaneously display loss and efficiency calculations for a maximum of four systems.

*Device accuracy

Independent harmonic analysis for a maximum of 6 systems (wideband/IEC)

0.1 Hz to 300 kHz fundamental frequency, 1.5 MHz analyzable bandwidth. Comes equipped with IEC61000-4-7-compliant harmonic analysis and up to 100th order wideband harmonic analysis.



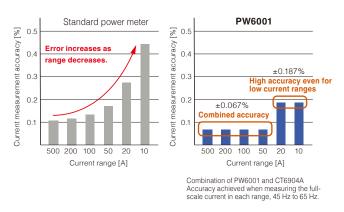
Applications

- Motor fundamental wave analysis
- Wireless power transmission waveforms
- Measuring distortion ratio of power conditioner output waveforms

Achieve high accuracy measurement, including in low current ranges

When used with a high accuracy current sensor*1, the PW6001 delivers exceptional accuracy*2. Achieve high accuracy measurement regardless of range, from high to low currents, even for loads that exhibit significant fluctuation.

Example of combination accuracy with current sensor

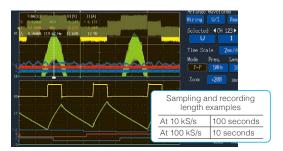


*1 Pass-through type: CT6872, CT6873, CT6875A, CT6876A, CT6877A, CT6904A Clamp type: CT6841A, CT6843A, CT6844A, CT6845A, CT6846A Direct connection type: PW9100A

*2 At DC and 50 Hz/60 Hz

Large-capacity waveform storage for oscilloscope and PQA-level waveform analysis

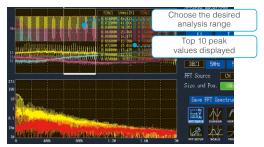
Waveform Storage of 1 MWord × (voltage-current 6 ch + Motor Analysis 4 ch). The torque sensor and encoder signals are displayed along with the voltage and current waveforms.



In addition to the level trigger function, the new event trigger starts recording when there is a fluctuation in RMS values or frequency. Cursor measurement and waveform zoom functions also render oscilloscopes unnecessary for waveform analysis.

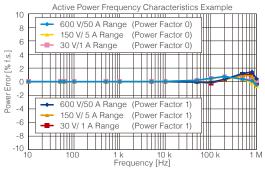
FFT analysis of target waveforms

Analyze frequencies up to 2 MHz across 2 channels. Specify any waveform analysis range you like and view the 10 highest peak values and frequencies. Observe frequency components that do not show up in harmonics and save the measured results.



Flat Frequency Characteristics

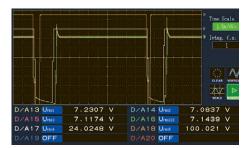
Frequency characteristics are flat up to 1 MHz even when the power factor is zero. Use together with the Current Sensor Phase Shift Function (see right) to make highly accurate low power factor measurements of high-frequency waves. It can very useful for assessing loss in high-frequency components like transformers and reactors.



* Options to further improve high-frequency wave phase characteristics available Contact us for more information

D/A Monitor

View up to 8 channels of progressive fluctuations in measured values. Voltage, current, power, frequency and other parameters are updated at the fastest rate of 10 ms, allowing you to observe even the tiniest variations.



Applications

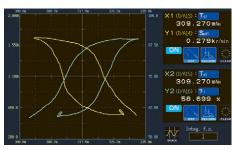
Power conditioner FRT Analysis

Motor Transient State Power Analysis

FRT (Fault Ride Through) : Ability to continue operation despite system disturbance in the power conditioner or similar systems

X-Y Plot

Easily check correlations in measured values for up to two systems simultaneously. Plot physical quantities other than measured values as well by using it together with the user defined calculation function.



Applications

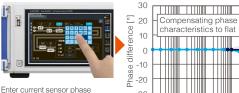
- Motor characteristics analysis
- Transformer characteristics analysis

• Power conditioner MPPT Analysis

MPPT: Maximum Power Point Tracker

Current Sensor Phase Shift Function

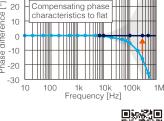
Our original virtual oversampling technology evolved ! It allows for phase compensation equivalent to that of a 2 GS/s oscilloscope a reality while maintaining 5 MS/s 18-bit high resolution. With this function, you can perform current sensor phase compensation with a 0.01° resolution, and measure power more accurately. This also makes high frequency, low power factor power measurements more accurate than ever before.



characteristic representative value

as phase compensation value (please refer to instruction manual

, version 03 or later)



*Scan the QR code on the right to download a technical brief about current sensor phase shift



Complex calculation formulas settable on the device

Set equations to compute measurement values any way you want. Enter up to 16 calculation formulas, including functions like sin and log. Calculation results can be used as parameters for other calculation formulas, enabling complex analysis.

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Applications

 Calculate multisystem efficiency and loss with solar power modules and similar equipment

Calculate Ld.Lg for motor vector control

Supports various power analysis systems

Improved connectivity to PCs over LAN. Remotely operate the PW6001 using a browser from any PC, tablet, or smartphone via the HTTP server function. Acquire files through the network with the FTP server function. LabVIEW driver and MATLAB Toolkit are also available.



* LabVIEW is a registered trademark of NATIONAL INSTRUMENTS MATLAB is a registered trademark of Mathworks, Inc.

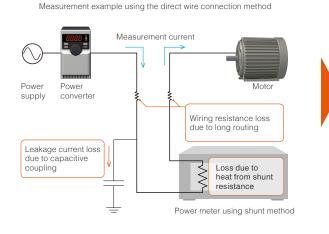
Specially designed for current sensors to achieve highly precise measurement

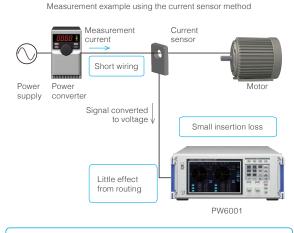
With direct wire connection method

The wiring of the measurement target is routed for connecting to the current input terminal. However, this results in an increase in the effects of wiring resistance and capacitive coupling, and meter loss occurs due to shunt resistance, all of which lead to larger accuracy uncertainty.

Advantages of current sensor method

A current sensor is connected to the wiring on the measurement target. This reduces the effects of wiring and meter loss, allowing measurements with wiring conditions that are close to the actual operating environment for a highly efficient system.





Compared to the direct wire connection method, measurement with conditions closer to the actual operation environment of a power converter is achieved

Seamless operability

Simple settings and intuitive operating interface.



9-inch touch screen with soft keypad



3P3W3M 3P3W3M Source Load Source 50/60Hz 50/60Hz HD DC DC HD G Ĥ 104. V 104 104 3 2 0. PWM HIGH FREQ. GENERAL LOW P 310.6mA 0.010 283 286.9mA а. аар 1mA T4

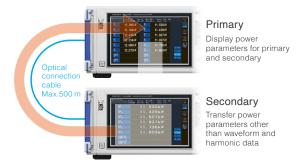
Quick Configuration screen*



* A low power factor measurement (LOW PF) mode for easily setting reactor and transformer loss measurement has been added.

Build a 12-channel power meter using "numerical synchronization"

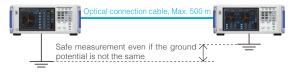
For multi-point measurements, use the numerical synchronization function to transfer power parameters from the secondary device to aggregate at the primary in realtime, essentially enabling you to build a 12-channel power analysis system



- Real-time display of secondary instrument measurement values on primary instrument screen
- · Real-time efficiency and loss calculations between primary and secondary instruments
- Save data for 2 units on recording media in primary instrument
- Use the secondary's measured values on the primary's user-defined calculations

Measure phase difference between 2 separate points

Use the waveform synchronization function to measure the phase relationship between 2 points separated by a maximum distance of 500 m. Due to insulation with an optical connection cable, measurement can be performed safely even if the ground potential between the 2 points is not the same.



Wide range of Motor Analysis functions

(Motor Analysis and D/A output model)

Enter signals from torque meters and speed meters to measure motor power. In addition to motor parameters such as motor power and electrical angle, output signals from insolation meters and wind speed meters can also be measured

measur	eu.			<u> </u>
Operating mode		Single	Dual	Independent input
	ch A Torque		Torque	Voltage/ Pulse
	ch B	Encoder A phase signal	Torque	Voltage/ Pulse
	ch C	Encoder B phase signal	RPM	Pulse
	ch D	Encoder Z phase signal	RPM	Pulse
Measurement targets		Motor x 1	Motor x 2, Motors, transmissions, etc.	Pyranometer/ anemometer and other output signals
Measurement		Electric angle Rotation direction Motor power RPM Torque Slip	Motor power x 2 RPM x 2 Torque x 2 Slip x 2	Voltage × 2 & Pulse × 2 or Pulse × 4

Simply transfer waveforms with "waveform synchronization"

Data sampled at 18 bits and 5 MS/s is sent between instruments in real time*, and the waveform measured by the secondary is displayed as-is on the primary instrument. This functionality lets you use the power analyzers to measure the voltage phase difference between two remote locations, for example at power substations, manufacturing plants, or railroad facilities.



channels of waveforms for primary and secondary

Transfer waveform data for max. 3

- · Real-time display of secondary instrument waveforms on primary instrument screen
- Harmonic analysis and fundamental wave analysis for primary instrument and secondary instrument
- · Simultaneously measure waveforms on primary device while using the secondary to trigger
- D/A output of the secondary instrument's waveform from the primary instrument

*For both primary instruments and secondary instrument,

waveform synchronization operates only when there are 3 or more channels. Max. ±5 sampling error.

D/A output waveforms captured 500m away

Transfer voltage/current waveforms taken by the secondary instrument located as far as 500m away and output the signals from the primary device. When combined with a Hioki MEMORY HiCORDER, timing tests and simultaneous analysis of multiple channels for 3-phase power are possible.



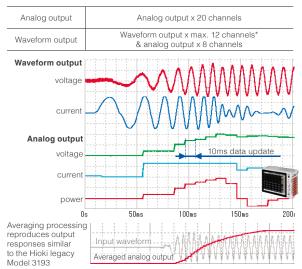
Max. analog 32 channels + logic 32 channels MEMORY HICORDER MR8827

> The waveform that is output has a delay of 7 µs to 12 µs, depending on the distance

Analog Output and 1 MS/s Waveform Output

(Motor Analysis and D/A output model)

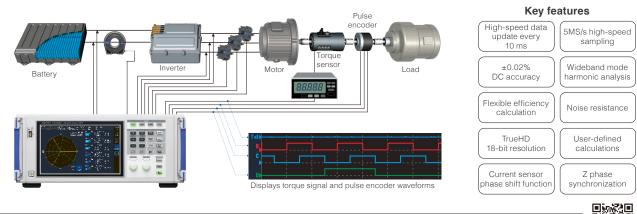
Output analog measurement data at update rates of up to 10ms. Combine with a data logger to record long-term fluctuations, and use the built-in waveform output function to output voltage and current at 1 MS/s*.



*During waveform output, accurate reproduction is possible at an output of 1 MS/s and with a sine wave up to 50 kHz.

Applications

EV/HEV inverter and motor analysis



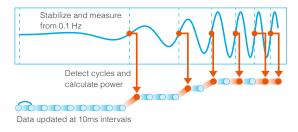
*Scan the QR code on the right to download a technical brief about SiC inverter power measurements.



Calculate transient state power with 10 ms high accuracy and high speed

Measure power transient states, including motor operations such as starting and accelerating, at 10 ms update rates. Automatically measure and keep up with power with fluctuating frequencies as low as 0.1 Hz.

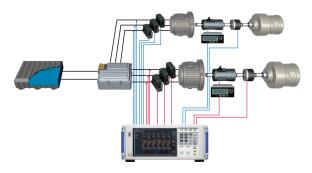
Further more, after a recent update, power calculation is now done every revolution of the motor, making efficiency calculations more stable than ever.



Even during frequency fluctuations from low to high, the fundamental waveform is automatically pursued. Comes equipped with $\Delta\text{-Y}$ and Y- Δ conversion while calculating with a high degree of accuracy.

Simultaneous measurement of 2 motor powers

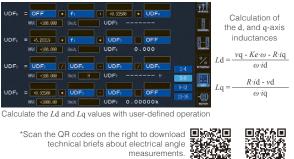
The PW6001 is engineered with the industry's first built-in dual mode motor analysis function that delivers the simultaneous analysis of 2 motors. Simultaneous measurement of the motor power for HEV driving and power generation is now possible.



Example of 2 motor measurement

Advanced electrical angle measurement function

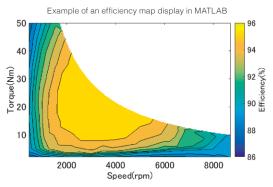
Comes equipped with electrical angle measurement necessary for vector control analysis via dq coordination systems as well as high efficiency synchronous motor parameter measurements. Measure voltage and current fundamental wave components based on encoder pulses in real time. In addition, analyze 4 quadrants of torque and rotation through detecting the forward/reverse from A-phasic and B-phasic pulses.

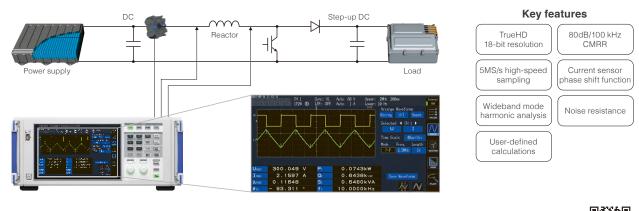


Evaluate inverter motor efficiency and loss

Evaluate efficiency and loss for an inverter, motor, and overall system by simultaneously measuring the inverter's input and output power and the motor's output. You can also create an efficiency map or loss map in MATLAB using measurement results recorded by the PW6001 at each operating point.

*MATLAB is a registered trademark of Mathworks, Inc.





Chopper circuit reactor loss measurement

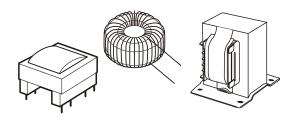
*Scan the QR code on the right to download a technical brief about reactor loss measurements



High-frequency and low power factor device evaluation

Reactors are used for high harmonic current suppression as well as the voltage step up/down of chopper circuits. The PW6001's outstanding high frequency characteristics, high-speed sampling, and noise-suppressing performance are effective in evaluating high-frequency, low power factor devices (reactors, transformers, etc.).

The low power factor measurement (LOW PF) mode in the simple setting mode makes measurement faster.



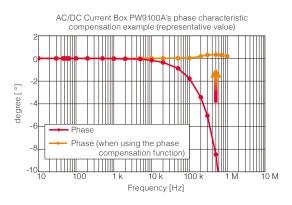
Harmonic analysis synchronized with switching frequencies

With the PW6001 you can perform harmonic analysis of fundamental waves up to 300 kHz with a band frequency of 1.5 MHz. For reactors used by chopper circuits, measure phase angles and RMS values for the current and voltage of each harmonic order through harmonic analysis synchronized with the switching frequency.



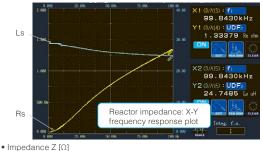
Current Sensor Phase Shift Function

In addition to the PW6001's flat, broad frequency characteristics, sensor phase error compensation allows highly accurate high-frequency and low power factor device analysis.

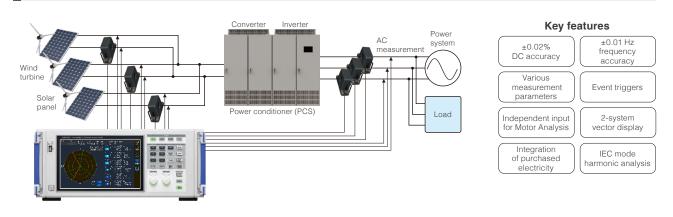


Circuit impedance analysis

Calculate circuit impedance, resistance, and inductance by using harmonic analysis results and user defined calculations. X-Y plot functions are especially effective for impedance analysis.



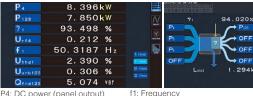
- = fundamental frequency voltage / fundamental frequency current Serial resistance RS [Ω]
- = Z × cos (voltage phase angle current phase angle)
 Serial inductance Ls [H]
- = Z × sin (voltage phase angle current phase angle) / (2 × π × frequency)



PV/Wind turbine Power Conditioner (PCS) Efficiency Measurement

Supports PCS-specific measurements

Simultaneously display the necessary parameters for PCS such as efficiency, loss, fundamental wave reactive power Qfnd, DC ripple ratio, three-phrase unbalanced factor, etc. Easily check the required measured items for improved test efficiency. In addition, by setting the DC power sync source to the output AC power channel, you can perform DC output and stable efficiency measurements perfectly synchronized with the output AC.

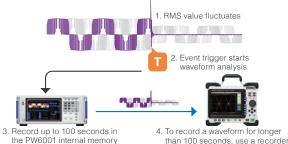


P4: DC power (panel output) P123: 3-phase power (power conditioner output) Urf4: Ripple rate n1: Conversion efficiency

Uthd1: Voltage total harmonic distortion Uunb123: Unbalance rate Qfnd123: Fundamental wave reactive power

Use event triggers to analyze waveforms

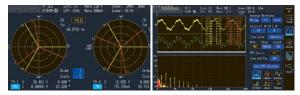
An event trigger function is now available with Ver.3.00. Set triggers for up to four measurement items, such as RMS value and frequency, and record waveforms during an event for up to 100 seconds. If you need to record waveforms for more than 100 seconds, use the D/A output function (Motor Analysis & D/A output option) to observe and record waveforms with a recorder, simplifying the evaluation system. (It is not necessary to connect a differential probe or current probe to the recorder.)



internal memory than 100 seconds, use a recorder to record the D/A output waveform

Harmonic analysis and conductive noise evaluation

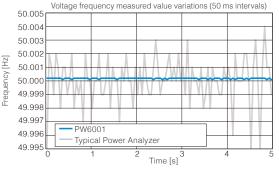
The PW6001 can perform IEC standard-based harmonic measurements that comply with IEC 61000-4-7. In wind power generation, where the generator hardware and grid operate at different frequencies, dual vector displays let you identify the tri-phase equilibrium at a glance. In addition, FFT analysis lets you to evaluate conductive noise generated by devices such as switching power supplies from 2 kHz to 150 kHz.



Measure output harmonics and noise through input waveform FFT analysis

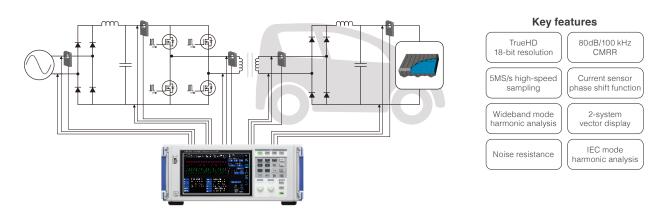
Voltage frequency measurement fundamental accuracy of ± 0.01 Hz*

Perform frequency measurements required for each PCS test with world-class accuracy and stability. Achieve highly accurate frequency measurement values for a maximum of 6 ch (12 ch when there are two devices) while measuring each parameter at the same time.



* ±0.01 Hz fundamental accuracy is defined for cases where the data update is over 50 ms. Please contact us for even more precise frequency measurement.

