

Structure & Flow

Basic Program Structure

```
void setup() {
    // Runs once when sketch starts
}
void loop() {
    // Runs repeatedly
}
```

Control Structures

```
if (x < 5) { ... } else { ... }
while (x < 5) { ... }
for (int i = 0; i < 10; i++) { ... }
break; // Exit a loop immediately
continue; // Go to next iteration
switch (var) {
    case 1:
        ...
        break;
    case 2:
        ...
        break;
    default:
        ...
}
return x; // x must match return type
return; // For void return type
```

Function Definitions

```
<ret. type> <name>(<params>) { ... }
e.g. int double(int x) {return x*2;}
```

Operators

General Operators

=	assignment		
+	add	-	subtract
*	multiply	/	divide
%	modulo		
==	equal to	!=	not equal to
<	less than	>	greater than
<=	less than or equal to		
>=	greater than or equal to		
&&	and		or
!	not		

Compound Operators

++	increment
--	decrement
+=	compound addition
-=	compound subtraction
*=	compound multiplication
/=	compound division
&=	compound bitwise and
=	compound bitwise or

Bitwise Operators

&	bitwise and		bitwise or
^	bitwise xor	~	bitwise not
<<	shift left	>>	shift right

Pointer Access

&	reference: get a pointer
*	dereference: follow a pointer

Variables, Arrays, and Data

Data Types

boolean	true false
char	-128 - 127, 'a'-'\$' etc.
unsigned char	0 - 255
byte	0 - 255
int	-32768 - 32767
unsigned int	0 - 65535
word	0 - 65535
long	-2147483648 - 2147483647
unsigned long	0 - 4294967295
float	-3.4028e+38 - 3.4028e+38
double	currently same as float
void	i.e., no return value

Strings

```
char str1[8] =
{'A','r','d','u','i','n','o','\0'};
// Includes \0 null termination
char str2[8] =
{'A','r','d','u','i','n','o'};
// Compiler adds null termination
char str3[] = "Arduino";
char str4[8] = "Arduino";
```

Numeric Constants

123	decimal
0b01111011	binary
0173	octal - base 8
0x7B	hexadecimal - base 16
123U	force unsigned
123L	force long
123UL	force unsigned long
123.0	force floating point
1.23e6	1.23*10^6 = 1230000

Qualifiers

static	persists between calls
volatile	in RAM (nice for ISR)
const	read-only
PROGMEM	in flash

Arrays

```
int myPins[] = {2, 4, 8, 3, 6};
int myInts[6]; // Array of 6 ints
myInts[0] = 42; // Assigning first
                // index of myInts
myInts[6] = 12; // ERROR! Indexes
                // are 0 though 5
```

Built-in Functions

Pin Input/Output

Digital I/O	- pins 0-13 A0-A5
pinMode(pin,	[INPUT, OUTPUT, INPUT_PULLUP])
int digitalRead(pin)	
digitalWrite(pin, [HIGH, LOW])	

Analog In

int analogRead(pin)	
analogReference([DEFAULT, INTERNAL, EXTERNAL])	

PWM Out

analogWrite(pin, value)	
-------------------------	--

Advanced I/O

tone(pin, freq_Hz)	
tone(pin, freq_Hz, duration_ms)	
noTone(pin)	
shiftOut(dataPin, clockPin, [MSBFIRST, LSBFIRST], value)	
unsigned long pulseIn(pin, [HIGH, LOW])	

Time

unsigned long millis()	// Overflows at 50 days
unsigned long micros()	// Overflows at 70 minutes
delay(msec)	
delayMicroseconds(usec)	

Math

min(x, y)	max(x, y)	abs(x)
sin(rad)	cos(rad)	tan(rad)
sqrt(x)	pow(base, exponent)	
constrain(x, minval, maxval)		
map(val, fromL, fromH, toL, toH)		

Random Numbers

randomSeed(seed)	// long or int
long random(max)	// 0 to max-1
long random(min, max)	

Bits and Bytes

lowByte(x)	highByte(x)
bitRead(x, bitn)	
bitWrite(x, bitn, bit)	
bitSet(x, bitn)	
bitClear(x, bitn)	
bit(bitn)	// bitn: 0=LSB 7=MSB

Type Conversions

char(val)	byte(val)
int(val)	word(val)
long(val)	float(val)

External Interrupts

attachInterrupt(interrupt, func, [LOW, CHANGE, RISING, FALLING])	
detachInterrupt(interrupt)	
interrupts()	
noInterrupts()	

Libraries

Serial - comm. with PC or via RX/TX

```
begin(long speed) // Up to 115200
end()
int available() // #bytes available
int read() // -1 if none available
int peek() // Read w/o removing
flush()
print(data) println(data)
write(byte) write(char * string)
write(byte * data, size)
SerialEvent() // Called if data ready
```

SoftwareSerial.h - comm. on any pin

```
SoftwareSerial(rxPin, txPin)
```

```
begin(long speed) // Up to 115200
```

```
listen() // Only 1 can listen
```

```
isListening() // at a time.
```

```
read, peek, print, println, write
```

```
// Equivalent to Serial library
```