Measure the efficiency of wireless power transmission (WPT)



Accurate measurement, even of lowpower-factor power

In wireless power transfer / transmission (WPT), the inductance component of the energy transmit and receive elements lowers the power factor. The PW6001's current sensor phase shift function can be used to accurately measure high-frequency, low-power-factor power. In WPT measurement, it's extremely effective to combine the PW6001 with a high-bandwidth current measurement tool.



DC to 3.5 MHz (-3 dB) PW9100A

....

DC to 4 MHz CT6904A

Analyze transmission frequency harmonics

The PW6001's harmonic analysis function can analyze fundamental harmonics of up to 300 kHz at a bandwidth of up to 1.5 MHz. For example, with a circuit that uses an 85 kHz band switching frequency (a frequency that could be used in power transmission in electric vehicle applications) as the fundamental harmonic, the analyzer is capable of simultaneously measuring voltage, current, power, and phase angle for both receive and transmit through the 15th order.



display

display

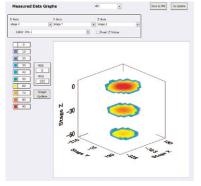
Automatic WPT TEST SYSTEM (For more information, please see the TS2400 product catalog.)

The WPT Evaluation System TS2400 is a system for automatically measuring the reproducible data that is required to evaluate WPT hardware by integrating measurement with an XYZ stage. A single software package provides control and automatic measurement functionality for instrument configuration, transmit and receive device positioning, and data collection. The results of analyses can be presented using a variety of bar graphs.

WPT evaluation supports the following types of measurement:

- Power transfer efficiency measurement (using the PW6001)
- · Automatic coupling coefficient measurement
- Voltage/temperature logging Magnetic flux density logging





WPT TEST SYSTEM TS2400

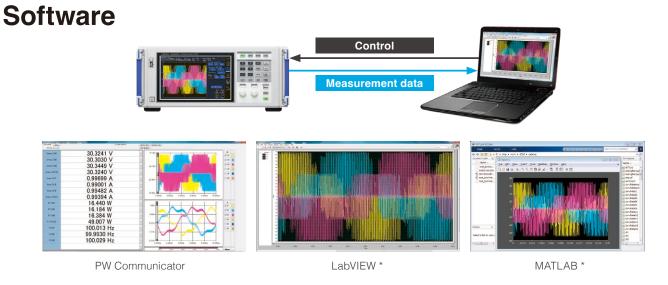
Example of a 4D graph of transfer efficiency

Interfaces Names of parts

USB flash drive —	
GP-IB	Data viewable through dedicated application Command control
RS-232C	Data viewable through dedicated application Command control Bluetooth® logger connection Send the D/A output of values measured with the PW6001 (maximum of 8 items) wirelessly to the Hioki Wireless Logging Station LR8410 using the dedicated cable and Bluetooth® serial conversion adapter. (Approx. 30m* line of sight)The observable output resolution. * The presence of obstructions (walls, metal, etc.) may shorten the communication range or destabilize the signal. * Bluetooth® is a trademark of Bluetooth SIG, Inc. and licensed for use by HIOKI E.E. CORPORATION.
External I/O	START/ STOP/ DATA RESET control Terminals shared with RS-232C, ±5 V/200 mA power supply possible
LAN	Gbit LAN supported Command control View data in free dedicated application

	RS-232C, External I/O GP-IB CP
Synchronous control	Optical connection cable connector, Duplex-LC (2-core)
D/A output (PW6001-11 to 16 only)	Switching for 20 channels of analog output or maximum 12 channels of waveform + 8 channels of analog output
Current probe input component	Power can also be supplied from the PW6001 to Probe1 or Probe2 by using the sliding cover.
Motor Analysis input component	Input signals from torque meters or rotation meters to measure motor power. Measure motor signals including electric angle and motor power from instruments such as actinometers and anemometers.
USB flash drive	Save waveform data/measured data (csv) Save screen copy (bmp) Save interval data (csv) in real time at the fastest interval of 10 ms
64 MB internal memory	Save interval data and send it to a USB flash drive later

Download the communication command manual from the HIOKI website at www.hioki.com



PC Communication Software – PW Communicator

PC Communicator is a free application that connects to the PW6001 via a communications interface (Ethernet, RS-232C, or GP-IB), making it easy to configure the instrument's settings and to monitor or save measured values and waveform data from a computer. The software can simultaneously connect to up to 8 Hioki power measuring instruments, including the PW6001, Power Analyzer PW3390, Power Meter PW3335, PW3336, and PW3337, and it can provide integrated control over multiple models. The software can also be used to simultaneously save measurement data on the computer and calculate efficiency between instruments.

LabVIEW driver and MATLAB toolkit

Hioki's LabVIEW driver and MATLAB toolkit can be used to build data collection and measurement systems. We also offer a number of sample programs to help you get started.
*LabVIEW is a registered trademark of National Instruments.
*MATLAB is a registered trademark of Mathworks, Inc.

GENNECT One SF4000

The SF4000 is a free application software that lets you display and save measurement data on a PC in real-time after connecting the PW6001 to the PC via Ethernet.

The application is also compatible with other Hioki measuring instruments such as Memory HiLogger LR8450 and the Wireless Logging Station LR8410, letting you connect up to 30 units at the same time to monitor, graph and display lists of measured values from multiple instruments all at once and in real-time. This is especially effective for performing a total analysis of power, temperature and other factors of equipment.



Download GENNECT One SF4000 to your PC

HUB

Power analyzer lineup

	Model	PW6001	PW8001+U7005	PW8001+U7001	PW3390
	Model			For measurement of	F W 3530
	Applications	For measurement of high-efficiency IGBT inverters	For measurement of SiC and GaN inverters and reactor/transformer loss	high-efficiency IGBT	Balance of high accuracy and portability
			reactor/transformer loss	inverters and solar inverters	
	Appearance				
	Measurement frequency band	DC, 0.1 Hz to 2 MHz	DC, 0.1 Hz to 5 MHz	DC, 0.1 Hz to 1 MHz	DC, 0.5 Hz to 200 kHz
	Basic accuracy for 50/60 Hz power	±(0.02% of reading + 0.03% of range)	±(0.01% of reading + 0.02% of range)	±(0.02% of reading + 0.05% of range)	±(0.04% of reading + 0.05% of range)
	Accuracy for DC power	±(0.02% of reading + 0.05% of range)	±(0.02% of reading + 0.03% of range)	±(0.02% of reading + 0.05% of range)	±(0.05% of reading + 0.07% of range)
	Accuracy for 10 kHz power	±(0.15% of reading + 0.1% of range)	±(0.05% of reading + 0.05% of range)	±(0.2% of reading + 0.05% of range)	±(0.2% of reading + 0.1% of range)
	Accuracy for 50 kHz power	±(0.15% of reading + 0.1% of range)	±(0.15% of reading + 0.05% of range)	±(0.4% of reading + 0.1% of range)	±(0.4% of reading + 0.3% of range)
srs	Number of power measurement channels	1 to 6 channels, a specify when ordering		specify U7001 or order (mixed available)	4 channels
mete	Voltage, current ADC sampling	18-bit, 5 MHz	18-bit, 15 MHz	16-bit, 2.5 MHz	16-bit, 500 kHz
tpara	Voltage range	6 V/15 V/30 V/60 V/150 V/ 300 V/600 V/1500 V	6 V/15 V/30 V/60 V/150) V/ 300 V/600 V/1500 V	15 V/30 V/60 V/150 V/ 300 V/600 V/1500V
Measuremen tparameters	Current range	Probe 1: 100 mA to 2000 A (6 ranges, based on sensor) Probe 2: 100 mV, 200 mV, 500 mV, 1 V, 2 V, 5 V	100 mA to 2000 A (6 ranges, based on sensor)	Probe 1: 100 mA to 2000 A (6 ranges, based on sensor) Probe 2: 100 mV, 200 mV, 500 mV, 1 V, 2 V, 5 V	100 mA to 8000 A (6 ranges, based on sensor)
	Common-mode voltage rejection ratio	50/60 Hz: 100 dB or greater 100 kHz: 80 dB typical	50/60 Hz: 120 dB or greater 100 kHz: 110 dB or greater	50/60 Hz: 100 dB or greater 100 kHz: 80 dB typical	50/60 Hz: 80 dB or greater
	Temperature coefficient	0.01%/°C	0.01	%/°C	0.01%/°C
	Voltage input method	Photoisolated input, resistor voltage division	Photoisolated input, resistor voltage division	Isolated input, resistor voltage division	Isolated input, resistor voltage division
	Current input method	Isolated input from current sensor	Isolated input fro	m current sensor	Isolated input from current sensor
	External current sensor input	Yes (ME15W, BNC)	Yes (ME15W)	Yes (ME15W, BNC)	Yes (ME15W)
	Power supplied to external current sensor	Yes	Yes		Yes
	Data update rate	10 ms, 50 ms, 200 ms	1 ms, 10 ms, 5	50 ms, 200 ms	50 ms
Voltage input	Maximum input voltage	1000 V,±2000 V peak (10 ms)	1000 V,±2000 V peak	1000 V AC, 1500 V DC, ±2000 V peak	1500 V, ±2000 V peak
<u>e</u>	Maximum rated line-to-ground voltage	600 V CAT III 1000 V CAT II	600 V CAT III 1000 V CAT II	600 V AC/1000 V DC CAT III 1000 V AC/1500 V DC CAT II	600 V CAT III 1000 V CAT II
alysis	Number of motor analysis channels	Maximum 2 motors*1		4 motors*1	Maximum 1 motors*1
An		Analog DC, frequency, pulse	Analog DC, frequency, pulse Yes (auto)		Analog DC, frequency, pulse
	Current sensor phase shift calculation	Yes		· · · ·	Yes
	Harmonics measurement Maximum harmonics analysis order	Yes (6, for each channel) 100th		ach channel) 0th	Yes 100th
	Harmonics synchronization frequency range	0.1 Hz to 300 kHz	0.1 Hz to 1.5 MHz	0.1 Hz to 1 MHz	0.5 Hz to 5 kHz
Ľ	IEC harmonics measurement	Yes		15 ^{*2}	-
Function	IEC flicker measurement	-	Ye	S*2	-
Fu	FFT spectrum analysis	Yes (DC to 2 MHz)	Yes*2 (DC ~ 4 MHz)	Yes*2 (DC ~ 1 MHz)	Yes (DC to 200 kHz)
	User-defined calculations	Yes	Y	es	-
	Delta conversion	Yes (Δ-Υ, Υ-Δ)	Yes (Δ·	-Y, Y-Δ)	Yes (Δ-Y)
	D/A output	Yes*1 20 ch (waveform output, analog output)	Yes*1 20 ch (waveform	output, analog output)	Yes*1 16 ch (waveform output, analog output)
Display	Display	9" WVGA TFT color LCD	10.1" WVGA	TFT color LCD	9" WVGA TFT color LCD
Dis	Touch screen	Yes		es	-
	External storage media	USB 2.0		3 3.0	USB 2.0, CF card Yes
	LAN (100BASE-TX, 1000BASE-T)	Yes		es	(10BASE-T and 100BASE-TX only)
ace	GP-IB	Yes	Yes		-
Interface	RS-232C	Yes (maximum 230,400 bps)		n 115,200 bps)	Yes (maximum 38,400 bps)
_⊆	External control	Yes		es	Yes
	Synchronization of multiple instruments	- -		instruments)	Yes (up to 8 instruments)
	Optical link	Yes		*1*2 *1	-
Dim	CAN or CAN FD	- 430 mm (16.93 in.) × 177 mm (6.97 in.) × 450 mm (17.72 in.) 14 kg (493.84 oz.)	430 mm (16.93 in.) × 221 mm	(8.70 in.) × 361 mm (14.21 in.))3.84 oz.)	- 340 mm (13.39 in.) × 170 mm (6.69 in.) × 156 mm (6.14 in.) 4.6 kg (162.26 oz.)

*1: Sold separately *2: This is a feature that will be supported in the upcoming firmware update to Ver. 2.0.

Specifications

Power measurement

	1-phase/ 3-phase/	2-wire (1P2W 3-wire (3P3V	/), 1-phase/3-wi /2M, 3V3A, 3P3	W3M), 3-phas	e/4-wire (3P4W	/)		
	CH1	CH2	CH3	CH4	CH5	CH6		
Pattern 1	1P2W	1P2W	1P2W	1P2W	1P2W	1P2W		
Pattern 2	1P3W/	3P3W2M	1P2W	1P2W	1P2W	1P2W		
Pattern 3	1P3W / 3	3P3W2M	1P2W	1P3W / 3	3P3W2M	1P2W		
Pattern 4	1P3W /	3P3W2M	1P3W /	3P3W2M	1P3W / 3	3P3W2M		
Pattern 5	3P3)	W3M / 3V3A /	3P4W	1P2W	1P2W	1P2W		
Pattern 6	3P3	W3M / 3V3A /	3P4W	1P3W /	3P3W2M	1P2W		
Pattern 7	3P3	3P3W3M / 3V3A / 3P4W 3P3W3M / 3V3A / 3P4W 3P3W3M / 3V3A / 3P4W						
			ations, select 1 ations, select 3					
Number of								
channels	1	2	3	4	5	6		
Pattern 1	1	1	1	1	1	1		
Pattern 2	-	1	1	1	1	1		
Pattern 3	-	-	-	-	-	1		
Pattern 4	-	-	-	1	-	1		
Pattern 5	-	-	1	1	1	1		
Pattern 6	-	-	-	-	1	1		
Pattern 7	-	-	-	-	-	1		
			hat can be sele		the number of o	channels:		
	[√] Can t	be selected, [·	–] Cannot be se	lected				
lumber of input	Max. 6 c	hannels; ead	h input unit pro	ovides 1 chanr	nel for simultar	neous volta		
hannels	and curre							
	Voltage	Plua-in	terminals (safe	ty terminals)				
nput terminal profile	Probe 1	Dedica	ted connector (I	VE15W)				
	Probe 2	BNC (m	netal) + power s	upply terminal				
Probe 2 power aver			0.5 V, max. 60	0 mA, up to a	max. of 700 n	nA for up to		
Probe 2 power supp	ly channels							
nout method		measuremen		plated input, re	sistance voltag	e divider		
nput method		measuremen			rent sensor (vo			
/oltage range	6 V / 15 V	//30V/60V	/ / 150 V / 300 V	/ 600 V / 1500	V			
-			A/4A/8A/20		(with 20 A sen	sor)		
			A / 4 A / 8 A / 20 / 80 A / 200 A	A	(with 20 A sen (with 200 A se			
Current range			A/ 800 A/ 2 kA		(with 2000 A s			
Probe 1)					(with 50 A sen			
	10 A / 20	1 A / 2 A / 5 A / 10 A / 20 A / 50 A (with 50 A sensor) 10 A / 20 A / 50 A / 100 A / 200 A / 500 A (with 500 A sensor)						
	20 A / 40	20 A / 40 A / 100 A / 200 A / 400 A / 1 kA (with 500 A sensor)						
	11.4 (0	LA / E LA / 40	LA (00 LA (50)//			
			kA / 20 kA / 50					
			/1 kA/2 kA/5					
Probe 2)			0 A / 200 A / 50					
		/ 5 A / 10 A /			V/A sensor; with			
		100 mA / 200 mA / 500 mA / 1 A / 2 A / 5 A (with 1 V/A sensor; with CT6700 or CT6701						
	(0.1 V / 0	.2 V / 0.5 V /	1.0 V / 2.0 V / 5.	0 V range)				
Power range	2.40000	W to 9.00000) MW (dependin		nd current com	binations)		
Power range	3 (relativ	e to voltage/c) MW (dependin urrent range rat	ig on voltage a		binations)		
	3 (relativ however,	e to voltage/c 1.33 for 150) MW (dependin urrent range rai) V range, 1.5 fo	ig on voltage a ting); or 5 V Probe 2 i	range	binations)		
	3 (relativ however, 300 (rela	e to voltage/c , 1.33 for 150 tive to minim) MW (dependin urrent range rat	ig on voltage a ting); or 5 V Probe 2 i e and current ir	range iput);	binations)		
Crest factor	3 (relativ however, 300 (rela	e to voltage/c , 1.33 for 150 tive to minim , 133 for 1500) MW (dependin urrent range ra) V range, 1.5 fo um valid voltage	ig on voltage a ting); or 5 V Probe 2 i e and current ir	range iput);	binations)		
Crest factor	3 (relativ however, 300 (rela however,	e to voltage/c , 1.33 for 1500 tive to minim , 133 for 1500 inputs) MW (dependin urrent range ra) V range, 1.5 fo um valid voltage V range, 150 fo	ig on voltage a ting); or 5 V Probe 2 i e and current ir	range iput); range	binations)		
Crest factor	3 (relativ however, 300 (rela however, Voltage Probe 1	e to voltage/c , 1.33 for 1500 tive to minim , 133 for 1500 inputs inputs	0 MW (dependin urrent range rai 0 V range, 1.5 fc um valid voltage V range, 150 fc 4 MΩ ±40 kΩ	ig on voltage a ting); or 5 V Probe 2 i and current ir or 5 V Probe 2 in Probe 2 in	range aput); range puts 1 M:			
Crest factor	3 (relativ however, 300 (rela however, Voltage	e to voltage/c , 1.33 for 1500 tive to minim , 133 for 1500 inputs inputs inputs	 MW (dependin current range rai 0 V range, 1.5 fd um valid voltage V range, 150 fd 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 ¹ Input voltage freq 	ig on voltage a ting); or 5 V Probe 2 i e and current ir or 5 V Probe 2 in Probe 2 in Probe 2 in Vpeak (10 ms c uency of 250 kH	range iput); range puts 1 M pr less) iz to 1 MHz, (125	Ω ±50 kΩ 0 - f) V		
Crest factor nput resistance 50 Hz / 60 Hz)	3 (relativ however, 300 (rela however, Voltage Probe 1 Voltage	e to voltage/c 1.33 for 1500 tive to minim 133 for 1500 inputs inputs inputs	0 MW (dependin urrent range rat 0 V range, 1.5 fc um valid voltage V range, 150 fc 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 Input voltage freq Input voltage freq	ig on voltage a ting); or 5 V Probe 2 i e and current ir or 5 V Probe 2 Probe 2 in Vpeak (10 ms c vuency of 250 kH aquency of 1 M	range iput); range puts 1 M pr less) iz to 1 MHz, (125	Ω ±50 kΩ 0 - f) V		
Crest factor nput resistance 50 Hz / 60 Hz)	3 (relativ however, 300 (rela however, Voltage Probe 1 Voltage	e to voltage/c 1.33 for 150 tive to minim 133 for 1500 inputs inputs inputs	0 MW (dependin urrent range rai) V range, 1.5 fc um valid voltage V range, 150 fc 4 MΩ \pm 40 kΩ 1 MΩ \pm 50 kΩ 1000 V, \pm 2000 1000 V, \pm 2000 Unput voltage fre Unit for f above:	g on voltage a ting); or 5 V Probe 2 i and current ir or 5 V Probe 2 in Probe 2 in Vpeak (10 ms c uency of 250 kH aquency of 1 M kHz	range iput); range puts 1 M: or less) iz to 1 MHz, (125 Hz to 5 MHz, 5	Ω ±50 kΩ 0 - f) V		
Crest factor nput resistance 50 Hz / 60 Hz)	3 (relativ however, 300 (rela however, Voltage Probe 1 Voltage	e to voltage/c 1.33 for 150 tive to minim 133 for 1500 inputs inputs inputs inputs	0 MW (dependin urrent range rat 0 V range, 1.5 fc um valid voltage V range, 150 fc 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 Input voltage freq Input voltage freq	ig on voltage a ting); or 5 V Probe 2 i and current in probe 2 inj Vpeak (10 ms c iuency of 250 kH aquency of 1 M kHz (10 ms or less)	range iput); range puts 1 M: or less) iz to 1 MHz, (125 Hz to 5 MHz, 5	Ω ±50 kΩ 0 - f) V		
Crest factor nput resistance 50 Hz / 60 Hz)	3 (relativ however, 300 (rela however, Voltage Probe 1 Voltage Probe 1 Probe 2	e to voltage/c 1.33 for 1500 tive to minimu 133 for 1500 inputs inputs inputs inputs	MW (dependim urrent range ratio 0 V range, 1.5 fo um valid voltage 1 V range, 150 fc 4 MΩ \pm 40 kΩ 1 MΩ \pm 50 kΩ 1000 V, \pm 2000 ¹ 1000 V, \pm 2000 V, \pm 2000 ¹ 1000 V, \pm 2000 V, \pm	ig on voltage a ting); or 5 V Probe 2 i and current in probe 2 inj Vpeak (10 ms c iuency of 250 kH aquency of 1 M kHz (10 ms or less)	range iput); range puts 1 M: or less) iz to 1 MHz, (125 Hz to 5 MHz, 5	Ω ±50 kΩ 0 - f) V		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt	3 (relativ however, 300 (rela however, 300 (rela however, Voltage Probe 1 Voltage Probe 1 Probe 2	e to voltage/c 1.33 for 1500 tive to minimu 133 for 1500 inputs inputs inputs inputs inputs nput terminal	MW (dependin urrent range ratio 0 V range, 1.5 ft 4 M Ω ±40 kQ 1 M Ω ±50 k Ω 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±2020 0 V, ±202 V, ±202 Vistage freq input voltage freq input voltage freq input voltage freq 0 V, ±202 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz)	g on voltage a ting); or 5 V Probe 2 i and current ir or 5 V Probe 2 in Probe 2 in Vpeak (10 ms or uuency of 250 kH aquency of 1 M k Hz (10 ms or less) (10 ms or less)	range iput); range puts 1 M: r less) z to 1 MHz, (125 Hz to 5 MHz, 5	Ω ±50 kΩ 0 - f) V		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt	3 (relativ however, 300 (rela however, Voltage Probe 1 Voltage Probe 1 Probe 2 age Voltage i CATIII 6(e to voltage/c 1.33 for 1500 tive to minimu 133 for 1500 inputs inputs inputs inputs nput terminal 00V; anticipat	MW (dependim urrent range ratio 0 V range, 1.5 fo um valid voltage 1 V range, 150 fc 4 MΩ \pm 40 kΩ 1 MΩ \pm 50 kΩ 1000 V, \pm 2000 ¹ 1000 V, \pm 2000 V, \pm 2000 ¹ 1000 V, \pm 2000 V, \pm	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Vpeak (10 ms c juency of 250 kH aquency of 1 M kHz (10 ms or less) (10 ms or less) ervoltage: 6000	range ipput); range puts 1 M: pr less) iz to 1 MHz, (125 Hz to 5 MHz, 5	Ω ±50 kΩ 0 - f) V		
Crest factor nput resistance 50 Hz / 60 Hz) Aaximum input volt Aaximum rated volte o earth	3 (relativ however, 300 (rela however, Probe 1 Probe 1 Probe 2 Voltage Quitage i Voltage i Voltage i Voltage v Voltage v V Voltage v Voltage v Voltage v Voltage v Voltage v V V Voltage v Voltage v V Voltage v V V V V V V V V V V V V V V V V V V V	e to voltage/c 1.33 for 1500 tive to minimi 133 for 1500 inputs inputs inputs inputs inputs oput terminal 00V; anticipat current simu	MW (dependim urrent range, 1.5 fc um valid voltage V range, 1.50 fc 4 MΩ \pm 40 kΩ 1 MΩ \pm 50 kΩ 1000 V, \pm 2000 1000 V, \pm 2000 1000 V, \pm 2200 1000 V, \pm 2200 1000 V, \pm 2200 (000 V, \pm 2200 (000 V, \pm 2200) (000 V, \pm 200 (000 V, \pm 200) (000 V, \pm200) (000 V, \pm 200) (000 V, \pm200) (000 V, \pm20)	g on voltage a ting); or 5 V Probe 2 ? Probe 2 inj Vpeak (10 ms c juency of 250 kH aquency of 1 M kHz (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000	range ipput); range puts 1 M: or less) iz to 1 MHz, (125 Hiz to 5 MHz, 5 W ov	Ω ±50 kΩ 0 - f) V 0 V		
Crest factor nput resistance 50 Hz / 60 Hz) Aaximum input volt Aaximum rated volte o earth	3 (relativ however, 300 (rela however, Probe 1 Voltage Probe 1 Probe 2 age Voltage i CATIII 60 CATIII 10 CATII 10	e to voltage/c 1.33 for 1500 tive to minimi 133 for 1500 inputs inputs inputs inputs inputs oput terminal 00V; anticipat current simu	MW (dependim urrent range ratio 0 V range, 1.5 fc um valid voltage 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±12 Vpeak 8 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) (50 Hz/60 Hz)	g on voltage a ting); or 5 V Probe 2 : Probe 2 inj Vpeak (10 ms c juency of 250 kH aquency of 1 M kHz (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000	range ipput); range puts 1 M: or less) iz to 1 MHz, (125 Hiz to 5 MHz, 5 W ov	Ω ±50 kΩ 0 - f) V 0 V		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volta o earth Measurement metho	3 (relativ however, 300 (rela however, Probe 1 Probe 1 Probe 2 Voltage Quitage i Voltage i Voltage i Voltage v Voltage v V Voltage v Voltage v Voltage v Voltage v Voltage v V V Voltage v Voltage v V Voltage v V V V V V V V V V V V V V V V V V V V	e to voltage/c 1.33 for 1500 tive to minimum 133 for 1500 inputs inputs inputs inputs inputs input terminal 00Y; anticipat courrent simu on	MW (dependim urrent range ratio 0 V range, 1.5 fc um valid voltage 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±12 Vpeak 8 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) (50 Hz/60 Hz)	g on voltage a ting); or 5 V Probe 2 : Probe 2 inj Vpeak (10 ms c juency of 250 kH aquency of 1 M kHz (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000	range ipput); range puts 1 M: or less) iz to 1 MHz, (125 Hiz to 5 MHz, 5 W ov	Ω ±50 kΩ 0 - f) V 0 V		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volta o earth Measurement meth Sampling	3 (relativ however, 300 (relativ however, 200 (relativ however, 200 (relativ however, 200 (relativ however, 200 (relativ Probe 1 Probe 1 Probe 1 Probe 1 Probe 2 200 (relativ ATII 6 CATII 10 CATII 10 CATII 10 Catulativ 5 MHz / '	e to voltage/c 1.33 for 1500 tive to minimum 133 for 1500 inputs inputs inputs inputs inputs input terminal 00Y; anticipat courrent simu on	MW (dependim urrent range ratio 0 V range, 1.5 fc um valid voltage 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±12 Vpeak 8 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) (50 Hz/60 Hz)	g on voltage a ting); or 5 V Probe 2 : Probe 2 inj Vpeak (10 ms c juency of 250 kH aquency of 1 M kHz (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000	range ipput); range puts 1 M: or less) iz to 1 MHz, (125 Hiz to 5 MHz, 5 W ov	Ω ±50 kΩ 0 - f) V 0 V		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volta o earth Measurement meth- Sampling Frequency band	3 (relativ however, 300 (relativ however, 300 (relativ Probe 1 Voltage Probe 1 Voltage Probe 1 Probe 2 Voltage CATII 0 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10	e to voltage/c 1.33 for 1500 inputs inputs inputs inputs inputs inputs ovi anticipat ovi ovi anticipat ovi anticipat ovi antic	MW (dependim urrent range ratio 0 V range, 1.5 fc um valid voltage 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±12 Vpeak 8 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) (50 Hz/60 Hz)	g on voltage a ting); or 5 V Probe 2 : Probe 2 inj Vpeak (10 ms c juency of 250 kH aquency of 1 M kHz (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000	range ipput); range puts 1 M: or less) iz to 1 MHz, (125 Hiz to 5 MHz, 5 W ov	Ω ±50 kΩ 0 - f) V 0 V		
Power range Crest factor Input resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volt Aaximum rated volt Aaximum rated volt Gampling Frequency band Synchronization requency range	3 (relativ however, 300 (relativ however, 200 (relativ however, 200 (relativ however, 200 (relativ however, 200 (relativ Probe 1 Probe 1 Probe 1 Probe 1 Probe 2 200 (relativ ATII 6 CATII 10 CATII 10 CATII 10 Catulativ 5 MHz / '	e to voltage/c 1.33 for 1500 inputs inputs inputs inputs inputs inputs ovi anticipat ovi ovi anticipat ovi anticipat ovi antic	MW (dependim urrent range ratio 0 V range, 1.5 fc um valid voltage 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±2000 1000 V, ±12 Vpeak 8 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) (50 Hz/60 Hz)	g on voltage a ting); or 5 V Probe 2 : Probe 2 inj Vpeak (10 ms c juency of 250 kH aquency of 1 M kHz (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000	range ipput); range puts 1 M: or less) iz to 1 MHz, (125 Hiz to 5 MHz, 5 W ov	Ω ±50 kΩ 0 - f) V 0 V		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volta o earth Measurement methon Sampling Frequency band Synchronization	3 (relativ however, 300 (relativ however, 300 (relativ Probe 1 Voltage Probe 1 Probe 1 Probe 2 Probe 1 Probe 2 Voltage CATII 10 CATII 10 C	e to voltage/c 1.33 for 1500 tive to minimum 133 for 1500 inputs inputs inputs inputs inputs ovy; anticipat ovy; anticipat ovy; anticipat current simu an 18 bits 12 to 2 MHz 2 MHz , I1 to 16, DC	MW (dependin urrent range rai 0 V range, 1.5 fc 4 MΩ ±40 kΩ 1 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 0 1000 V, ±2000 0 1000 V, ±2000 0 5 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) ed transient ove ted transient ove ted transient ove (fixed at data up	g on voltage a ting); or 5 V Probe 2 of Probe 2 in Vpeak (10 ms c uency of 250 kH quency of 250 kH quency of 250 kH (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 il sampling wi	range ipput); range puts 1 M: or less) iz to 1 MHz, (125 Hiz to 5 MHz, 5 W ov	Ω ±50 kΩ 0 - f) V 0 V		
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Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volta o earth Measurement methon Sampling Frequency band Synchronization	3 (relativ however, 300 (relativ however, 300 (relativ however, Voltage Probe 1 Voltage Probe 1 Probe 2 Voltage CATII 0 CATII 10 CATII 10	e to voltage/c 1.33 for 1500 inputs inputs inputs inputs inputs inputs ov; anticipat ov; anticipat ov	MW (dependin urrent range rai 0 V range, 1.5 fc 4 MΩ ±40 kΩ 1 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 0 Input voltage free Input voltage free Unit for f above; 5 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) ed transient ove ted transient ove ted transient ove (fixed at data up	g on voltage a ting); or 5 V Probe 2 i Probe 2 inj Probe 2 inj Vpeak (10 ms or kHz (10 ms or less) (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 il sampling wi bodate rate), a after passing	range ipput); range r less) iz to 1 MHz, (125 Hz to 5 MHz, 5 DV DV	Ω ±50 kΩ 0 - f) V 0 V		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volta o earth Measurement methon Sampling Frequency band Synchronization requency range	3 (relativ however, 300 (relativ however, 300 (relativ however, Voltage Probe 1 Voltage Probe 1 Probe 2 Probe 1 Probe 2 Voltage CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 DC, 0.1 Hz to U1 to U6 The zerc is used a	e to voltage/c 1.33 for 1500 inputs inputs inputs inputs inputs inputs inputs ov; anticipat ov; anticipat current simu n 18 bits 12 to 2 MHz 2 MHz , I1 to I6, DC xt2, Zph, CH -cross point is the standar	MW (dependin urrent range rai 0 V range, 1.5 fc 4 MΩ ±40 kQ 1 MΩ ±40 kQ 1 MΩ ±50 kΩ 1000 V, ±2000 1 1000 V, ±2000 1 000 V, ±2000 1 5 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) de transient ove ted transient ove (fixed at data up C, CH D of the waveform d for U or I sele	g on voltage a ting); or 5 V Probe 2 i Probe 2 inj Probe 2 inj Vpeak (10 ms or kHz (10 ms or less) (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 il sampling wi bodate rate), a after passing	range ipput); range r less) iz to 1 MHz, (125 Hz to 5 MHz, 5 DV DV	Ω ±50 kΩ 0 - f) V 0 V		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volt: o earth Measurement methons Sampling Frequency band Synchronization requency range Synchronization sou	3 (relativ however, 300 (relativ however, 300 (relativ however, 200 (relativ however, 200 (relativ Probe 1 Probe 1 Probe 1 Probe 1 Probe 2 Probe 1 Probe 2 Voltage CATIII 60 CATII 10 DC, 0.1 H DC, 0.1 Hz to 5 MHz / ' DC, 0.1 Hz to 0.1 Hz to 5 kt 10 E Ext1 to Ext1 to Ex	e to voltage/c 1.33 for 150 tive to minimum 133 for 1500 inputs inputs inputs inputs inputs mput terminal 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 100V; anticip	MW (dependin urrent range rai 0 V range, 1.5 fc 4 MΩ ±40 kQ 1 MΩ ±40 kQ 1 MΩ ±50 kΩ 1000 V, ±2000 1 1000 V, ±2000 1 000 V, ±2000 1 5 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) de transient ove ted transient ove (fixed at data up C, CH D of the waveform d for U or I sele	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Vpeak (10 ms c uency of 250 kH (10 ms or less) (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 il sampling wit bodate rate), n after passing ction.	range iput); range 1 M: r less) iz to 1 MHz, (125 Hz to 5 MHz, 5 0V 0V th zero-cross through the zero	Ω ±50 kΩ 0 - f) V 0 V synchronize		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volt: o earth Measurement methons Sampling Frequency band Synchronization requency range Synchronization sou	3 (relativ however, 300 (rela however, 300 (rela however, 300 (rela however, 200 (rela Probe 1 Probe 1 Probe 1 Probe 1 Probe 2 CATII 0 CATII 10 CATII 10 CATII 10 CATII 10 S MHz / 1 DC, 0.1 H DC, 0.1 H DC, 0.1 H to U6 Ext1 to E The zerc is used a 10 m s / 5 When us	e to voltage/c 1.33 for 150 tive to minimum 133 for 1500 inputs inputs inputs inputs inputs mput terminal 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 100V; anticip	MW (dependin urrent range, 1-5 fo urrent range, 1-5 fo urrent range, 1-5 fo urrent range, 1-5 fo 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 1 1000 V, ±2000 V, ±2000 1 1000 V, ±2000 V, ±200	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Vpeak (10 ms c uency of 250 kH (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 il sampling wi bodate rate), n after passing ction.	range iput); range 1 M: r less) iz to 1 MHz, (125 Hz to 5 MHz, 5 0V 0V th zero-cross through the zero	Ω ±50 kΩ 0 - f) V 0 V synchronize		
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Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volta o earth Measurement metho Sampling Grequency band Synchronization requency range Synchronization sou Data update rate	3 (relativ however, 300 (relativ however, 300 (relativ however, 200 (relativ however, 200 (relativ Probe 1 Probe 1 Probe 1 Probe 2 Probe 1 Probe 2 Voltage CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 DC, 0.1 H DC, 0.1 H DC, 0.1 H The zero is used a 10 ms / 5 When us of averag 500 Hz / Approx. 6	e to voltage/c 1.33 for 150 tive to minimi 133 for 1500 inputs inputs inputs inputs inputs input terminal 00Y; anticipat 00Y; anticipat 00Y; anticipat 00Y; anticipat 00Y; anticipat 1 to 16, DC 1 xt2, 20h, CH -cross point 1 kHz / 5 kHz 00 kHz analoj hen off, add	MW (dependin urrent range, 1.5 fc U range, 1.5 fc 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 V 1000 V 1000 V, ±2000 V 1000 V V 1000 V 10	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Probe 2 in Vpeak (10 ms or kHz (10 ms or less) (10 ms or less) (10 ms or less) ervoltage: 6000 il sampling wi bdate rate), a after passing ction. ta update rate Hz / 100 kHz / 5 a filter (Butterway	through the zero-cross	Ω ±50 kΩ 0 · f) V 0 V synchronize ero-cross fill on the numb ics equivale		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volta o earth Measurement methe Sampling Frequency band Synchronization requency range Synchronization sou Data update rate _PF	3 (relativ however, 300 (relativ however, 300 (relativ however, 200 (relativ however, 200 (relativ Probe 1 Probe 1 Probe 1 Probe 2 Probe 1 Probe 2 Voltage CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 DC, 0.1 H DC, 0.1 H DC, 0.1 H The zero is used a 10 ms / 5 When us of averag 500 Hz / Approx. 6	e to voltage/c 1.33 for 150 tive to minimi 133 for 1500 inputs inputs inputs inputs inputs input terminal 00Y; anticipat 00Y; anticipat 00Y; anticipat 00Y; anticipat 00Y; anticipat 1 to 16, DC 1 xt2, 20h, CH -cross point 1 kHz / 5 kHz 00 kHz analoj hen off, add	MW (dependim urrent range, 1.5 fr urrent range, 1.5 fr urrent range, 1.5 fr urrent range, 1.50 fr 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 1 1000 V, ±2000 V, ±2000 1 1000 V, ±2000 V, ±20	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Probe 2 in Vpeak (10 ms or kHz (10 ms or less) (10 ms or less) (10 ms or less) ervoltage: 6000 il sampling wi bdate rate), a after passing ction. ta update rate Hz / 100 kHz / 5 a filter (Butterway	through the zero-cross	Ω ±50 kΩ 0 · f) V 0 V synchronize ero-cross fill on the numb ics equivale		
Crest factor Input resistance 50 Hz / 60 Hz) Aaximum input volt Aaximum input volt Aaximum rated volts o earth Aeasurement metho Sampling Frequency band Synchronization Synchronization sou Data update rate PF Polarity detection	3 (relativ however, 300 (rela however, 300 (rela however, 300 (rela however, 300 (rela however, 300 (rela however, 300 (rela however, 200 (rela ho	e to voltage/c 1.33 for 150 tive to minim 133 for 1500 inputs inputs inputs inputs inputs inputs over anticipat 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 100V; anticipat 11 to 16, DC xt22, Zph, CH -cross point is the standar 00 ms / 200 m ing simple av ing simple av 11 kH / 5 kHz 00 kHz analo vire anticipat 10 kHz / 5 kHz	MW (dependin urrent range, 1.5 fc U range, 1.5 fc 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 V 1000 V 1000 V, ±2000 V 1000 V V 1000 V 10	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Vpeak (10 ms c uency of 250 kH aquency of 250 kH (10 ms or less) (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 il sampling wi odate rate), a after passing ction. ta update rate Hz / 100 kHz / 5 R filter (Butterw e accuracy. than or equal to	through the zero-cross	Ω ±50 kΩ 0 · f) V 0 V synchronize ero-cross fill on the numb ics equivale		
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Crest factor Input resistance 50 Hz / 60 Hz) Aaximum input volt Aaximum input volt Aaximum rated volts o earth Aeasurement metho Sampling Frequency band Synchronization Synchronization sou Data update rate PF Polarity detection	3 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 200 (relativ Probe 1 Probe 1 Probe 1 Probe 1 Probe 2 Probe 1 Probe 2 Voltage CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 DC, 0.1 Hz 10 DC, 0.1 H	e to voltage/c 1.33 for 1500 tive to minimum 133 for 1500 inputs inputs inputs inputs inputs inputs ov; anticipat 00%, anticipat 00%, anticipat 00%, anticipat 10%, anticipat 11 to 16, DC 12 to 2 MHz 2 MHz 2 MHz 11 to 16, DC 12 KHZ, 20 MHZ 2 MHZ 11 to 16, DC 12 KHZ, 20 MHZ 13 KHZ / 5 KHZ 00 kH	MW (dependin urrent range, 1-5 fo urrent range, 1-5 fo urrent range, 1-5 fo urrent range, 1-5 fo 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 1 input voltage fred Unit for f above: 5 V, ±12 Vpeak (50 Hz/60 Hz) ed transient ove ted tra	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Probe 2 in Vpeak (10 ms or S0 V Probe 2 in Vpeak (10 ms or kHz (10 ms or less) (10 ms or less) (10 ms or less) ervoltage: 6000 il sampling wi bodate rate), a after passing ction. ta update rate A filter (Butterwo A filter or equal to a r (P), apparen	range puts 1 M: pr less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 V V V V v th zero-cross through the zero varies based c 500 kHz / OFF porth characterist b 1/10 of the se tt power (S), re	Ω ±50 kΩ 0 - f) V 0 V synchronize pro-cross filt in the numb ics equivale t frequency.		
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Crest factor Input resistance 50 Hz / 60 Hz) Aaximum input volt Aaximum rated volt: o earth Aeasurement meth Sampling Trequency band Synchronization Paynchronization sou Data update rate PF Polarity detection Oltage Aeasurement	3 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 200 (relativ Probe 1 Probe 1 Probe 2 Voltage CATII 0 CATII 10 CATII 10	e to voltage/c 1.33 for 1500 inputs inputs inputs inputs inputs inputs inputs over anticipat over an	MW (dependin urrent range, 1.5 ft 2 V range, 1.5 ft 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 0 1000 V, ±2000 0 1000 V, ±2000 0 1000 V, ±2000 0 5 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) ed transient ove ted tra	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Vpeak (10 ms of kHz quency of 250 kH quency of 250 kH quency of 250 kH quency of 1 M kHz (10 ms or less) (10 ms or less) (10 ms or less) trivoltage: 6000 ervoltage: 6000 ervoltage: 6000 il sampling wi bodate rate), h after passing ction. ta update rate A filter (Butterw e accuracy. than or equal ta n rr (P), apparen), frequency (f)	through the zero-cross through the zero-cross through the zero-cross through the zero-cross	Ω ±50 kΩ 0 - f) V 0 V synchroniz ero-cross fill on the numb ics equivale t frequency. pactive pow), loss (Los		
Crest factor Input resistance 50 Hz / 60 Hz) Aaximum input volt Aaximum rated volta Aaximum rated volta a earth Aeasurement meth sampling requency band Synchronization equency range Synchronization sou Data update rate PF Volarity detection oltage Measurement arameters Effective measurem	3 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ Probe 1 Probe 1 Probe 2 Probe 1 Probe 2 Voltage CATIII 60 CATIII	e to voltage/c 1.33 for 150 tive to minimum 133 for 1500 inputs inputs inputs inputs inputs mut terminal 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 10V; anticipat 11V; antici	MW (dependin urrent range, 15 ft 20 V range, 15 ft 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 1000 V, ±2000 V, ±2000 1000 V, ±2000 V, ±2000 V, ±2000 1000 V, ±2000 V	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Vpeak (10 ms of uency of 250 kH (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 ervoltage: 6000 il sampling with after passing ction. ta update rate Hz / 100 kHz / f R filter (Butterwo e accuracy. than or equal to n rr (P), apparen prophe factor (I (Upk), current	through the zero-cross through the zero-cross through the zero-cross through the zero-cross	Ω ±50 kΩ 0 - f) V 0 V synchroniz ero-cross fill on the numb ics equivale t frequency. pactive pow), loss (Los		
Crest factor nput resistance 50 Hz / 60 Hz) Maximum input volt Maximum rated volta o earth Measurement meth- sampling requency band Synchronization requency range Synchronization sou Data update rate .PF Polarity detection oltage Measurement arameters Effective measurem	3 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ Probe 1 Probe 1 Probe 2 Probe 1 Probe 2 Voltage CATII 10 CATII 10 CATII 10 CATII 10 DC, 0.1 H 0.1 Hz to 10 ms / 5 When us of average 500 Hz / Approx. 6 Except tw Defined 1 Current z Voltage (0), power in ant Voltage,	e to voltage/c 1.33 for 150 tive to minimum 133 for 1500 inputs inputs inputs inputs inputs mut terminal 00% anticipat 00% anticip	MW (dependin urrent range, 1.5 fc 2 V range, 1.5 fc 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 0 1000 V, ±2000 0 1000 V, ±2000 0 1000 V, ±2000 0 5 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) ed transient ove ted tra	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Vpeak (10 ms of uency of 250 kH (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 ervoltage: 6000 il sampling with after passing ction. ta update rate Hz / 100 kHz / f R filter (Butterwo e accuracy. than or equal to n rr (P), apparen prophe factor (I (Upk), current	through the zero-cross through the zero-cross through the zero-cross through the zero-cross	Ω ±50 kΩ 0 - f) V 0 V synchronize ero-cross fill on the numb ics equivale t frequency. pactive pow), loss (Los		
Crest factor Input resistance 50 Hz / 60 Hz) Aaximum input volt Aaximum rated volts o earth Aeasurement metho Sampling Frequency band Synchronization Prequency range Synchronization sou Data update rate PF Polarity detection oltage Aeasurement barameters Effective measurem ange Zero-suppression	3 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 200 (relativ Probe 1 Probe 1 Probe 2 Voltage CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 CATII 10 DC, 0.1 H DC, 0.1 H	e to voltage/c 1.33 for 1500 1.33 for 1500 inputs inputs inputs inputs inputs inputs inputs ov; anticipat 00%; anticipat 00%; anticipat 00%; anticipat 00%; anticipat 00%; anticipat 18 bits 4z to 2 MHz 2 MHz 1 to 16, DC xt2, Zph, CH- -cross point ing simple as ing simple as ing simple as ing simple as 1 kHz / 5 kHz 00 kHz analog tereo-cross tim (U), current I er factor (A), ripple factor ter factor ter factor (A), ripple factor ter factor	MW (dependimurrent range rai) urrent range, 1.5 fc 0 Y range, 1.5 fc 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 ¹ 1000 V, ±100 ¹	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Probe 2 in Vpeak (10 ms or kHz (10 ms or less) (10 ms or less) (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 il sampling wi bodate rate), a after passing ction. ta update rate Hz / 100 kHz / 5 filter (Butterw e accuracy. than or equal to h rr (P), apparen), frequency (1 (Upk), current of range	through the zero-cross through the zero-cross through the zero-cross through the zero-cross through the zero-cross	Ω ±50 kΩ 0 - f) V 0 V synchroniz ero-cross fil on the numb ics equivale t frequency. eactive pow), loss (Los legration (I		
Crest factor Input resistance 50 Hz / 60 Hz) Aaximum input volt Aaximum rated volta b earth Aeasurement metho Sampling Frequency band Synchronization sou Data update rate PF Polarity detection oltage	3 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ however, 300 (relativ Probe 1 Probe 1 Probe 2 Voltage Voltage Voltage CATIII 6 CATIII 6 CATII	e to voltage/c 1.33 for 150 tive to minimi 133 for 1500 inputs inputs inputs inputs inputs mut terminal 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 00V; anticipat 100V; anticipat 1100V; anticipat 1200V; anticipat 120	MW (dependin urrent range, 1.5 fc 2 V range, 1.5 fc 4 MΩ ±40 kΩ 1 MΩ ±50 kΩ 1000 V, ±2000 0 1000 V, ±2000 0 1000 V, ±2000 0 1000 V, ±2000 0 5 V, ±12 Vpeak 8 V, ±15 Vpeak (50 Hz/60 Hz) ed transient ove ted tra	g on voltage a ting); or 5 V Probe 2 in Probe 2 in Vpeak (10 ms of uency of 250 kH (10 ms or less) (10 ms or less) (10 ms or less) (10 ms or less) ervoltage: 6000 ervoltage: 6000 ervoltage: 6000 il sampling wi bodate rate), a after passing ction. ta update rate Hz / 100 kHz / f a filter (Butterwi e accuracy. than or equal to a rr (P), apparen (Upk), current of range blayed even wh	range pput); range r less) z to 1 MHz, (125 Hz to 5 MHz, 5 W W W W W W W W W W W W W	Ω ±50 kΩ 0 - f) V 0 V synchronize ero-cross filt on the numb ics equivale t frequency. sactive pow), loss (Los egration (II ero input.		