EEPROM.h - access non-volatile memory

```
byte read(addr)
```

```
write(addr, byte)
```

```
EEPROM[index] // Access as array
```

Servo.h - control servo motors

```
attach(pin, [min_uS, max_uS])
```

```
write(angle) // 0 to 180
```

```
writeMicroseconds(uS) // 1000-2000; 1500 is midpoint
```

```
int read() // 0 to 180
```

```
bool attached()
```

```
detach()
```

Wire.h - I²C communication

```
begin() // Join a master
```

```
begin(addr) // Join a slave @ addr
```

```
requestFrom(address, count)
```

```
beginTransmission(addr) // Step 1
```

```
send(byte) // Step 2
```

```
send(char * string)
```

```
send(byte * data, size)
```

```
endTransmission() // Step 3
```

```
int available() // #bytes available
```

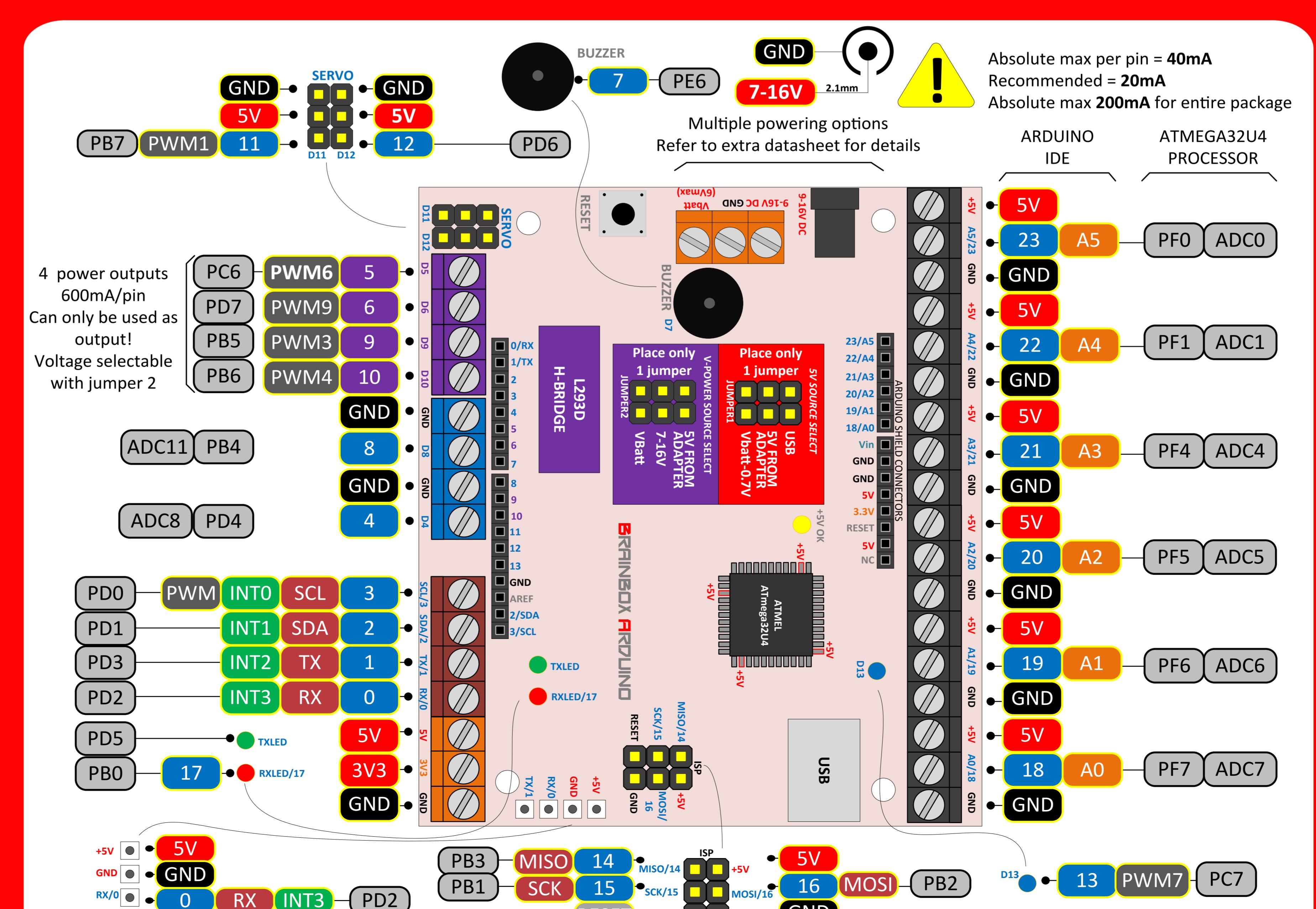
```
byte receive() // Get next byte
```

```
onReceive(handler)
```

```
onRequest(handler)
```

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source: <https://github.com/liffiton/Arduino-Cheat-Sheet/>



- Original: Gavin Smith
- www.e2cre8.be >> Brainbox AVR