	of 0 V, afte Within the	effective measurement ran	ige			
		Voltage (U)	Current (I)			
DC		±0.02% rdg. ±0.03%	-			
0.1 Hz ≤ f < 30 Hz		±0.1% rdg. ±0.2% f				
30 Hz ≤ f		±0.03% rdg. ±0.05%				
$45 \text{ Hz} \le f \le 66 \text{ Hz}$ $66 \text{ Hz} < f \le 1 \text{ kHz}$ $1 \text{ kHz} < f \le 50 \text{ kHz}$ $50 \text{ kHz} < f \le 100 \text{ kHz}$		±0.02% rdg. ±0.02%				
		±0.03% rdg. ±0.04% ±0.1% rdg. ±0.05%				
		-	-			
100 kHz < f		±0.01×f% rdg. ±0.2% ±0.008×f% rdg. ±0.5%				
500 kHz < 1		±(0.021×f-7)% rdg. ±1	-			
Frequence		2 MHz (-3 dB, typic				
	J) Bana					
		Active power (P)				
DC		±0.02% rdg. ±0.05%				
0.1 Hz ≤ f		±0.1% rdg. ±0.2% f				
30 Hz ≤ f		±0.03% rdg. ±0.05%				
45 Hz ≤ f		±0.02% rdg. ±0.03%				
66 Hz < f		±0.04% rdg. ±0.05%				
1 kHz < f s		±0.15% rdg. ±0.1%				
10 kHz < f		±0.15% rdg. ±0.1%				
50 kHz < f s		±0.012×f% rdg. ±0.29				
100 kHz < f		±0.009×f% rdg. ±0.59				
500 kHz < 1		±(0.047×f-19)% rdg. ±2	2% f.s. ±(0.055×f)° nentioned in the table above: kHz			
	add ±0.2° - The accur Hz to 10 H - The accur 220 V fron - The accur 750 V for - The accur (22000/f [] - Add ±0.02 are referen Even for ir until the i - For voltag difference - 500 Hz - 5 kHz < f	% rdgid.2% fs. for curren to the phase at or above 10 acy figures for voltage, curre z are reference values. acy figures for voltage, activ 10 Hz to 16 Hz are referen acy figures for voltage, activ values of f such that 30 kHz acy figures for voltage, activ values of such that 30 kHz (Hz) V for values of 1 such t % rdg. for voltage and activ roce values).	ant, active power, and phase difference for 0.1 re power, and phase difference in excess of ce values. re power, and phase difference in excess of < ≤ 100 kHz are reference values. re power, and phase difference in excess of hat 100 kHz <f <1="" are="" mhz="" reference="" values<br="">e power at or above 1000 V (however, figures han 1000 V, the effect will persist falls.</f>			
	Measure					
	Apparent		racy + current accuracy ±10 dgt.			
	Reactive		ver accuracy +			
	Power fa	ctor φ of other that	$ \begin{array}{l} \overset{\text{r4}}{} xf \pm 1.0022 - \lambda^2 - \sqrt{1 - \lambda^2}) \times 100\% \text{ f.s.} \\ \text{an } \pm 90^\circ; \\ \hline \\ \underline{\text{phase difference accuracy}} \\ \hline \\ \hline \\ cos(\varphi) \end{array} \right) \times 100\% \text{rdg.} \pm 50 \text{dg} \\ \end{array} $			
	Waveforr	±cos (φ + pha n peak Voltage/curre	use difference accuracy) × 100% f.s. ±50 dgt. ent RMS accuracy ±1% f.s. 00% of range)			
		Display value for voltage/ value for power factor				
Effects of temperatu and humidity	Add the following to the voltage, current, and active power accuracy within range of 0°C to 20°C or 26°C to 40°C: ±0.01% dg./°C dd0.01% f.s./°C for DC measured values) For current and active power when using Probe 2, ±0.02% dg./°C (add 0.0 f.s./°C for DC measured values) Under conditions of 60% RH or greater: Add ±0.0006 k humidty (%RH) x [kH2]% rdg. to the voltage and active power accur Add ±0.0006 k humidty 1% [kH2] v for the phase difference.					
Effects of common- mode voltage	100 kHz : Defined for	inputterminals and the 80 dB or greater (refer				
Effects of external magnetic fields	±1% f.s. or	less (in a magnetic field of	400 A/m, DC or 50 Hz/ 60 Hz)			

Frequency measurement

Number of measurement channels Max. 6 channels (f1 to f6), based on the number of input channels					
Measurement source	Select from U/I for each connection.				
Measurement method	Reciprocal method + zero-cross sampling value correction Calculated from the zero-cross point of waveforms after application of the zero- cross filter.				
Measurement range	0.1 Hz to 2 MHz (Display shows 0.00000 Hz or Hz if measurement is not possible.)				
Accuracy	±0.01Hz (Only when measuring 45-66 Hz with a minimum measurement interval of 50 ms and sine input of at least 50% relative to the voltage range when measuring the voltage frequency.) ±0.05% rdg ± 1 dgt. (other than the conditions mentioned above, when the sine wave is at least 30% relative to the measurement source's measurement range)				
Display format	0.10000 Hz to 9.99999 Hz, 9.9000 Hz to 99.9999 Hz, 99.000 Hz to 999.999 Hz, 0.99000 KHz to 9.99999 KHz, 9.9000 KHz to 99.9998 Hz, 99.000 KHz to 999.999 KHz, 0.99000 MHz to 2.00000 MHz				

Integration measurement

Select RMS or DC for each connection (DC mode can only be selected when using an AC/DC sensor with a 1P2W connection).					
Current integration (Ih+, Ih-, Ih), active power integration (WP+, WP-, WP) Ih+ and Ih- are measured only in DC mode. Only Ih is measured in RMS mode.					
Digital calculation based on current and active power values					
DC mode Every sampling interval, current values and instantaneous power values are integrated separately for each polarity.					
RMS mode The current RMS value and active power value are integrated for each measurement interval. Only active power is integrated separately for each polarity.					
999999 (6 digits + decimal point), starting from the resolution at which 1% of each range is f.s.					
0 to ±9999.99 TAh/TWh					
10 sec. to 9999 hr. 59 min. 59 sec.					
±0.02% rdg. (0°C to 40°C)					
±(current or active power accuracy) ±integration time accuracy					
None					

Harmonics measurement

Number of measurement channels	Max. 6 channels, based on the number of built-in channels
Synchronization source	Based on the synchronization source setting for each connection.
Measurement modes	Select from IEC standard mode or wideband mode (setting applies to all channels).
Measurement parameters	Harmonic voltage RMS value, harmonic voltage content ratio, harmonic voltage phase angle, harmonic current RMS value, harmonic current content ratio, harmonic current phase angle, harmonic active power, harmonic power content ratio, harmonic voltage/current phase difference, total voltage harmonic distortion, total current harmonic distortion, voltage unbalance ratio, current unbalance ratio
FFT processing word length	32 bits
Antialiasing	Digital filter (automatically configured based on synchronization frequency)
Window function	Rectangular
Grouping	OFF / Type 1 (harmonic sub-group) / Type 2 (harmonic group)
THD calculation	THD_F / THD_R (Setting applies to all connections.) Select calculation order from 2nd order to 100th order

method from 2nd order to 100th order (however, limited to the maximum analysis order for each mode). (1) IEC standard mode Zero-cross synchronization calculation method (same window for each

Measurement method		synchronization source) Fixed sampling interpolation calculation method with average thinning in window IEC 61000-47:2002 compliant with gap overlap						
Synchronization frequency range		45 Hz to	45 Hz to 66 Hz					
Data update	e rate	Fixed at 2	200 ms.					
Analysis or	ders	0th to 50t	h					
Window way	ve number	When les	s than 56 Hz, 10 waves; whe	n 56 Hz or greater, 12 wa	ves			
Number of F	FT points	4096 poir	nts					
	Freque	ency	Harmonic voltage and current	Harmonic power	Phase difference			
	DC (0th	order)	±0.1% rdg. ±0.1% f.s.	±0.1% rdg. ±0.2% f.s.				
	45 Hz ≤ f	≤ 66 Hz	±0.2% rdg. ±0.04% f.s.	±0.4% rdg. ±0.05% f.s.	±0.08°			
Accuracy	66 Hz < f ≤	≤ 440 Hz	±0.5% rdg. ±0.05% f.s.	±1.0% rdg. ±0.05% f.s.	±0.08°			
440 Hz < f		≤1 kHz	±0.8% rdg. ±0.05% f.s.	±1.5% rdg. ±0.05% f.s.	±0.4°			
	1 kHz < f ≤ 2.5 kHz		±2.4% rdg. ±0.05% f.s.	±4% rdg. ±0.05% f.s.	±0.4°			
	2.5 kHz < f	≤ 3.3 kHz	±6% rdg. ±0.05% f.s.	±10% rdg. ±0.05% f.s.	±0.8°			
		Power is Accuracy than or ea Add the o power, ar Add ±0.0 figures ar Even for	in accuracy calculations as m defined for a power factor of specifications are defined f qual to 50% of the range. urrent sensor accuracy to the d phase difference. 12% rdg, for voltage and act ie reference values). input voltages that are less t stance temperature falls.	1. for fundamental wave in e above accuracy figures tive power at or above	put that is greater for current, active 1000 V (however,			

(2) Wideband mode

		Zero-cross synchronization calculation method (same window for each					
Measure	ment method		nization source) with ampling interpolatior		ion method		
Synchror frequenc		0.1 Hz t	o 300 kHz				
Data upd		Fixed a	t 50 ms.				
			Frequency	Windo	w wave number	Maxim	um analysis order
		0.	1 Hz ≤ f < 80 Hz		1		100th
		80	Hz ≤ f < 160 Hz		2		100th
		16	0 Hz ≤ f < 320 Hz		4		60th
		32	0 Hz ≤ f < 640 Hz		2		60th
order and	n analysis	64	40 Hz ≤ f < 6 kHz		4		50th
	a wave number	6	kHz ≤ f < 12 kHz		2		50th
window	wave number	12	kHz ≤ f < 25 kHz		4	ĺ	50th
		25	kHz ≤ f < 50 kHz		8		30th
		50	kHz ≤ f < 101 kHz		16		15th
		101	kHz ≤ f < 201 kHz		32		7th
		201	kHz ≤ f ≤ 300 kHz		64		5th
Accuracy		(P), and	following to the acc phase difference. (I	<u>Jnit for f i</u>	n following table:	kHz)	().
	Frequer	icy	Harmonic voltage and current		Harmonic pow	er F	hase difference
	DC		±0.1% f.s.		±0.2% f.s.		-
	0.1 Hz ≤ f <		±0.05% f.s.		±0.05% f.s.		±0.1°
	30 Hz ≤ f <		±0.1% f.s.		±0.2% f.s.		±0.1°
	45 Hz ≤ f ≤		±0.05% f.s.		±0.1% f.s.		±0.1°
	$66 \text{ Hz} < f \le 1 \text{ kHz}$ $1 \text{ kHz} < f \le 10 \text{ kHz}$ $10 \text{ kHz} < f \le 50 \text{ kHz}$		±0.05% f.s.		±0.1% f.s.		±0.1°
			±0.05% f.s.		±0.1% f.s.		±0.6°
			±0.2% f.s.		±0.4% f.s.		(0.020×f)° ±0.5°
	50 kHz < f ≤ 100 kHz		±0.4% f.s.		±0.5% f.s.		±(0.020×f)° ±1°
100 kHz < f ≤ 500 kHz 500 kHz < f ≤ 900 kHz				±2% f.s.		=(0.030×f)° ±1.5°	
	500 kHz < f ≤) kHz $\pm 4\%$ f.s. $\pm 5\%$ f.s. $\pm (0.030 \times f)^{\circ} \pm 2^{\circ}$ nit for f in accuracy calculations as mentioned in the table above: kHz					
			ures for voltage, cu				
						nerence	tor frequencies in
		excess of 300 kHz are reference values. When the fundamental wave is outside the range of 16 Hz to 850 Hz, the figures					
		for voltage, current, power, and phase difference for frequencies other than the					
		fundamental wave are reference values.					
		When	the fundamental way	e is with	in the range of 16	6 Hz to 8	50 Hz, the figures
		for vol	tage, current, pow	er, and	phase difference	e in exc	ess of 6 kHz are

reference values. Accuracy values for phase difference are defined for input for which the voltage and current for the same order are at least 10% f.s.

Waveform recording

Number of	Voltage and current waveforms Max. 6 channels					
measurement channels	Motor waveforms * (based on the number of installed channel Max. 2 analog DC channels + max. 4 pulse chan					
Recording capacity	1 Mword × ((voltage + current) × max. 6 channels + motor waveforms) Fixed to 1 Mword when the number of channels is low. Motor waveforms: Motor analysis and D/A-equipped models only No memory allocation function					
Waveform resolution	16 bits (Voltage and current waveforms use the upper 16 bits of the 18-bit A/D.)					
Sampling speed	Voltage and current waveforms Always 5 MS/s Motor waveforms * Always 50 kS/s (analog DC) Motor pulse * Always 5 MS/s					
Compression ratio	1/1, 1/2, 1/5, 1/10, 1/20, 1/50, 1/100, 1/200, 1/500 (5 MS/s, 2.5 MS/s, 1 MS/s, 500 kS/s, 250 kS/s, 100 kS/s, 50 kS/s, 25 kS/s, 10 kS/s) However, motor waveforms* are only compressed at 50 kS/s or less.					
Recording length	1 kWord / 5 kWord / 10 kWord / 50 kWord / 100 kWord / 500 kWord / 1 Mword					
Storage mode	Peak-to-peak compression or simple thinning					
Trigger mode	SINGLE or NORMAL (with forcible trigger setting) When FFT analysis is enabled in NORMAL mode, the instrument enters trigger standby and waits for FFT calculations to complete.					
Pre-trigger	0% to 100% of the recording length, in 10% steps					
Trigger source	Voltage and current waveform, waveform after voltage and current zero-cross filter, manual, motor waveform*, motor pulse*					
Trigger slope	Rising edge, falling edge					
Trigger level	±300% of the range for the waveform, in 0.1% steps Level trigger / Event trigger					
Trigger detection method	Detects the trigger based on fluctuations in the level of the storage waveform Trigger source: Voltage and current waveform, waveform after voltage and current waveform, moto pulse (motor waveform and motor pulse: Motor analysis an DIA-equipped models only) Trigger slope: Hsing edge, falling edge Trigger level: ±300% of the range for the waveform, in 0.1% steps (2) Event trigger Detects the trigger based on fluctuations in the value of the measuremen parameter selected for D/A output. Specifically, trigger detection conditions are set using OR and ANI operation has precedence over the OR perator. Event: These condition definitions consist of a D/A outpu measurement parameter (D/A13 to D/A20), an inequality sign (c or >), and a value (0.00000 to 999997). EVent: These condition XXXXXX y (m: 1 to 4, n: 13 to 20, C): Inequality sign, x.XXXXX: 6-digi constant, y: SI prefix)					
FFT analysi	*Motor waveform and motor pulse: Motor Analysis and D/A-equipped models onl S Voltage-Current Waveform - 1 channel (selected from input channels) Motor Waveform - Analog DC Analysis performed only when FFT screen is displayed					
Calculation type	RMS spectrum					
Number of FFT points	1,000, 5,000, 10,000 or 50,000 points					
FFT processing word length	32 bits					
Analysis position	Any desired position among the waveform record data					
Antialiasing	Automatic Digital Filter (during simple thinning mode) None (During Peak-Peak compression mode, use the Max value and perform FFT)					
Window function	Rectangular/Hanning/Flat-top					
Max. analysis frequency	Linked with compression ratio of waveform records. 2 MHz, 1 MHz, 400 kHz, 200 kHz, 100 kHz, 40 kHz, 20 kHz, 10 kHz or 4 kHz / 20 kHz, 10 kHz, or 4kHz during analog DC input (Mentioned above frequency - frequency resolution) becomes the maximum analysis frequency					
FFT peak value display	Compute 10 frequencies and voltage-current peak value levels (local maximum value each starting from the top, ordered by level / For FFT calculation results, recognize a the peak value when the data on both sides is lower than the original data					
Motor Analy	/SIS (PW6001-11 to -16 only)					
	4 channels: CH A Analog DC input / Frequency input / Pulse input					

Number of input channels	4 channels: CH A Analog DC input / Frequency input / Pulse input CH B Analog DC input / Frequency input / Pulse input CH C Pulse input					
channels	CH D Pulse input					
Operating mode	Single, dual, or independent input					
Input terminal profile	Isolated BNC connectors					
Input resistance (DC)	1 MΩ ±50 kΩ					
Input method	Function-isolated input and single-end input					
Measurement parameters	Voltage, torque, rpm, frequency, slip, motor power					
Maximum input voltage	±20 V (analog DC and pulse operation)					
Additional conditions for guaranteed accuracy	Input: Terminal-to-ground voltage of 0 V, after zero-adjustment					
(1) Analog DC inpu	ut (CH A/CH B)					
Measurement range	±1 V / ±5 V / ±10 V					
Effective input range	1% to 110% f.s.					
Sampling	50 kHz, 16 bits					
Response speed	0.2 ms (when LPF is OFF)					
Measurement method	Simultaneous digital sampling, zero-cross synchronization calculation method (averaging between zero-crosses)					
Measurement accuracy	±0.05% rdg. ±0.05% f.s.					
Temperature coefficient	±0.03% f.s./°C					
Effects of common-	±0.01% f.s. or less with 50 V applied between the input terminals and the enclosure					
mode voltage	(DC / 50 Hz / 60 Hz)					
LPF	OFF (20 kHz) / ON (1 kHz)					
Display range	From the range's zero-suppression range setting to ±150%					
Zero-adjustment	Voltage ±10% f.s., zero-correction of input offsets that are less					
(2) Frequency input	(CH A/CH B)					
Detection level	Low: 0.5 V or less; high: 2.0 V or more					
Measurement frequency band	0.1 Hz to 1 MHz (at 50% duty ratio)					
Minimum detection width	0.5 µs or more					
Measurement accuracy	±0.05% rdg. ±3 dgt.					
Display range	1.000 kHz to 500.000 kHz					
(3) Pulse input (CH	A / CH B / CH C / CH D)					
Detection level	Low: 0.5 V or less; high: 2.0 V or more					
Measurement frequency band	0.1 Hz to 1 MHz (at 50% duty ratio)					
Minimum detection width	0.5 µs or more					
Pulse filter	OFF / Weak / Strong (When using the weak setting, positive and negative pulses of less than 0.5 μ s are ignored. When using the strong setting, positive and negative pulses of 5 μ s are ignored.)					
Measurement accuracy	±0.05% rdg. ±3 dgt.					
Display range	0.1 Hz to 800.000 kHz					
Unit	Hz / r/min.					
Frequency division						
setting range	1~60000					
Rotation direction detection	Can be set in single mode (detected based on lead/lag of CH B and CH C).					
Mechanical angle origin detection	Can be set in single mode (CH B frequency division cleared at CH D rising edge).					

D/A output (PW6001-11 to -16 only)

Number of output channels	20 channels				
Output terminal profile	D-sub 25-pin connector × 1				
Output details	Switchable between waveform output and analog output (select from basic measurement parameters). Waveform output is fixed to CH1 to CH12.				
D/A conversion resolution	16 bits (polarity + 1	15 bits)			
Output refresh rate	Analog output Waveform output	10 ms / 50 ms / 200 ms (based on data update rate for the selected parameter) 1 MHz			
Output voltage	Analog output Waveform output	±5 V DC f.s. (max. approx. ±12 V DC) Switchable between ±2 V f.s. and ±1 V f.s., crest factor of 2.5 or greater. Setting applies to all channels.			
Output resistance	100 Ω ±5 Ω				
Output accuracy	Analog output Waveform output	Output measurement parameter measurement accuracy ±0.2% f.s. (DC level) Measurement accuracy ±0.5% f.s. (at ±2 V f.s.)			
		or ±1.0% f.s. (at ±1 V f.s.) (RMS value level, up to 50 kHz)			
Temperature coefficient	±0.05% f.s./°C				

Display section

Display characters	English, Japanese	, Chinese (simplified)			
Display	9" WVGA TFT color LCD (800 × 480 dots) with an LED backlight and analog resistive touch panel				
Display value resolution	999999 count (incl	uding integration values)			
Display refresh rate	Measured values Waveforms	Approx. 200 ms (independent of internal data update rate) When using simple averaging, the data update rate varies based on the number of averaging iterations. Based on display settings			

External interface

(1) USB flash drive					
Connector	USB Type A connector x 1				
Electrical specifications	USB 2.0 (high-speed)				
Power supplied	Max. 500 mA				
Supported USB flash drives	USB Mass Storage Class compatible				
	- Save/load settings files				
Recorded data	- Save measured values/automatic recorded data (CSV format)				
	 Copy measured values/recorded data (from internal memory) Save waveform data, save screenshots (compressed BMP format) 				
(2) LAN interface					
Connector	RJ-45 connector x 1				
Electrical specifications	IEEE 802.3 compliant				
Transmission method	10Base-T / 100Base-TX / 1000Base-T (automatic detection)				
Protocol	TCP/IP (with DHCP function)				
	HTTP server (remote operations)				
Functions	Dedicated port (data transferring, command control)				
	FTP server (file transferring)				
(3) GP-IB interfac	e				
Communication	IEEE 488.1 1987 compliant developed with reference to IEEE 488.2 1987				
method	Interface functions: SH1, AH1, T6, L4, SR1, RL1, PP0, DC1, DT1, C0				
Addresses	00 to 30				
Functions	Command control				
(4) RS-232C inter	face				
Connector	D-sub 9-pin connector x 1, 9-pin power supply compatible, also used for external control				
Communication	RS-232C, EIA RS-232D, CCITT V.24, and JIS X5101 compliant				
method	Full duplex, start stop synchronization, data length of 8, no parity, 1 stop bit				
Flow control	Hardware flow control ON/OFF				
Communications speed	9,600 bps / 19,200 bps / 38,400 bps / 57,600 bps / 115,200 bps / 230,400 bps				
	Command control				
Functions	LR8410 Link supported (dedicated connector is required)				
	Used through exclusive switching with external control interface				
(5) External control	ol interface				
Connector	D-sub 9-pin connector × 1, 9-pin power supply compatible, also used for RS-232C				
Power supplied	OFF/ON (voltage of +5 V, max. 200 mA)				
Electrical specifications	0/5 V (2.5 V to 5 V) logic signals or contact signal with terminal shorted or open				
	Same operation as the [START/STOP] key or the [DATA RESET] key on the				
Functions	control panel				
	Used through exclusive switching with RS-232C				
(6) Two-instrumer	nt synchronization interface				
Connector	SFP optical transceiver, Duplex-LC (2-wire LC)				
Optical signal	850 nm VCSEL, 1 Gbps				
Laser class	Class 1				
	50/125 µm multi-mode fiber equivalent, up to 500 m				
Fiber used	Sories primitium-indee here equivalent, up to sour in Sends data from the connected secondary instrument to the primary instrumen which performs calculations and displays the results.				

Auto-range function

Operating mode OFF/ON (selectable for each connection) Broad/narrow (applies to all channels) Broad/narrow (applies to all channels) Broad The range is increased by one if the peak value is exceeded for the connection or if there is an RMS value that is greater than or equal to 110% f.s. The range is increased by one if the peak value is exceeded for the connection or if there is an RMS values for the connection are less than or equal to 10% f.s. The range is increased by one if the peak value is exceeded for the connection or if there is an RMS value that is greater than or equal to 10% f.s. The range is lowered by one if all RMS values for the connection are less than or equal to 10% f.s. Voltage range changes when Δ-Y conversion is enabled are determined by multiplying the range by $\left[\frac{1}{4\pi}\right]$	Functions	The voltage and current ranges for each connection are automatically changed in response to the input.
Auto-range breadth Broad The range is increased by one if the peak value is exceeded for the connection or if there is an RMS value that is greater than or equal to 10% f.s Auto-range breadth Narrow The range is lowered by two if all RMS values for the connection are less than or equal to 10% f.s Narrow The range is increased by one if the peak value is exceeded for the connection or if there is an RMS value that is greater than or equal to 10% f.s The range is lowered by one if all RMS values for the connection are less than or equal to 40% f.s Voltage range changes when Δ-Y conversion is enabled are determined	Operating mode	OFF/ON (selectable for each connection)
10	Auto-range breadth	Broad The range is increased by one if the peak value is exceeded for the connection or if there is an RMS value that is greater than or equal to 110% f.s. The range is lowered by two if all RMS values for the connection are less than or equal to 10% f.s. Narrow The range is lowered by one if the peak value is exceeded for the connection or if there is an RMS value that is greater than or equal to 15% f.s. The range is lowered by one if all RMS values for the connection are less than or equal to 10% f.s. The range is lowered by one if all RMS values for the connection are less than or equal to 40% f.s. Voltage range changes when Δ-Y conversion is enabled are determined

Time control function

Timer control	OFF, 10 sec. to 9999 hr. 59 min. 59 sec. (in 1 sec. steps)				
Actual time control	OFF, start time/stop time (in 1 min. steps)				
Intervals	OFF / 10 ms / 50 ms / 200 ms / 500 ms / 1 sec. / 5 sec. / 10 sec. / 15 sec. / 30 sec. 1 min. / 5 min. / 10 min. / 15 min. / 30 min. / 60 min.				
Hold function	on				
	Stops updating the display with all measured values and holds the value				

currently being displayed. Used exclusively with the peak hold function.
Updates the measured value display each time a new maximum value is set. Used exclusively with the hold function.

Calculation function

Functions	Selects the voltage and current values used to calculate apparent and reactive power and power factor.										
Operating mode	RMS/mean (Ca		cted for eac	h connectio	n's voltaç	e and curi	rent.)				
2) Scaling											
VT (PT) ratio CT ratio	OFF/ 0.00001 to OFF/ 0.01 to 99										
3) Averaging (AV											
Functions	All instantaneo	us measui	red values,	including ha	irmonics,	are avera	ged.				
Operating mode	OFF / Simple av Simple averaging					a numb	er of simpl				
	Simple averagi	a	veraging ite	rations for			ycle, and th				
Onenting		Т	utput data is he data up	date rate i	s lengthe	ened by th	ie number o				
Operation	Exponential ave	eraging D	veraging ite ata is expo	onentially a	veraged	using a ti	me constar				
		a	veraging re	sponse rate			exponentia				
	During averaging Number of a					1					
Number of simple	iteratio		5 50 ms	10 100 ms	20 200 ms	50 500 ms	100 1 sec.				
averaging iterations	Data update rate	50 ms	250 ms	500 ms	1 sec.	2.5 sec.	5 sec.				
		200 ms	1 sec.	2 sec.	4 sec.	10 sec.	20 sec.				
		Setting	10 ms	FAST 0.1 sec.		ID sec.	SLOW 5 sec.				
Exponential averaging response rate	Data update rat	e	50 ms 200 ms	0.5 sec. 2.0 sec.		sec.	25 sec. 100 sec.				
	These values in	ndicate the	e time requi	ed for the f	nal stabi						
	on ±1% when th	ne input ch	anges from	0% f.s. to 9	90% f.s.						
4) User-defined c											
Functions	User-specified specified calcul	d basic n lation form	neasureme nulas.	nt parame	ters are	calculate	ed using th				
	Four basic mea are four-arithme	asured iter etic operat	ms or const tors.	ants with a	maximu	m of 6-dig	its; operator				
	UDFn = ITEM1 ITEMn : basic n	ITEM2	ITEM3 🗆 I	EM4 stant of up	to 6 digits						
Calculated items	□ : any one of + UDFn can also I	, -, *, or /					the order of .				
Calculated items	The functions t	hat can be	e selected a	ind calculat	ed in reg	ards to ea	ch ITEMn ar				
	as follows: neg, exp, asin, acos,	atan, sinh	i, cosh, tanh	1							
	When a UDFn calculated value	es are use	d	1 the curren	IT ODF IS	encounte	a, previous				
Number of allowed calculations Maximum value setting	16 formulas (UI Set for each UI) u to 100.0	T / Funct	ions as a l	JDFn range				
Unit	Up to 6 charact				171 dilo	ionio do d	obriniango				
5) Efficiency and	loss calcula	tions									
Calculated items	Active power va										
Number of calculations	(Motor Analysis Four each for e			dels offiy) ic	each ch	anneranu	connection				
that can be performed		-		(a) and Da		- 6-11	(
Formula	Calculated items are specified for Pin(n) and Pout(n) in the following format: Pin = Pin1 + Pin2 + Pin3 + Pin4, Pout = Pout1 + Pout2 + Pout3 + Pout4 $\eta = 100 \times \frac{ Pout }{ Pin }$, Loss = Pin - Pout										
(6) Power formula	selection										
Functions			er, power fa	ctor, and po	wer phas	e angle fo	rmulas.				
		mpatible v	with TYPE1	Selects the reactive power, power factor, and power phase angle formulas. TYPE1 / TYPE2 / TYPE3 TYPE1 Compatible with TYPE1 as used by the Hioki 3193 and 3390.							
-	TYPE2 Compatible with TYPE2 as used by the Hioki 3192 and 3193. TYPE3 The sign of the TYPE1 power factor and power phase angle are										
Formula	TYPE3 Th	e sign of	the TYPE1	as used by power fac	the Hioki	3192 and ower pha	3193.				
	TYPE3 Th use	e sign of	vith TYPE2 the TYPE1 active powe	as used by power fac	the Hioki	3192 and ower pha	3193.				
	TYPE3 Thuse	e sign of ed as the a	the TYPE1 active powe	as used by power fac r signs.	the Hioki tor and p	ower pha	3193. se angle ar				
Formula (7) Delta conversi	TYPE3 Th use ON Δ-Y When u wavefor	e sign of ed as the a using a 3P m to a pha	the TYPE1 active powe 23W3M or 3 ase voltage	as used by power fac r signs. W3A conne waveform u	the Hioki tor and p ection, co sing a vir	ower pha	3193. se angle ar e line voltag al point.				
(7) Delta conversi	TYPE3 Th use ON Δ-Y When u wavefor Y-Δ When u a line vo	e sign of ed as the a using a 3P m to a pha sing a 3P4 oltage way	the TYPE1 active powe 33W3M or 3 ase voltage W connect reform.	as used by power fac r signs. W3A conne waveform u ion, convert	the Hioki tor and p ection, cc sing a vii s the pha	oower pha nverts the tual neutra	3193. se angle ar e line voltag al point. e waveform t				
(7) Delta conversi	TYPE3 Th use ON Δ-Y When u wavefor Y-Δ When u	e sign of ed as the a using a 3P m to a pha sing a 3P oltage wav values ar	the TYPE1 active powe 33W3M or 3 ase voltage W connect eform. ad all volta	as used by power fac r signs. W3A conne waveform u ion, convert ge parame	the Hioki tor and p ection, cc sing a vii s the pha	oower pha nverts the tual neutra	3193. se angle ar e line voltag al point. e waveform t				
(7) Delta conversi	TYPE3 Th ON Δ-Y When u VA When u a line vc Voltage RMS calculated usin	e sign of ed as the a using a 3P m to a pha sing a 3P4 oltage wav values ar g the post	the TYPE1 active powe 3W3M or 3 ase voltage W connect eform. ad all volta -conversior	as used by power fac r signs. W3A conne waveform u ion, convert ge parame	the Hioki tor and p ection, cc sing a vii s the pha	oower pha nverts the tual neutra	3193. se angle ar e line voltag al point. e waveform t				
	TYPE3 Th ON Δ-Y When u VA When u a line vc Voltage RMS calculated usin	e sign of ed as the a using a 3F m to a pha sing a 3P ² oltage wav values ar g the post	the TYPE1 active powe 3W3M or 3 ase voltage WW connect eform. ad all volta -conversion ation	as used by power fac r signs. W3A conne waveform u ion, convert ge parame voltage.	the Hioki tor and p ection, co sing a vin s the pha ters, inc	nverts the tual neutra ise voltage luding ha	3193. se angle ar a line voltag al point. a waveform t rmonics, ar				
 (7) Delta conversi Functions (8) Current sensor Functions 	TYPE3 Th ON Δ-Y When u Δ-Y When u a line vc Voltage RMS ³ calculated usin r phase shift Compensates th Compensation Compensation	e sign of ed as the a sing a 3F m to a pha sing a 3P4 oltage wav values ar g the post t Calcula te current s points are	the TYPE1 active power 3W3M or 3 ase voltage W connect eform. d all volta conversion ation sensor's ham set using ti 0.1 kHz to 9	as used by power fac r signs. W3A conne waveform u ion, convert ge parame voltage. monic phase ne frequenc 9.9 s HHz (ir	the Hioki tor and p ection, cc sing a vius s the pha- ters, inc characte y and phi- o 0.1 kHz	noverts the tual neutra tual n	3193. se angle ar b line voltag al point. b waveform t rmonics, ar g calculations				
 (7) Delta conversi Functions (8) Current sensor Functions Compensation value 	TYPE3 Th ON Δ-Y When u wavefor Y-Δ When u a line vc Voltage RMS- calculated usin calculated usin r phase shift Compensation Frequency Phase diffe Phase diffe	e sign of ed as the e sing a 3F m to a pha sing a 3P oltage wav values ar g the post t Calcula te current s points are rence	the TYPE1 active power '3W3M or 3 ase voltage W connect eform. Id all volta -conversion ation set using ti 0.1 kHz to 9 0.10° to ±90	as used by power fac r signs. W3A conne waveform u ion, convert ge parame voltage. nonic phase ne frequence 99.9 kHz (in 0.0	the Hioki tor and p ection, cc sing a vir s the pha ters, inc characte y and pha 0.1 kHz 1° interva	nverts the tual neutra se voltage luding ha ristics using ase differe steps) ls)	3193. se angle ar line voltag al point. waveform t rmonics, ar g calculation: nce.				
 (7) Delta conversi Functions (8) Current sensor Functions Compensation value 	TYPE3 Th US ON Δ-Y When u wavefor Y-Δ When u a line vc Voltage RMS calculated usin r phase shift Compensates th Compensates th	e sign of ed as the e ising a 3P m to a phá sing a 3P values ar g the post t Calcula e current s points are rence	the TYPE1 active powe 3W3M or 3 ase voltage www.connect eform. d all volta -conversior ation eensor's harr set using th 0.1 kHz to 9 0.00° to ±90 in time calc	as used by power fac r signs. W3A conne waveform u ion, convert ge parame voltage. nonic phase ne frequence 99.9 kHz (in 0.0	the Hioki tor and p ection, cc sing a vir s the pha ters, inc characte y and pha 0.1 kHz 1° interva	nverts the tual neutra se voltage luding ha ristics using ase differe steps) ls)	3193. se angle ar line voltag al point. waveform t rmonics, ar g calculation: nce.				
7) Delta conversi Functions 8) Current sensor Functions Compensation value settings	TYPE3 Th use ON △-Y When u wavefor Y-Δ When u a line v Voltage RMS calculated usin r phase shift Compensation Frequency Phase diffe However, the d can be up to 98	e sign of ed as the e ising a 3P m to a phá sing a 3P values ar g the post t Calcula e current s points are rence	the TYPE1 active powe 3W3M or 3 ase voltage www.connect eform. d all volta -conversior ation eensor's harr set using th 0.1 kHz to 9 0.00° to ±90 in time calc	as used by power fac r signs. W3A conne waveform u ion, convert ge parame voltage. nonic phase ne frequence 99.9 kHz (in 0.0	the Hioki tor and p ection, cc sing a vir s the pha ters, inc characte y and pha 0.1 kHz 1° interva	nverts the tual neutra se voltage luding ha ristics using ase differe steps) ls)	3193. se angle ar line voltag al point. waveform t rmonics, ar g calculation: nce.				
 (7) Delta conversi Functions (8) Current sensor Functions Compensation value settings Display function 	TYPE3 Th use on △-Y When u wavefor Y-Δ When u a line v voltage RMS calculated usin r phase shift Compensates th Compensates th Co	e sign of ed as the a asing a 3F m to a pha- sing a 3P ² oltage wav values ar g the post t Calcula e current s points are rence ifference is μ s in 0.5r	the TYPE1 active powe 3W3M or 3 ase voltage www.connect eform. d all volta -conversior ation eensor's harr set using th 0.1 kHz to 9 0.00° to ±90 in time calc	as used by power fac r signs. W3A conne waveform u ion, convert ge parame voltage. nonic phase ne frequence 99.9 kHz (in 0.0	the Hioki tor and p ection, cc sing a vir s the pha ters, inc characte y and pha 0.1 kHz 1° interva	nverts the tual neutra se voltage luding ha ristics using ase differe steps) ls)	3193. se angle ar line voltag al point. waveform t rmonics, ar g calculation: nce.				
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7) Delta conversi Functions 8) Current sensol Functions Compensation value settings Display func 1) Connection co Functions Mode at startup	TYPE3 Th USE ON Δ-Y When u wavefor Y-Δ When u a line vc Voltage RMS calculated usin r phase shift Compensates th Compensates th C	e sign of ed as the e sing a 3F m to a pho- m to a pho- sing a 3P- oblige way values ar g the post t calcula e current si g on to so t calcula e current si points are points are rence of ifference creen creen creen to so creen to a correct of t o display setting).	the TYPEI active power 33W3M or 3 ase voltage W connect eform. Id all volta conversion ation mensor's han set using ti 0.00° to ±90 in time calc is intervals agram and v res. connection ecked.	as used by power fac r signs. IV3A conne waveform u ion, convert ge parame voltage. monic phase re frequenc 99.9 kHz (ir 0.00° (in 0.0 ulated from voltage and are displaye ction confirm	the Hioki tor and p oction, cc sing a vii s the pha ters, inc characte y and pha o.1 kHz 1° interve the freq current v ed on the nation sc	over pha inverts the tual neutri- use voltage luding ha ristics using ase differe steps) ls) uency pha ectors bas vector disj reen at sta	3193. se angle ar line voltagg al point. waveform t rmonics, ar g calculations nce. se difference ed on the play so that trup				
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Displays the voltage and current waveforms and motor waveform. All-waveform display, waveform + numerical display Cursor measurement supported

Functions Display patterns

Simplified Graph Function (1) D/A Monitor Graph

Functions	Graph measured values chosen as D/A output items in chronological order Illustrated waveforms are Peak-Peak compressed by setting time axis to data at data update rate, and data is not recorded.
Operations	Start and stop drawing with the RUN/STOP button Illustrate the displayed value during hold and peak hold Illustrated data is cleared when Clear button is pressed during changes in settings related to measured values of range and D/A output items
Number of illustrated items	Maximum of 8 items
Illustrated items	Operates simultaneously with D/A output items from CH13 to CH20 settings
Time axis	10 ms/dot to 48 min/dot (Cannot be selected below the data update rate)
Vertical axis	Autoscaling (operates to fit data on screen within screen display range with time axis) Manual (user sets displayed maximum value and minimum value)

(2) X-Y Plot

. ,	
	Select horizontal and vertical axis items from fundamental measurement items and display X-Y graph
	Dot illustrations are done at data update rate, and data is not recorded
Functions	Illustration data can be cleared / a total of two combinations of graphs can be displayed: X1-Y1 or X2-Y2
	Gauge display, displayed max value and min value settings are allowed
	X1, Y1, X2, and Y2 operate in synchronization with D/A output item settings for CH13, 14, 15, and 16 respectively

Automatic save function

Functions	Saves the specified measured values in effect for each interval.		
Save destination	OFF / Internal memory / USB flash drive		
Saved parameters	User-selected from all measured values, including harmonic measured values		
Maximum amount of saved data	Internal memory 64 MB (data for approx. 1800 measurements) USB flash drive Approx. 100 MB per file (automatically segmented) × 20 files		
Data format	CSV file format		

Manual save function (1) Measurement data

Functions	The [SAVE] key saves specified measured values at the time it is pressed. Comment text can be entered for each saved data point, up to a maximum of 20 alphanumeric characters. *The manual save function for measurement data cannot be used while automatic save is in progress.	
Save destination	USB flash drive	
Saved parameters	User-selected from all measured values, including harmonic measured values	
Data format	CSV file format	

(2) Waveform data

Functions	(Within touch panel) Use Save Waveforms Button to save waveform data during that session Input comments for each set of saved data "Cannot be operated when waveform data is invalid during storage and automatic saving	
Save destination	USB flash drive - Assign destinations for saved data	
Comment entry	OFF/ON - up to 40 letters/symbols	
Data format	CSV file format (read-only attribute included), binary file format (BIN format)	

(3) Screenshots

Functions	The [COPY] key saves a screenshot to the save destination. *This function can be used at an interval of 1 sec or more while automatic saving is in progress.	
Save destination	USB flash drive	
Comment entry	OFF / Text / Handwritten When set to [Text], up to 40 alphanumeric characters When set to [Handwritten], hand-drawn images are pasted to the screen.	
Data format	Compressed BMP	

(4) Settings data

Functions	Saves settings information to the save destination as a settings file via functionality provided on the File screen. In addition, previously saved settings files can be loaded and their settings restored on the File screen. However, language and communications settings are not saved.
Save destination USB flash drive	
(5) FFT data	
(Within touch panel) Use Save FFT Spectrum button to save wavefor	

Functions	Input comments for each set of saved data *Cannot be operated when waveform data is invalid during storage and automatic saving	
Save destination	SB flash drive - Assign destinations for saved data	
Comment entry	OFF/ON - up to 40 letters/symbols	
Data format	CSV file format (with read-only attribute set)	

Two-instrument synchronization function

Functions	Sends data from the connected secondary instrument to the primary instrument, which performs calculations and displays the results. In numerical synchronization mode, the primary instrument operates as a power meter with up to 12 channels. In waveform synchronization mode, the primary instrument operates while synchronizing up to three channels from the secondary instrument at the waveform level.		
Operating mode	OFF / Numerical synchronization / Waveform synchronization Numerical synchronization cannot be selected when the data update rate is 10 ms. Waveform synchronization operates only when primary device has more than 3 channels		
Synchronized items	,	Data update timing, start/stop/data reset Voltage/current sampling timing	
Synchronization delay	Numerical synchronization mode Waveform synchronization mode		
Transfer items	Numerical synchronization mode Waveform synchronization mode	Basic measurement parameters for up to six channels (including motor data) Voltage/current sampling waveforms for up to three channels (not including motor data). However, the maximum number of channels is limited to a total of six, including the	
		primary instrument's channels.	

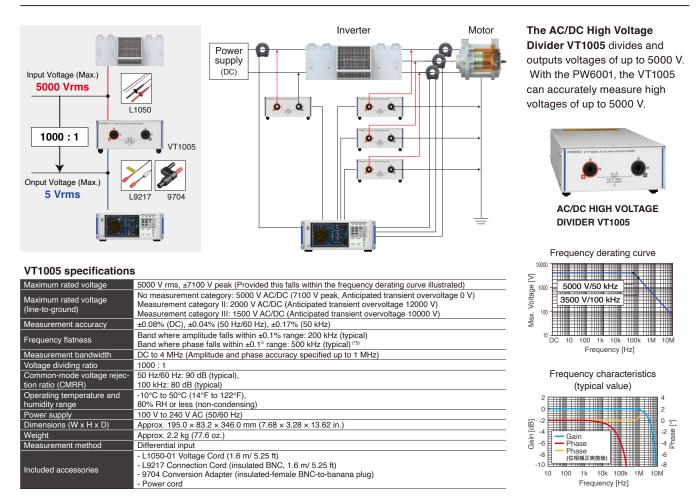
General Specifications

Operating environment	Indoors at an elevation of up to 2000 m in a Pollution Level 2 environment	
Storage temperature and humidity	-10°C to 50°C, 80% RH or less (no condensation)	
Operating temperature and humidity	0°C to 40°C, 80% RH or less (no condensation)	
Dielectric strength	50 Hz/60 Hz 5.4 kV rms AC for 1 min. (sensed current of 1 mA) Between voltage input terminals and instrument enclosure, and between current sensor input terminals and interfaces 1 kV rms AC for 1 min. (sensed current of 3 mA) Between motor input terminals (Ch. A, Ch. B, Ch. C, and Ch. D) and the instrument enclosure	
Standards	Safety EN61010 EMC EN61326 Class A	
Rated supply voltage	100 V AC to 240 V AC, 50 Hz/ 60 Hz	
Maximum rated power	200 VA	
External dimensions	Approx. 430 mm (16.93 in)W × 177 mm (6.97 in)H × 450 mm (17.72 in)D (excluding protruding parts)	
Mass	Approx. 14 kg (49.4 oz) (PW6001-16)	
Backup battery life	Approx. 10 years (reference value at 23°C) (lithium battery that stores time and setting conditions)	
Product warranty period	3 year	
Guaranteed accuracy period	6 months (1-year accuracy = 6-month accuracy × 1.5)	
Accuracy guarantee conditions	Accuracy guarantee temperature and humidity range: 23°C ±3°C, 80% RH or less Warm-up time: 30 min. or more	
Accessories	Instruction manual x 1, power cord x 1, D-sub 25-pin connector x 1 (PW6001-1x only)	

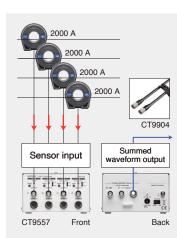
Other functions

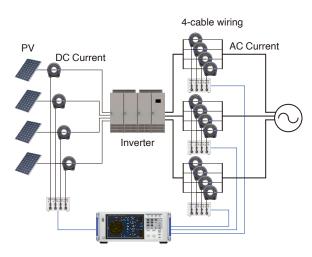
Clock function	Auto-calendar, automatic leap year detection, 24-hour clock	
Actual time accuracy	When the instrument is on, ±100 ppm; when the instrument is off, within ±3 sec./day (25°C)	
Sensor identification	Current sensors connected to Probe1 are automatically detected.	
Zero-adjustment function	After the AC/DC current sensor's DEMAG signal is sent, zero-correction of th voltage and current input offsets is performed.	
Touch screen correction	orrection Position calibration is performed for the touch screen.	
Key lock	While the key lock is engaged, the key lock icon is displayed on the screen.	

Measure High Voltages of up to 5000 V



Measure Large Currents of up to 8000 A





The Sensor Unit CT9557 adds and outputs current sensor output from multi-wire lines. With the PW6001, the CT9557 can be used to accurately measure large currents of up to 8000 A (on a 4-wire line).



SENSOR UNIT CT9557

CT9557 specifications

Connectable current sensor	Current sensors are lis	sted on p. 19 - p. 21.	
	DC	: ±0.06% ±0.03%	
	~ 1 kHz	: ±0.06% ±0.03%	
Summed waveform	~ 10 kHz	: ±0.10%. ±0.03%	
output accuracy ±(% of reading + % of full	~ 100 kHz	: ±0.20% ±0.10%	
scale)	~ 300 kHz	: ±1.0% ±0.20%	
000107	~ 700 kHz	: ±5.0% ±0.20%	
	~ 1 MHz	: ±10.0% ±0.50%	
Operating temperature and	-10°C to 50°C (14°F to 122°F),		
humidity	80% RH or less		
Power supply	100 V to 240 V AC (50	Hz/60 Hz)	
Output connector	HIOKI ME15W (male of	connector)	
Dimensions (W x H x D)	Approx. 116 mm W × 67 mm H × 132 mm D		
	(approx. 4.57 in. W × 2.64 in. H × 5.20 in. D)		
Weight	Approx. 420 g (14.8 oz.)		
Included accessories	AC ADAPTER Z1002, Power cord		

Wiring	Current	Using sensors	
Single-cable or bundled wiring	1000 A	CT6876A CT6846A	
	2000 A	CT6877A	
2-cable	2000 A	CT9557+CT6876A×2/ CT9557+CT6846A×2	
wiring	4000 A	CT9557+CT6877A×2	
3-cable	3000 A	CT9557+CT6876A×3/ CT9557+CT6846A×3	
wiring	6000 A	CT9557+CT6877A×3/	
4-cable	4000 A	CT9557+CT6876A×4/ CT9557+CT6846A×4	
wiring	8000 A	CT9557+CT6877A×4	



Option CONNECTION CABLE CT9904 Cable length: 1 m (3.28 ft) CT9904 required to connect to PW6001.

Current sensors High accuracy pass-through (connect to Probe1 input terminal)

Appearance			СТ6877А,	CT6877A-1*2	CT6876A,	CT6876A-1*2	CT6904A-2	CT6904A-2, CT6904A-3*2	
			NEW		NEW		NEW Wideband 4 MHz		
Rat	ed current		2000	A AC/DC	1000	A AC/DC	800 A	AC/DC	
Fre	quency ban	d	DC	to 1 MHz		DC to 1.5 MHz : DC to 1.2 MHz		: DC to 4 MHz : DC to 2 MHz	
Diar	meter of meas	surable conductors	Max. ф 80) mm (3.14 in.)	Мах. ф 36	6 mm (1.42 in.)	Мах. ф 32	mm (1.25 in.)	
		0	DC	:±0.06% ±0.038%	DC	: ±0.06% ±0.038%	DC	: ±0.050% ±0.037%	
F	PW6001	Current (I)	45 Hz ≤ f ≤ 66 Hz	:±0.06% ±0.028%	45 Hz ≤ f ≤ 66 Hz	: ±0.06% ±0.028%	45 Hz ≤ f ≤ 65 Hz	: ±0.045% ±0.027%	
0	Combined*1	A attive a survey (D)	DC	:±0.06% ±0.058%	DC	: ±0.06% ±0.058%	DC	: ±0.050% ±0.057%	
		Active power (P)	45 Hz ≤ f ≤ 66 Hz	:±0.06% ±0.038%	45 Hz ≤ f ≤ 66 Hz	: ±0.06% ±0.038%	45 Hz ≤ f ≤ 65 Hz	: ±0.045% ±0.037%	
			DC	: ±0.04% ±0.008%	DC	: ±0.04% ±0.008%	DC	: ±0.030% ±0.009%	
			DC < f < 16 Hz	: ±0.1% ±0.02%	DC < f < 16 Hz	: ±0.1% ±0.02%	DC < f < 16 Hz	: ±0.2% ±0.025%	
_			16 Hz ≤ f < 45 Hz	: ±0.05% ±0.01%	16 Hz ≤ f < 45 Hz	: ±0.05% ±0.01%	16 Hz ≤ f < 45 Hz	: ±0.1% ±0.025%	
ac	Sensor only (amplitude) ±(% of reading +% of full scale) full scale is rated current of sensor		45 Hz ≤ f ≤ 66 Hz	: ±0.04% ±0.008%	45 Hz ≤ f ≤ 66 Hz	: ±0.04% ±0.008%	45 Hz ≤ f ≤ 65 Hz	: ±0.025% ±0.009%	
Accuracy			66 Hz < f ≤ 100 Hz	: ±0.05% ±0.01%	66 Hz < f ≤ 100 Hz	: ±0.05% ±0.01%	65 Hz < f ≤ 850 Hz	: ±0.05% ±0.009%	
			100 Hz < f ≤ 500 Hz	: ±0.1% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.1% ±0.02%	850 Hz < f ≤ 1 kHz	: ±0.1% ±0.013%	
			500 Hz < f ≤ 1 kHz	: ±0.2% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.2% ±0.02%	1 kHz < f ≤ 5 kHz	: ±0.4% ±0.025%	
1			1 kHz < f ≤ 10 kHz	: ±0.5% ±0.02%	1 kHz < f ≤ 5 kHz	: ±0.5% ±0.02%	5 kHz < f ≤ 10 kHz	: ±0.4% ±0.025%	
			10 kHz < f ≤ 50 kHz	: ±1.5% ±0.05%	5 kHz < f ≤ 10 kHz	: ±0.5% ±0.02%	10 kHz < f ≤ 50 kHz	: ±1.0% ±0.025%	
			50 kHz < f ≤ 100 kHz	: ±2.5% ±0.05%	10 kHz < f ≤ 50 kHz	: ±2.0% ±0.05%	50 kHz < f ≤ 100 kHz	:±1.0% ±0.063%	
			100 kHz < f ≤ 700 kHz	: ±(0.025×f kHz)% ±0.05%	50 kHz < f ≤ 100 kHz	: ±3.0% ±0.05%	100 kHz < f ≤ 300 kHz	: ±2.0% ±0.063%	
				_	100 kHz < f ≤ 1 MHz	: ±(0.03×f kHz)% ±0.05%	300 kHz < f ≤ 1 MHz	: ±5.0% ±0.063%	
Ope	erating Temp	perature	-40°C to 85°0	C (-40°F to 185°F)	-40°C to 85°	C (-40°F to 185°F)	-10°C to 50°C	(-14°F to 122°F)	
Max	kimum rated	voltage to earth	CAT	III 1000 V	CAT	III 1000 V	CATI	I 1000 V	
Dim	nensions		229W (9.02") × 232H	(9.13") × 112D (4.41") mm	160W (6.30") × 112H	(4.41") × 50D (1.97") mm	139W (5.47") × 120H	4.72") × 52D (2.05") mm	
Dill	IEIISIOIIS			9.84 ft), CT6877A-1:10 m (32.81 ft)]		9.84 ft), CT6876A-1:10 m (32.81 ft)]			
Mas	SS			rox. 5 kg (176.4 oz.)		rox. 970 g (34.2 oz.)		rox. 1150 g (40.6 oz.)	
				ox. 5.3 kg (187.0 oz.)* ²		ox. 1300 g (45.9 oz.) *2		x. 1450 g (51.1 oz.) *2 uency derating	
Derating properties		rties	Frequency derating		Frequency detailing 10		Property of the second		

*1 ±(% of reading + % of range), range is PW6001 CT6877A/CT6877A-1: Add ±0.15% of the range for 40 A range; CT6876A/CT6876A-1: Add ±0.15% of the range for 20 A range; CT6904A-2/CT6904A-3: Add ±0.12% of the range for 20 A range or 40 A range; CT6877A-1, CT6877A-1, add CT6904A-3 have a 10 m cord. For the CT6876A-1, add ±(0.005 × f kHz)% of the reading for amplitude accuracy and ±(0.015 × f kHz)° for phase accuracy for frequencies of 1 kHz < f ≤ 1 MHz. For the CT6977A-1, add ±(0.005 × f kHz)% of the reading for amplitude accuracy and ±(0.015 × f kHz)° for phase accuracy for frequencies of 1 kHz < f ≤ 1 MHz. For the CT697A-1, add ±(0.005 × f kHz)% of the reading for amplitude accuracy and ±(0.015 × f kHz)° for phase accuracy for frequencies of 1 kHz < f ≤ 1 MHz.

		CT6904A,	CT6904A-1*4	CT6875A, CT6875A-1*4		СТ6873,	CT6873, CT6873-01*4	
A	opearance	NEW Wideband 4 MHz		NEW		NEW Wideband 10 MHz		
R	ated current	500	A AC/DC	500	A AC/DC	200	A AC/DC	
F	requency band		: DC to 4 MHz 1: DC to 2 MHz		: DC to 2 MHz : DC to 1.5 MHz	DC	to 10 MHz	
D	ameter of measurable conductors	Мах. ф 32	2 mm (1.25 in.)	Мах. ф 36	6 mm (1.42 in.)	Мах. ф 2	4 mm (0.94 in.)	
	Ourmant (I)	DC	: ±0.045% ±0.037%	DC	: ±0.06% ±0.038%	DC	: ±0.05% ±0.032%	
	Current (I) PW6001	45 Hz ≤ f ≤ 65 Hz	: ±0.04% ±0.027%	45 Hz ≤ f ≤ 66 Hz	: ±0.06% ±0.028%	45 Hz ≤ f ≤ 66 Hz	: ±0.05% ±0.027%	
	Combined*3	DC	: ±0.045% ±0.057%	DC	: ±0.06% ±0.058%	DC	: ±0.05% ±0.052%	
	Active power (P)	45 Hz ≤ f ≤ 65 Hz	: ±0.04% ±0.037%	45 Hz ≤ f ≤ 66 Hz	: ±0.06% ±0.038%	45 Hz ≤ f ≤ 66 Hz	: ±0.05% ±0.037%	
		DC	: ±0.025% ±0.007%	DC	: ±0.04% ±0.008%	DC	: ±0.03% ±0.002%	
		DC < f < 16 Hz	: ±0.2% ±0.02%	DC < f < 16 Hz	: ±0.1% ±0.02%	DC < f ≤ 16 Hz	: ±0.1% ±0.01%	
~		16 Hz ≤ f < 45 Hz	: ±0.1% ±0.02%	16 Hz ≤ f < 45 Hz	: ±0.05% ±0.01%	16 Hz < f ≤ 45 Hz	: ±0.05% ±0.01%	
racy	Sensor only (amplitude) ±(% of reading +% of full scale) full scale is rated current of sensor	45 Hz ≤ f ≤ 65 Hz	: ±0.02% ±0.007%	45 Hz ≤ f ≤ 66 Hz	: ±0.04% ±0.008%	45 Hz < f ≤ 66 Hz	: ±0.03% ±0.007%	
Accuracy		65 Hz < f ≤ 850 Hz	: ±0.05% ±0.007%	66 Hz < f ≤ 100 Hz	: ±0.05% ±0.01%	66 Hz < f ≤ 100 Hz	: ±0.04% ±0.01%	
Ă		850 Hz < f ≤ 1 kHz	: ±0.1% ±0.01%	100 Hz < f ≤ 500 Hz	: ±0.1% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.05% ±0.01%	
		1 kHz < f ≤ 5 kHz	: ±0.4% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.2% ±0.02%	500 Hz < f ≤ 3 kHz	: ±0.1% ±0.01%	
		5 kHz < f ≤ 10 kHz	: ±0.4% ±0.02%	1 kHz < f ≤ 5 kHz	: ±0.4% ±0.02%	3 kHz < f ≤ 5 kHz	: ±0.2% ±0.02%	
		10 kHz < f ≤ 50 kHz	: ±1.0% ±0.02%	5 kHz < f ≤ 10 kHz	: ±0.4% ±0.02%	5 kHz < f ≤ 10 kHz	: ±0.2% ±0.02%	
		50 kHz < f ≤ 100 kHz	: ±1.0% ±0.05%	10 kHz < f ≤ 50 kHz	: ±1.5% ±0.05%	10 kHz < f ≤ 1 MHz	: ±(0.018×f kHz)% ±0.05%	
		100 kHz < f ≤ 300 kHz	: ±2.0% ±0.05%	50 kHz < f ≤ 100 kHz	: ±2.5% ±0.05%		_	
		300 kHz < f ≤ 1 MHz	: ±5.0% ±0.05%	100 kHz < f ≤ 1 MHz	: ±(0.025×f kHz)% ±0.05%		_	
0	perating Temperature	-10°C to 50°C	C (-14°F to 122°F)	-40°C to 85°	C (-40°F to 185°F)	-40°C to 85°C (-40°F to 185°F)		
Μ	aximum rated voltage to earth	CAT	III 1000 V	CAT	III 1000 V	CATIII 1000 V		
D	imensions	139W (5.47") × 120H Cable length [CT6904A: 3 m ((4.72") × 52D (2.05") mm 9.84 ft), CT6904A-1:10 m (32.81 ft)]		(4.41") × 50D (1.97") mm 9.84 ft), CT6875A-1:10 m (32.81 ft)]		I (4.33") × 53D (2.09") mm (9.84 ft), CT6873-01:10 m (32.81 ft)]	
Μ	ass	CT6904A: appr CT6904A-1: appro	ox. 1.05kg (37.0 oz.) ox. 1.35 kg (47.6 oz.) *4	CT6875A: appr CT6875A-1: appr	ox. 0.8 kg (28.2 oz.) ox. 1.1 kg (38.8 oz.) *4	CT6873: app CT6873-01: app	rox. 370 g (13.1 oz.) rrox. 690 g (24.3 o.z) * ⁴	
D	erating properties	1k 550 A 1m temperature	Ancy derating	2k 1k 1k 000 000 000 000 000 000	C (140°F) (continuous)	Free 500 100 100 100 100 100 100 100	finosi)	

Frequency [Hz]

Frequency [Hz]

*3 ±(% of reading + % of range) , range is PW6001

Frequency [Hz]

 *4 The CT6904A-1. CT6875A-1. add ±0.12% of the range for 10 A range or 20 A range; CT6875A/CT6875A-1: Add ±0.15% of the range for 10 A range or 20 A range; CT6873/CT6873-01: Add ±0.15% of the range for 10 A range or 20 A range;
 *4 The CT6904A-1, CT6875A-1, add ±0.05% of the range for 4 A range or 8 A range.
 *4 The CT6904A-1, CT6875A-1, add ±0.05% of the range for 4 A range or 8 A range.
 *4 The CT6904A-1, CT6875A-1, add ±0.05% of the range for 30 kHz < f ≤ 1 MHz.
 For the CT6875A-1, add ±0.005% f kHz/% of the reading for amplitude accuracy and ±0.015 x f kHz/% for phase accuracy for frequencies of 50 kHz < f ≤ 1 MHz. For the CT6873A-1, add $\pm(0.015$ x f kHz)° for phase accuracy for frequencies of 1 kHz < f \leq 1 MHz.

		CT6863-05		CT6872,	CT6872, CT6872-01*6		862-05	
Appearance				NEW Wideband 10 MHz				
R	ated current	200 A	AC/DC	50 /	A AC/DC	50 A	AC/DC	
F	requency band	DC to	500 kHz	DC1	to 10 MHz	DC to	o 1 MHz	
D	iameter of measurable conductors	Мах. ф 24	mm (0.94 in.)	Мах. ф 24	4 mm (0.94 in.)	Мах. ф 24	mm (0.94 in.)	
	PW6001 Combined* ⁵ Current (I) Active power (P)	- PW6001 accuracy + Sensor accuracy		DC 45 Hz ≤ f ≤ 66 Hz DC 45 Hz ≤ f ≤ 66 Hz	: ±0.05% ±0.032% : ±0.05% ±0.027% : ±0.05% ±0.052% : ±0.05% ±0.037%	PW6001 accuracy + Sensor accuracy		
		DC	: ±0.05% ±0.01%	DC	: ±0.03% ±0.002%	DC	: ±0.05% ±0.01%	
		DC < f ≤ 16 Hz	: ±0.10% ±0.02%	DC < f ≤ 16 Hz	: ±0.1% ±0.01%	DC < f ≤ 16 Hz	: ±0.10% ±0.02%	
acy	Sensor only (amplitude)	16 Hz ≤ f < 400 Hz	: ±0.05% ±0.01%	16 Hz < f ≤ 45 Hz	: ±0.05% ±0.01%	16 Hz ≤ f < 400 Hz	: ±0.05% ±0.01%	
ccuracy		400 Hz ≤ f ≤ 1 kHz	: ±0.2% ±0.02%	45 Hz < f ≤ 66 Hz	: ±0.03% ±0.007%	400 Hz ≤ f ≤ 1 kHz	: ±0.2% ±0.02%	
Ac		1 kHz < f ≤ 5 kHz	: ±0.7% ±0.02%	66 Hz < f ≤ 100 Hz	: ±0.04% ±0.01%	1 kHz < f ≤ 5 kHz	: ±0.7% ±0.02%	
	±(% of reading +% of full scale)	5 kHz < f ≤ 10 kHz	: ±1.0% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.06% ±0.01%	5 kHz < f ≤ 10 kHz	: ±1.0% ±0.02%	
	full scale is rated current of sensor	10 kHz < f ≤ 50 kHz	: ±2.0% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.1% ±0.01%	10 kHz < f ≤ 50 kHz	: ±1.0% ±0.02%	
		50 kHz < f ≤ 100 kHz	: ±5.0% ±0.05%	1 kHz < f ≤ 5 kHz	: ±0.15% ±0.02%	50 kHz < f ≤ 100 kHz	: ±2.0% ±0.05%	
		100 kHz < f ≤ 300 kHz	: ±10% ±0.05%	5 kHz < f ≤ 10 kHz	: ±0.15% ±0.02%	100 kHz < f ≤ 300 kHz	: ±5.0% ±0.05%	
		300 kHz < f ≤ 500 kHz	: ±30% ±0.05%	10 kHz < f ≤ 1 MHz	: ±(0.012×f kHz)% ±0.05%		: ±10% ±0.05%	
_	· · ·	0000 - 0500	-	4000 1 0500 (4005		700 kHz < f < 1 MHz	: ±30% ±0.05%	
	perating Temperature		(-22°F to 185°F)	-40°C to 85°C (-40°F to 185°F), 80% RH or less			(-22°F to 185°F)	
N	aximum rated voltage to earth		I 1000 V	-	111 1000 V		II 1000 V	
D	imensions		3.94") × 53D (2.09") mm prox. 3 m (9.84 ft.)		(4.33") × 53D (2.09") mm 9.84 ft), CT6872-01:10 m (32.81 ft)]		3.94") × 53D (2.09") mm pprox. 3 m (9.84 ft.)	
N	ass	Approx. 35	0 g (12.3 oz.)	CT6873: appr CT6873-01: app	ox. 370 g (13.1 oz.) rox. 690 g (24.3 o.z) * ⁶	Approx. 34	10 g (12.0 oz.)	
D	erating properties	Building and a second s	uency derating	CT6873-01: approx. 690 g (24.3 o.z) * ⁶ Frequency denting 100 100 100 100 100 100 100 10		Frequency derating Frequency derating		

*5 ±(% of reading + % of range), range is PW6001 CT6872/CT6872-01: Add ±0.15% of the range for 1 A range or 2 A range. *6 The CT6872-01 has a 10 m cord. For the CT6872-01, add ±(0.015 × f kHz)° for phase accuracy for frequencies of 1 kHz < f ≤ 1 MHz.

Custom cable lengths also available. Please inquire with your Hioki distributor.

Current sensors High accuracy clamp (connect to Probe1 input terminal)

		CT6846A		CT6845A		CT6844A		
Appearance			NEW		NEW		NEW	
Ra	ated current		1000	A AC/DC	500	A AC/DC	500 4	A AC/DC
Fr	equency band	d	DC t	o 100 kHz	DC t	o 200 kHz	DC to	500 kHz
Dia	ameter of meas	urable conductors	Мах. ф 50) mm (1.97 in.)	Мах. ф 5(0 mm (1.97 in.)	Мах. ф 20	mm (0.79 in.)
			DC	: ±0.22% ±0.05%	DC	: ±0.22% ±0.05%	DC	: ±0.22% ±0.05%
	PW6001	Current (I)	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.04%	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.04%	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.04%
	Combined*1	A.I. (D)	DC	: ±0.22% ±0.07%	DC	: ±0.22% ±0.07%	DC	: ±0.22% ±0.07%
		Active power (P)	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.05%	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.05%	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.05%
			DC	: ±0.2% ±0.02%	DC	: ±0.2% ±0.02%	DC	: ±0.2% ±0.02%
Ś			DC < f ≤ 100 Hz	: ±0.2% ±0.01%	DC < f ≤ 100 Hz	: ±0.2% ±0.01%	DC < f ≤ 100 Hz	: ±0.2% ±0.01%
Accuracy			100 Hz < f ≤ 500 Hz	: ±0.5% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.3% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.3% ±0.02%
Acc		(amplitude)	500 Hz < f ≤ 1 kHz	: ±1.0% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.5% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.5% ±0.02%
		g +% of full scale)	1 kHz < f ≤ 5 kHz	: ±2.0% ±0.02%	1 kHz < f ≤ 5 kHz	: ±1.0% ±0.02%	1 kHz < f ≤ 5 kHz	:±1.0%±0.02%
		ed current of sensor	5 kHz < f ≤ 10 kHz	: ±5% ±0.02%	5 kHz < f ≤ 10 kHz	:±1.5% ±0.02%	5 kHz < f ≤ 10 kHz	:±1.5% ±0.02%
			10 kHz < f ≤ 50 kHz	: ±30% ±0.02%	10 kHz < f ≤ 20 kHz	: ±5% ±0.02%	10 kHz < f ≤ 50 kHz	: ±5.0% ±0.02%
				_	20 kHz < f ≤ 50 kHz	:±10% ±0.05%	50 kHz < f ≤ 100 kHz	:±15% ±0.05%
				_	50 kHz < f ≤ 100 kHz	: ±30% ±0.05%	100 kHz < f ≤ 300 kHz	:±30% ±0.05%
O	perating Temp	erature	-40°C to 85°C (-40°F to 185°F)		-40°C to 85°C (-40°F to 185°F)		-40°C to 85°C (-40°F to 185°F)	
M	aximum rated	voltage to earth	CAT	III 1000 V	CATIII 1000 V		CATIII 1000 V	
	mensions		238 (9.37") W × 116 (4.57") H × 35 (1.38") D mm	238 (9.37") W × 116 (4.57") H × 35 (1.38") D mm	153 (6.02") W × 67 (2.	64") H × 25 (0.98") D mm
	mensions		Cable leng	gth: 3 m (9.84 ft)	Cable leng	gth: 3 m (9.84 ft)	Cable leng	th: 3 m (9.84 ft)
M	ass		Approx. 9	990 g (34.9 oz)	Approx. 8	360 g (30.3 oz)	Approx. 4	00 g (14.1 oz)
De	Derating properties		1900 1900 1900 1900 1900 1900 1900 1900			tinuous)	0 0 0 0 0 0 0 0 0 0 0 0 0 0	(2000)

*1 ±(% of reading + % of range), range is PW6001 CT6846A: Add ±1% of the range for the 20 A range, ±0.5% of the range for the 40 A range, and ±0.1% of the range for the 100 A range. CT6845A/CT6844A: Add ±1% of the range for the 10 A range, ±0.5% of the range for the 20 A range, and ±0.1% of the range for the 50 A range.

		CT	6843 A	СТ	6841A
Appearance		NEW		NEW	
Ra	ited current	200 /	A AC/DC	20 A	AC/DC
Fr	equency band	DC to	700 kHz	DC t	o 2 MHz
Di	ameter of measurable conductors	Мах. ф 20	mm (0.79 in.)	Max. ф 20) mm (0.79 in.)
		DC	: ±0.22% ±0.05%	DC	: ±0.22% ±0.08%
	Current (I) PW6001	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.04%	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.04%
	Combined*2	DC	: ±0.22% ±0.07%	DC	: ±0.22% ±0.1%
	Active power (P)	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.05%	45 Hz ≤ f ≤ 66 Hz	: ±0.22% ±0.05%
		DC	: ±0.2% ±0.02%	DC	: ±0.2% ±0.05%
		DC < f ≤ 100 Hz	: ±0.2% ±0.01%	DC < f ≤ 100 Hz	: ±0.2% ±0.01%
ŝ		100 Hz < f ≤ 500 Hz	: ±0.3% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.3% ±0.02%
Accuracy		500 Hz < f ≤ 1 kHz	: ±0.5% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.5% ±0.02%
400	Sensor only (amplitude)	1 kHz < f ≤ 5 kHz	: ±1.0% ±0.02%	1 kHz < f ≤ 5 kHz	: ±1.0% ±0.02%
	±(% of reading +% of full scale)	5 kHz < f ≤ 10 kHz	: ±1.5% ±0.02%	5 kHz < f ≤ 10 kHz	: ±1.5% ±0.02%
	full scale is rated current of sensor	10 kHz < f ≤ 50 kHz	: ±5.0% ±0.02%	10 kHz < f ≤ 50 kHz	: ±2.0% ±0.02%
		50 kHz < f ≤ 100 kHz	:±10% ±0.05%	50 kHz < f ≤ 100 kHz	: ±5.0% ±0.05%
		100 kHz < f ≤ 300 kHz	:±15% ±0.05%	100 kHz < f ≤ 300 kHz	: ±10% ±0.05%
		300 kHz < f ≤ 500 kHz	: ±30% ±0.05%	300 kHz < f ≤ 500 kHz	: ±15% ±0.05%
			-	500 kHz < f < 1 MHz	: ±30% ±0.05%
O	perating Temperature	-40°C to 85°C	C (-40°F to 185°F)	-40°C to 85°C (-40°F to 185°F)	
M	aximum rated voltage to earth	CATI	II 1000 V	CATIII 1000 V	
Dimensions			64") H × 25 (0.98") D mm th: 3 m (9.84 ft)	153 (6.02") W × 67 (2.64") H × 25 (0.98") D mm Cable length: 3 m (9.84 ft)	
Mass		Approx. 3	70 g (13.1 oz)	Approx. 3	50 g (12.3 oz)
Derating properties		Approx. 3/0 g (13.1 02)		1 1	

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*2 ±(% of reading + % of range), range is PW6001 CT6843A: Add ±1% of the range for the 4 A range, ±0.5% of the range for the 8 A range, and ±0.1% of the range for the 20 A range. CT6841A: Add ±2% of the range for the 400 mA range, ±1% of the range for the 800 mA range, and ±0.1% of the range for the 2 A range.

Custom cable lengths also available. Please inquire with your Hioki distributor.

Wide-band probes (connect to Probe2 input terminal)

	3273-50	3274	3275	3276
Appearance	00			00
Rated current	30 A AC/DC	150 A AC/DC	500 A AC/DC	30 A AC/DC
Frequency band	DC to 50 MHz (-3 dB)	DC to 10 MHz (-3 dB)	DC to 2 MHz (-3 dB)	DC to 100 MHz (-3 dB)
Diameter of measurable conductors	Max.φ 5 mm (0.20") (insulated conductors)	Max.φ 20 mm (0.79") (insulated conductors)	Max.φ 20 mm (0.79") (insulated conductors)	Max.φ 5 mm (0.20") (insulated conductors)
Basic accuracy	0 to 30 A rms ±1.0% rdg. ±1 mV 30 A rms to 50 A peak ±2.0% rdg. (At DC and 45 to 66 Hz)	0 to 150 A rms ±1.0% rdg. ±1 mV 150 A rms to 300 A peak ±2.0% rdg. (At DC and 45 to 66 Hz)	0 to 500 A rms ±1.0% rdg. ±5 mV 500 A rms to 700 A peak ±2.0% rdg. (At DC and 45 to 66 Hz)	0 to 30 A rms ±1.0% rdg. ±1 mV 30 A rms to 50 A peak ±2.0% rdg. (At DC and 45 to 66 Hz)
Operating temperature	0°C to 40°C (32°F to 104°F)	0°C to 40°C (32°F to 104°F)	0°C to 40°C (32°F to 104°F)	0°C to 40°C (32°F to 104°F)
Effect of external magnetic fields	20 mA equivalent or lower (400 A/m, 60 Hz and DC)	150 mA equivalent or lower (400 A/m, 60 Hz and DC)	400 mA equivalent or lower (400 A/m, 60 Hz and DC)	400 mA equivalent or lower (400 A/m, 60 Hz and DC)
Dimensions	175W (6.89") × 18H(0.71") × 40D (1.57") mm Cable length: 1.5 m	176W (6.93") × 69H (2.72") × 27D(1.06") mm Cable length: 2 m	176W (6.93") × 69H (2.72") × 27D(1.06") mm Cable length: 2 m	175W (6.89") × 18H(0.71") × 40D (1.57") mm Cable length: 1.5 m
Mass	230 g (8.1 oz)	500 g (17.6 oz)	520 g (18.3 oz)	240 g (8.5 oz)
Derating properties	10 10 10 10 10 10 10 10 10 10	The second secon	(Supplementation of the second	10 10 10 10 10 10 10 10 10 10 10 10 10 1

	CT6700	CT6701		
Appearance	60	60		
Rated current	5 A AC/DC	5 A AC/DC		
Frequency band	DC to 50 MHz (-3 dB)	DC to 120 MHz (-3 dB)		
Diameter of measurable conductors	Max.ø 5 mm (0.20") (insulated conductors)	Max.φ 5 mm (0.20") (insulated conductors)		
Basic accuracy	typical ±1.0% rdg. ±1 mV ±3.0% rdg. ±1 mV (At DC and 45 to 66 Hz)	typical ±1.0% rdg. ±1 mV ±3.0% rdg. ±1 mV (At DC and 45 to 66 Hz)		
Operating temperature	0°C to 40°C (32°F to 104°F)	0°C to 40°C (32°F to 104°F)		
Effects of external magnetic fields	20 mA equivalent or lower (400 A/m, 60 Hz and DC)	5 mA equivalent or lower (400 A/m, 60 Hz and DC)		
Dimensions	155W (6.10") × 18H(0.71") × 26D (1.02") mm Cable length: 1.5 m	155W (6.10") × 18H(0.71") × 26D (1.02") mm Cable length: 1.5 m		
Mass	250 g (8.8 oz)	250 g (8.8 oz)		
Derating properties	Werview in the second lywer in the second lywer is the second lywer in the second lywer is the second lywer in the second lywer is the second lywe	We when the second seco		

Sensor switching method



High accuracy sensor terminal: Slide the cover to the left.

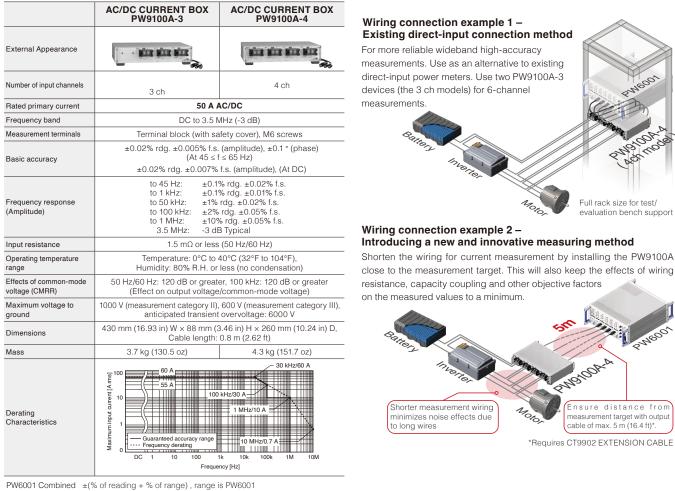
When connecting CT6877A, CT6877A-1, CT6904A, CT6904A-1, CT6904A-2, CT6904-3, CT6876A, CT6876A-1, CT6875A, CT6875A-1, CT6873, CT6873-01, CT6863-05, CT6872, CT6872-01, CT6862-05, CT6841A, CT6843A, CT6844A, CT6845A, CT6846A, PW9100A-3, PW9100A-4



Wideband probe terminal: Slide the cover to the right. When connecting 3273-50, 3274, 3275, 3276, CT6700 or CT6701

High-accuracy sensors: direct connection type (connect to Probe1 input terminal)

The newly developed DCCT method provides world-leading measurement bands and accuracy at a 50 A rating. Delivering a direct-coupled type current testing tool that brings out the PW6001 POWER ANALYZER's maximum potential. (A 5 A-rated version is also available. Contact us for more information.)



	Current (I)	Active power (P)
DC	±0.04% ±0.037%	±0.04% ±0.057%
45 Hz ≤ f ≤ 66 Hz	±0.04% ±0.025%	±0.04% ±0.035%

Add ±0.12% of the range for 1 A range or 2 A range.

Model: POWER ANALYZER PW6001

Model No. (Order Code)	Number of built-in channels	Motor Analysis & D/A Output
PW6001-01	1ch	
PW6001-02	2ch	
PW6001-03	3ch	
PW6001-04	4ch	
PW6001-05	5ch	
PW6001-06	6ch	
PW6001-11	1ch	✓
PW6001-12	2ch	1
PW6001-13	3ch	✓
PW6001-14	4ch	1
PW6001-15	5ch	<i>s</i>
PW6001-16	6ch	1





PW6001-16 (with 6 channels and Motor Analysis & D/A Output

Accessories: Instruction manual × 1, power cord × 1, D-sub 25-pin connector (PW6001-11 to -16 only) × 1

The separately sold voltage cord and current sensor are required for taking measurements.
 Specify the number of built-in channels and whether to include the Motor Analysis & D/A Output upon order for factory installation. Please contact your local Hioki sales subsidiary or branch for changes after shipment.

Model No. (Order Code)	Model	Rated current	Frequency band	Number of channels Cable length
CT6877A	AC/DC CURRENT SENSOR	2000 A rms	DC to 1 MHz	3 m
CT6877A-1	AC/DC CURRENT SENSOR	2000 A rms	DC to 1 MHz	10 m
CT6876A	AC/DC CURRENT SENSOR	1000 A rms	DC to 1.5 MHz	3 m
CT6876A-1	AC/DC CURRENT SENSOR	1000 A rms	DC to 1.2 MHz	10 m
CT6904A-2*	AC/DC CURRENT SENSOR	800 A rms	DC to 4 MHz	3 m
CT6904A-3*	AC/DC CURRENT SENSOR	800 A rms	DC to 2 MHz	10 m
CT6904A	AC/DC CURRENT SENSOR	500 A rms	DC to 4 MHz	3 m
CT6904A-1*	AC/DC CURRENT SENSOR	500 A rms	DC to 2 MHz	10 m
CT6875A	AC/DC CURRENT SENSOR	500 A rms	DC to 2 MHz	3 m
CT6875A-1	AC/DC CURRENT SENSOR	500 A rms	DC to 1.5 MHz	10 m
CT6873	AC/DC CURRENT SENSOR	200 A rms	DC to 10 MHz	3 m
CT6873-01	AC/DC CURRENT SENSOR	200 A rms	DC to 10 MHz	10 m
CT6863-05	AC/DC CURRENT SENSOR	200 A rms	DC to 500 kHz	3 m
CT6872	AC/DC CURRENT SENSOR	50 A rms	DC to 10 MHz	3 m
CT6872-01	AC/DC CURRENT SENSOR	50 A rms	DC to 10 MHz	10 m
CT6862-05	AC/DC CURRENT SENSOR	50 A rms	DC to 1 MHz	3 m
CT6846A	AC/DC CURRENT PROBE	1000 A rms	DC to 100 kHz	3 m
CT6845A	AC/DC CURRENT PROBE	500 A rms	DC to 200 kHz	3 m
CT6844A	AC/DC CURRENT PROBE	500 A rms	DC to 500 kHz	3 m
CT6843A	AAC/DC CURRENT PROBE	200 A rms	DC to 700 kHz	3 m
CT6841A	AC/DC CURRENT PROBE	20 A rms	DC to 2 MHz	3 m
PW9100A-3	AC/DC CURRENT BOX	50 A rms	DC to 3.5 MHz	3 ch
PW9100A-4	AC/DC CURRENT BOX	50 A rms	DC to 3.5 MHz	4 ch

Current measurement options (High accuracy: pass-through, clamp, direct connection type)

* Build-to-order product

Current measurement options (Wide-band probes)

Model No. (Order Code)	Model	Rated current	Frequency band	Sensor cable length
3273-50	CLAMP ON PROBE	30 A rms	DC to 50 MHz	1.5 m
3274	CLAMP ON PROBE	150 A rms	DC to 10 MHz	2 m
3275	CLAMP ON PROBE	500 A rms	DC to 2 MHz	2 m
3276	CLAMP ON PROBE	30 A rms	DC to 100 MHz	1.5 m
CT9700	CURRENT PROBE	5 A rms	DC to 50 MHz	1.5 m
CT9701	CURRENT PROBE	5 A rms	DC to 120 MHz	1.5 m

Voltage Measurement Options



VOLTAGE CORD L9438-50

banana-banana (red, black, 1 each), alligator clip, spiral tube, approx. 3 m (9.84 ft.) length CAT IV 600 V, CAT III 1000 V





VOLTAGE CORD L1000 banana-banana (red, yellow, blue, gray, 1 each, black × 4), alligator clip, approx. 3 m (9.84 ft.) length

CAT IV 600 V, CAT III 1000 V **CONNECTION CORD L9257**

banana-banana (red, black, 1 each), alligator clip, approx. 1.2 m (3.94 ft.) length CAT IV 600 V, CAT III 1000 V

AC/DC HIGH VOLTAGE DIVIDER VT1005 VT1005 divides and outputs voltages of up to 5000 V.

Connection Options



CONNECTION CORD L9217, L9217-01, L9217-02 For motor analysis input and connection to VT1005, BNC-BNC. L9217: 1.6 m (5.25 ft), L9217-01: 3.0 m (9.84 ft), L9217-02: 10 m (32.81 ft)

OPTICAL CONNECTION CABLE L6000 50 µm, 125 µm multi-mode fiber equivalent, 10 m (32.81 ft.) length



CONNECTION CABLE 9444 For external control, 9pin-9pin, straight cable, 1.5 m (4.92 ft.) length



CONVERSION CABLE CT9900 For use with CT6862, CT6863, CT6841, CT6843, CT6844, CT6845, CT6846.



Cable length 1 m; required in order to connect the CT9557's added waveform output terminal to the PW6001.

DISTRIBUTED BY







CONVERSION ADAPTER 9704 For connection to VT1005 BNC-to-banana plug

Supplied with straight to cross conversion

RS-232C CABLE 9637 9pin-9pin cross

Cable length: 1.8 m (5.91 ft)

GP-IB CONNECTOR CABLE 9151-02 2 m (6.56 ft.) length

SENSOR UNIT CT9557 Merges up to four current sensor output waveforms on a single channel, for output to PW6001.

Other _

The following made-to-order items are also available.

Please contact your Hioki distributor or subsidiary for more information. - Carrving case (hard trunk, with casters)

- D/A output cable, D-sub 25-pin-BNC (male), 20 ch conversion, 2.5 m
- (8.20 ft) length - Bluetooth® serial converter adapter cable 1 m (3.28 ft)
- Rackmount fittings (EIA, JIS)
- Optical connection cable, Max. 500 m (1640.55 ft) length
- PW9100 5 A rated version, CT6904 800 A rated version



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Rackmount fittings



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HEADQUARTERS

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regional contact information



D/A output cable

Carrying case



GRABBER CLIP L9243 GRABBER CLIP (red, black, 1 each)

PATCH CORD L1021-01

CAT IV 600 V, CATIII 1000 V

PATCH CORD L1021-02

CAT IV600 V, CATIII 1000 V

For VT1005

clip (red × 1), 0.5 m (1.64 ft.) length

clip (black × 1), 0.5 m (1.64 ft.) length

CAT II 1000 V

Attaches to the tip of the banana plug cable

for branching voltage input, banana branch to banana

for branching voltage input, banana branch to banana

VOLTAGE CORD L1050-01, L1050-03

L1050-01: 1.6 m (5.25 ft), L1050-03: 3.0 m (9.84 ft)

LAN CABLE 9642 connector, Cable length: 5 m (16.41 ft)